Navigability is a robust property

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Workshop on Algorithms and Models for the Webgraph, TU Eindhoven , Netherlands



December 11, 2015

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1 Introduction

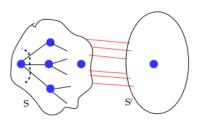
- **2** Geometric Requirements
- **3** Unified Framework
- 4 Robustness





Small World Phenomenon

Small World Phenomenon existence of short paths between any two people using personal acquaintances.



Interpretation: Small Diameter

$$D = O(\log n) w.h.p$$

Reason: Expansion

Branching process - Renormalization

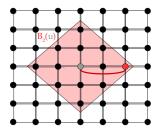
How to find such paths efficiently? \Rightarrow Geometry

Navigability

Millgram's Experiment given occupation and location of a random individual, send a message to the person most likely to know that person.

[Kleinberg'99] Algorithmic interpretation to Milgram's experiment.

Navigability: greedy decentralized search in poly log(n) time.



Rank Based Augmentation (RBA)

$$P(u,v) \propto rac{1}{\mathrm{Vol}(B_u(r))^{lpha}}$$

Uniform over distance scales for $\alpha = 1$ Distance is cut in half every $\log(n)$ steps.

How general is this phenomenon?

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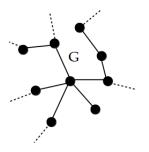
Discussion

Geometric Requirements

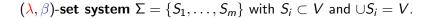
Geometric Requirements

Graph Augmentation

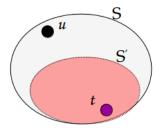
Can any graph be turned into a small world? [Duchon et al. DISC'05]



- [Local Connectivity] - Connected Graph *G* . [Geometry] - Shortest path metric [Augmentation] - RBA using SP-metric.
- Navigable for O(log log n) Doubling Dimension [Slivkins PODC'05]
- Necessary for RBA-type augmentation [Fraigniaud'10]..



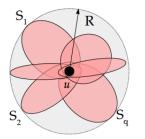
Bounded Growth: $|S_i| \leq R$ and $u \in S_i \Rightarrow |\cup S_i| \leq \beta R$.



Descent Property: $\forall S \in \Sigma \text{ and } \forall u, t \in S \Rightarrow$ $\exists S' \in \Sigma, t \in S', |S'| \ge \lambda |S|.$

Navigability in Set Systems

$$(\lambda, \beta)$$
-set system $\Sigma = \{S_1, \dots, S_m\}$ with $S_i \subset V$ and $\cup S_i = V$.



[Local Connectivity] - Adding $\Omega(\log^2 n)$ links. [Geometry] - $d_{\Sigma}(u, v) := \min_{S \in \Sigma} \{|S| - 1|u, v \in S\}.$ [Augmentation] - RBA with d_{Σ} semi-metric.

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Navigability only for 1-RBA [Kleinberg NIPS'03]

Introduction

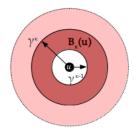
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Unified framework for Navigability

Unified Framework for Navigability

Unified Framework

Geometry (V, D): a set V and a semi-metric $d: V \times V \rightarrow R_+$.



[Local Connectivity]

- substrate E_0 .

[Geometry]

- γ -coherent semi-metric d.

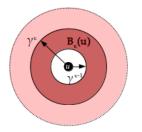
[Augmentation]

- Uniformly Rich product measure.

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Coherent Geometries

Geometry (V, D): a set V and a semi-metric $d: V \times V \rightarrow R_+$.



- [Coarsening] $\gamma > 1$ $d(u, v) \in I_k := [\gamma^{k-1}, \gamma^k)$
- **Bounded Growth** $Vol(B_k(u)) \propto \gamma^k, \forall u \in V$
- [Coherence] $Vol(G(u, v)) \ge \phi \cdot \gamma^k$.

"Bounded" Density Fluctuations for all non-trivial scales.

Example: *n* random points in [0, 1] are $(1 + \frac{c}{n})$ -coherent.

Set Systems are Coherent Geometries

Theorem[Achlioptas, S'15]

For every (λ, β) - set system Σ , there exists $\gamma(\lambda, \beta)$ such that (V, d_{Σ}) is a γ -coherent geometry, where $d_{\Sigma}(u, v) = \min_{S \in \Sigma} \{|S| - 1|u, v \in S\}$

Proof: main quantity to control $Vol(B_k(u))$. $B_{[k]}(u) = \bigcup_{i \leq k} B_i(u)$.

$$\operatorname{Vol}(B_k(u)) = \operatorname{Vol}(B_{[k]}(u)) - \operatorname{Vol}(B_{[k-1]}(u))$$

- Upper bound: easy follows from bounded growth.
- Lower bound: uses the descent property.
 a. ∃S ∈ Σ such that u ∈ Σ and |S| ∈ [γ^{k-1}, γ^k] for each k.
 b. coarsening of geometry.

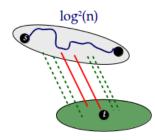
Uniform Richness

A product measure $Q \in [0,1]^{n \times n}$ such that: $(u,v) \stackrel{ind}{\sim} \operatorname{Ber}(Q_{ij})$, is called uniformly rich $d(u,v) \in [\gamma^{k-1},\gamma^k) \Rightarrow Q(u,v) \ge \frac{c}{\log^{\theta} n} \gamma^k$.

