

Statistical mechanics, graph estimation and semidefinite programming

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Stanford University

September 29, 2015

Plan

Planning for a tutorial

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What the organizers ask you to cover

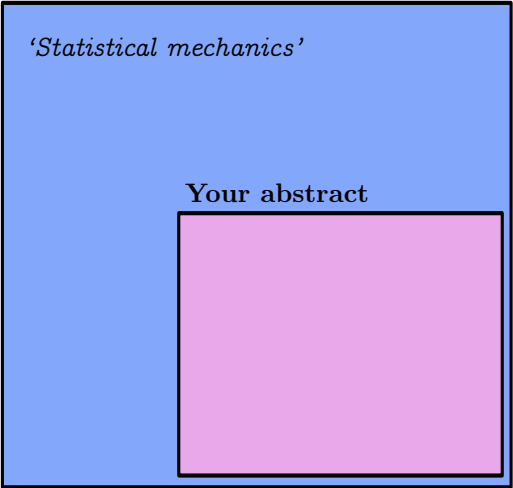
'Statistical mechanics'

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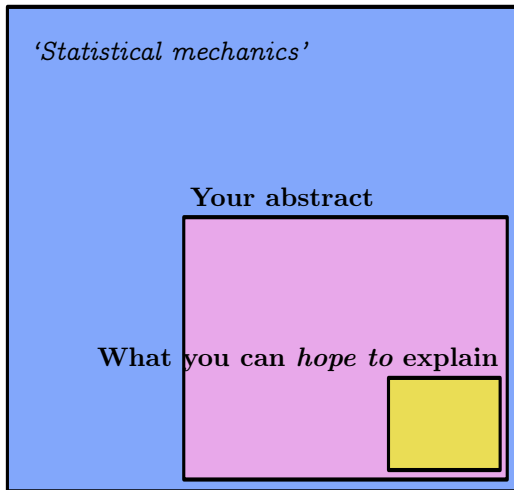
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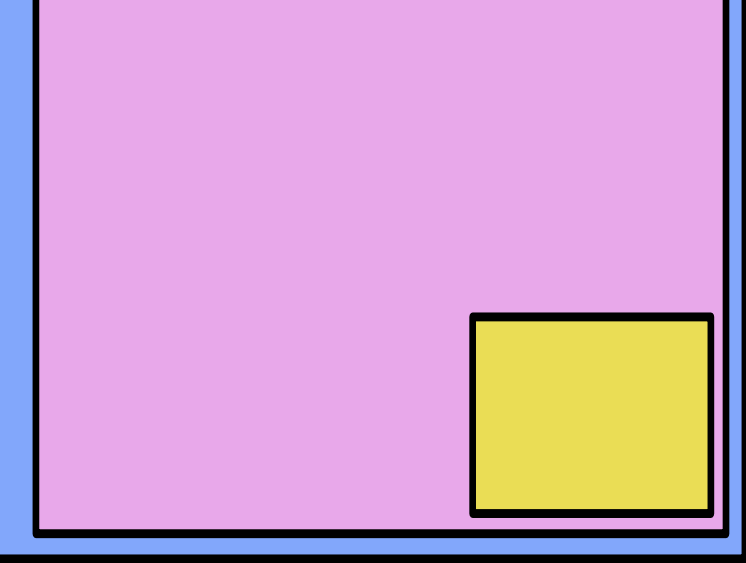
Your abstract



Planning for a tutorial

What the organizers ask you to cover





Universality and the Lindeberg method

What is this tutorial about

Universality:

- ▶ The macroscopic properties of a statistical physics system are insensitive to the microscopic details of the model.

Lindeberg method:

- ▶ A technique to prove some universality properties.

Outline

- 1 Warm up: CLT via Lindeberg method
- 2 Extremal cuts of random graphs
- 3 Semidefinite programs on random graphs
- 4 Compressed sensing
- 5 Conclusion

References

Applications to Computer Science/Information Theory:

- ▶ A. Dembo, A. Montanari, S. Sen (2015), *Extremal cuts of sparse random graphs*, arXiv:1503.03923
- ▶ A. Montanari, S. Sen (2015), *Semidefinite Programs on Sparse Random Graphs*, arXiv:1504.05910
- ▶ Y. Deshpande, E. Abbe, A. Montanari (2015), *Asymptotic mutual information for the two-groups stochastic block model*, arXiv:1507.08685
- ▶ S.B. Korada, A. Montanari (2011), *Applications of the Lindeberg principle in communications and statistical learning*, IEEE Transactions on Information Theory, 57 (4), 2440-2450

References

A nice application to physics:

- ▶ P. Carmona, Y. Hu (2006), *Universality in Sherrington-Kirkpatrick's spin glass model*,
Annales de l'IHP Probabilités et statistiques, 42, 2006

A nice 'pre-packaged' tool:

- ▶ S. Chatterjee (2005), *A simple invariance theorem*, arXiv:0508213

[Many other applications!!]

Caveat: This is going to be technical!

Warm up: CLT via Lindeberg method

CLT

- ▶ X_1, X_2, \dots, X_N independent, $\mathbb{E}[X_i] = 0$, $\mathbb{E}[X_i^2] = 1$.

We want to prove

$$\frac{1}{\sqrt{N}} \sum_{i=1}^N X_i \xrightarrow{d} N(0, 1).$$

Idea:

- ▶ Easy for $Z_1, Z_2, \dots, Z_N \sim_{i.i.d.} N(0, 1)$.
- ▶ Prove, for h smooth

$$\left| \mathbb{E}h\left(\frac{1}{\sqrt{n}} \sum_{i=1}^N X_i\right) - \mathbb{E}h\left(\frac{1}{\sqrt{N}} \sum_{i=1}^N Z_i\right) \right| \leq o_n(1)$$

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Side note

- ▶ Classically, a whole class of test functions h .
- ▶ Here: Work with a specific h .

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Notation

$$\mathbf{x} = (x_1, x_2, \dots, x_N) \in \mathbb{R}^N$$

$$f(\mathbf{x}) \equiv h\left(\frac{1}{\sqrt{N}} \sum_{i=1}^N x_i\right)$$

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Key idea ('smart path')

$$\mathbf{X}^{(i)} = (X_1, X_2, \dots, X_{i-1}, X_i, Z_{i+1}, \dots, Z_n)$$

$$|\mathbb{E}f(\mathbf{X}) - \mathbb{E}f(\mathbf{Z})| \leq \sum_{i=1}^N |\mathbb{E}f(\mathbf{X}^{(i)}) - \mathbb{E}f(\mathbf{X}^{(i-1)})|$$

This is brilliant:

- ▶ \mathbf{X} and \mathbf{Z} are difficult to relate to each other.
- ▶ $\mathbf{X}^{(i)}$ and $\mathbf{X}^{(i-1)}$ are easy to connect!

(Taylor expansion!)

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(Taylor expansion!)

Taylor expansion ($x \geq 0$)

$$g(x) = g(0) + xg'(0) + \int_0^x (x-t)g''(t) dt$$

$$\begin{aligned} \left| g(x) - \left\{ g(0) + g'(0)x + \frac{1}{2}g''(0)x^2 \right\} \right| &\leq \int_0^x (x-t)|g''(t) - g''(0)| dt \\ &\leq (\|g''\|_\infty x^2) \vee \left(\frac{1}{6}\|g'''\|_\infty x^3 \right) \end{aligned}$$

$$\begin{aligned} \left| g(x) - \left\{ g(0) + g'(0)x + \frac{1}{2}g''(0)x^2 \right\} \right| &\leq \mathcal{R} \\ \mathcal{R} &\equiv \|g''\|_\infty x^2 \mathbf{1}_{\{|x|>K\}} + \frac{1}{6}\|g'''\|_\infty x^3 \mathbf{1}_{\{|x|\leq K\}} \end{aligned}$$