Theorem[Achlioptas, S'15]

Coherent geometry (V, d) with substrate E_0 , let $E_Q \sim Ber(\mathbf{Q})$ where Q a uniformly rich product measure, then

 $G(V, E_0 \cup E_Q)$ is navigable.



Proof sketch:

- Substrate $\Rightarrow \exists$ local path $P(s, t) \subset E_0$.
- Coherence \Rightarrow enough good pairs.
- Uniform Richness $\Rightarrow \exists$ good edge w.h.p.

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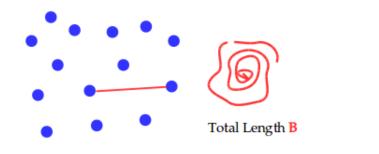
Robustness of Navigability

Robustness of Navigability

Questions about Navigability

- Independence: where does it come from? Is it necessary?
- Evolvability: of RBA or Uniform richness.
- **Robustness:** Kleinberg showed unique exponent for augmentation through RBA.

Graph G uniformly at random such that total length being $\leq B$?



Graphs of Bounded Cost

Agnostic approach: uniformly at random subject to constraints. Cost-geometry $\Gamma = (V, d, c)$, with $c : V \times V \rightarrow R_+$ symmetric.

$$G_{\Gamma}(B) = \left\{ E \subset V imes V \left| \sum_{e \in E} c_e \leq B \right. \right\}$$

• c=1: essentially G(n,m) with m=B edges. • c=0: essentially G(n,1/2) uniform at random. • $c = \begin{cases} 1 & d=1\\ \infty & d>1 \end{cases}$ nearest neighbor percolation

No independence assumption, geometry drives edge formation!

Unified Framework

Discussion

Product measure approximation

Theorem[Achlioptas, S ICALP'15]

For all sufficiently symmetric sets S of graphs, \exists product measures \mathbf{Q}^{\pm} such that if $G \sim U(S), G^{\pm} \sim \text{Ber}(\mathbf{Q}^{\pm})$ then w.h.p.

$$G_{-} \subseteq G \subseteq G_{+}$$

Intuition:

- Uniform measure \Rightarrow counting.
- Symmetry \Rightarrow counting possible.
- **Concentration** around **MaxEnt** solution (product measure).

For Bounded cost graphs the product measure has an explicit form!

$$Q_{ij} = rac{1}{1 + \exp(\lambda(B)c_{ij})}$$

Inevitabilty

A cost function c is γ -consistent if it is constant in $[\gamma^{k-1}, \gamma^k)$.

Theorem[Achlioptas, S'15]

- A $\Gamma = (V, d, c)$ coherent cost geometry:
 - Navigability: for every B ≥ B₊(Γ) almost all elements of G_Γ(B) are navigable.
 - Sparsity: for every $B_0 \le B \le B^-$ almost all elements of $G_{\Gamma}(B)$ have at most poly-log density.

Proof:

- Coupling with product measure.
- Proof for product measure.
- Use monotonicity and coupling to translate back to uniform measure.

RBA through Indexing

Corollary [Achlioptas, S '15]

Let $\overline{B}_k = \frac{|\bigcup_{u \in V} B_k(u)|}{n}$, and $c = \frac{1}{\beta} \log \overline{B}_k$, for $B_-(\Gamma) \le B \le B_+(\Gamma)$: **1** Navigability with poly-log density.

2 Robustness:
$$B_+/B^- = \Omega(\log^{\theta} n)$$
.

3 RBA for
$$B^*$$
, $P(u,v) \propto rac{1}{\operatorname{Vol}(B_k(u))}$.

Kleinberg's Phase transition \Rightarrow artifact of λ parametrization.

Rank Based Augmentation \Rightarrow cost of indexing.

Optimal adaptation of technology (cost) to geometry!

Historical Emergence of Navigability

Technology: cost function c (cost communicating at distance d). Economic activity: total budget BConsider the cost function (King-Plosser-Rebelo preferences):

$$c_k(eta) := egin{cases} rac{ar{B}_k^eta - 1}{eta}, & eta > 0 \ \log ar{B}_k, & eta = 0 \end{cases}$$

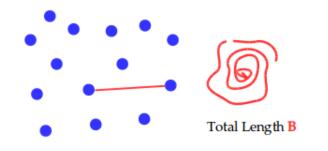
Navigability and Sparsity for $\beta = 0 \Rightarrow$ **Technological** breakthrough!



Introduction	Geometric Requirements	Unified Framework	Robustness	Discussion
Summary				

- Why? \Rightarrow Coherent Geometry
- How? ⇒ Uniform richness
- When?⇒ Technology becomes as good as Indexing!

Robustness: almost all feasible graphs are Navigable!



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Open questions

Inhomogeneous random graph: generate a sample in time proportional to the density?



Thank You!

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"How can i link, with three, four, or at most five links of the chain, trivial, everyday things of life. How can I link one phenomenon to another? How can i join the relative and the ephimeral with steady, permanent things - how can I tie up the part with the whole"

Frigyes Karinthy 1929, Chains.