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Consider now a single step

$$\begin{aligned}\mathbf{X}^{(i)} &= (X_1, X_2, \dots, X_{i-1}, \mathbf{X}_i, Z_{i+1}, \dots, Z_n) \\ \mathbf{X}^{(i-1)} &= (X_1, X_2, \dots, X_{i-1}, \mathbf{Z}_i, Z_{i+1}, \dots, Z_n) \\ \mathbf{X}_0^{(i)} &= (X_1, X_2, \dots, X_{i-1}, \mathbf{0}, Z_{i+1}, \dots, Z_n)\end{aligned}$$

Taylor expansion around $\mathbf{X}_0^{(i)}$

$$\begin{aligned}f(\mathbf{X}^{(i)}) &= f(\mathbf{X}_0^{(i)}) + X_i \partial_i f(\mathbf{X}_0^{(i)}) + \frac{1}{2} X_i^2 \partial_i^2 f(\mathbf{X}_0^{(i)}) \pm \mathcal{R}_i \\ f(\mathbf{X}^{(i-1)}) &= f(\mathbf{X}_0^{(i)}) + Z_i \partial_i f(\mathbf{X}_0^{(i)}) + \frac{1}{2} Z_i^2 \partial_i^2 f(\mathbf{X}_0^{(i)}) \pm \tilde{\mathcal{R}}_i\end{aligned}$$

$$\mathcal{R}_i \equiv \|\partial_i^2 f\|_\infty X_i^2 \mathbf{1}_{\{|X_i| > K\}} + \frac{1}{6} \|\partial_i^3 f\|_\infty X_i^3 \mathbf{1}_{\{|X_i| \leq K\}},$$

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Consider now a single step

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Take expectation with respect to X_i, Z_i

$$\begin{aligned}\mathbb{E}_i\{f(\mathbf{X}^{(i)}) - f(\mathbf{X}^{(i-1)})\} &\leq \\&\leq \partial_i f(\mathbf{X}_0^{(i)}) \mathbb{E}_i(X_i - Z_i) + \frac{1}{2} \partial_i^2 f(\mathbf{X}_0^{(i)}) \mathbb{E}_i(X_i^2 - Z_i^2) + \mathbb{E}_i(\mathcal{R}_i + \tilde{\mathcal{R}}_i) \\&= \mathbb{E}_i(\mathcal{R}_i + \tilde{\mathcal{R}}_i)\end{aligned}$$

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Summing the terms back together

Lemma

$$\mathbb{E}\{f(\mathbf{X}) - f(\mathbf{Z})\} \leq T_2(K) \max_{i \in n} \|\partial_i^2 f\|_\infty + T_3(K) \max_{i \in n} \|\partial_i^3 f\|_\infty,$$

$$T_2(K) \equiv \sum_{i=1}^N \left\{ \mathbb{E}[X_i^2 \mathbf{1}_{\{|X_i| > K\}}] + \mathbb{E}[Z_i^2 \mathbf{1}_{\{|Z_i| > K\}}] \right\}$$

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Morally: I can replace the X_i 's by Gaussians if

- ▶ $f(\cdot)$ does not depend too strongly on any of the coordinates.
- ▶ X_i 's have light tails

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Getting the CLT $|h''(x)|, |h'''(x)| \leq 1, K = \varepsilon\sqrt{N}$

$$f(\mathbf{x}) = h\left(\frac{1}{\sqrt{N}} \sum_{i=1}^N x_i\right),$$

$$\|\partial_i^2 f\|_\infty = \frac{1}{N} \|h''\|_\infty,$$

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$$\begin{aligned} \text{Bound} &= \frac{1}{N} \sum_{i=1}^N \mathbb{E}[X_i^2 \mathbf{1}_{\{|X_i| > \varepsilon\sqrt{n}\}}] + \frac{1}{N^{3/2}} \sum_{i=1}^N \mathbb{E}[|X_i|^3 \mathbf{1}_{\{|X_i| \leq \varepsilon\sqrt{N}\}}] + Z\text{'s} \\ &\leq \frac{1}{N} \sum_{i=1}^N \mathbb{E}[X_i^2 \mathbf{1}_{\{|X_i| > \varepsilon\sqrt{N}\}}] + \frac{\varepsilon}{N} \sum_{i=1}^N \mathbb{E}[|X_i|^2] + \dots \\ &\leq \frac{1}{N} \sum_{i=1}^N \mathbb{E}[X_i^2 \mathbf{1}_{\{|X_i| > \varepsilon\sqrt{N}\}}] + \varepsilon + \dots \end{aligned}$$

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Getting the CLT

Theorem (Lindeberg, 1922)

Assume that $N^{-1} \sum_{i=1}^n \mathbb{E}[X_i^2 \mathbf{1}_{\{|X_i| > \varepsilon \sqrt{N}\}}] \rightarrow 0$ for any $\varepsilon > 0$. Then

$$\frac{1}{\sqrt{N}} \sum_{i=1}^N X_i \xrightarrow{d} N(0, 1).$$

[To conclude...]

Remarks

- ▶ Introduced by Lindeberg (1922)
- ▶ Used for non-sum functions in mathematical physics, e.g. Guerra-Toninelli (2004)
- ▶ Chatterjee (2005) points out that Lemma holds for any $f : \mathbb{R}^N \rightarrow \mathbb{R}$
- ▶ Several variants. Example, $\theta \in [0, \pi/2]$

$$\mathbf{X}(\theta) \equiv \mathbf{Z} \cos \theta + \mathbf{X} \sin \theta$$

(‘smart path method’, ‘interpolation’, ...)

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Extremal cuts of random graphs

Background: Random graph models

Erdős-Renyi Random graph $G = (V, E) \sim \mathcal{G}(n, \gamma/n)$

- ▶ $|V| = n$ vertices
- ▶ Each edge present with probability γ/n

Random regular graph $G = (V, E) \sim \mathcal{G}^{\text{reg}}(n, \gamma)$

- ▶ $|V| = n$ vertices
- ▶ Uniformly random among all graphs with $\deg(i) = \gamma$ for all $i \in V$.

Average degree $\gamma = O(1)$

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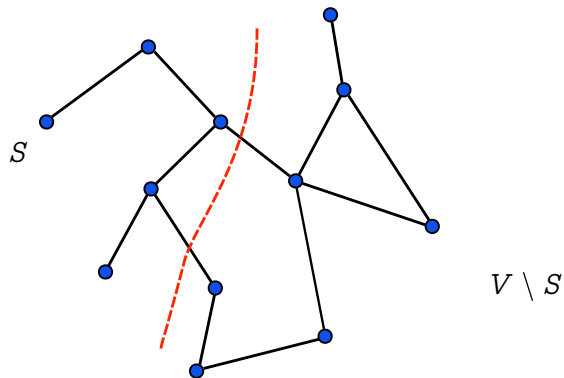
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Cuts



$$\text{cut}_G(S) \equiv \left| \{(i, j) \in E : i \in S, j \in V \setminus S\} \right|$$

Interesting for many reasons

- ▶ Clustering similarity matrices
- ▶ Graph layout
- ▶ Community structure in social networks
- ▶ ...

Extremal cuts

Minimum bisection

$$\text{mcut}(G) = \min \left\{ \text{cut}_G(S) : S \subseteq V, |S| = n/2 \right\}$$

Maximum bisection

$$\text{MCUT}(G) = \max \left\{ \text{cut}_G(S) : S \subseteq V, |S| = n/2 \right\}$$

Maximum Cut

$$\text{MaxCut}(G) = \max \left\{ \text{cut}_G(S) : S \subseteq V \right\}$$

Extremal cuts

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Maximum Cut

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A long history

- ▶ Bollobas, 1984
- ▶ Alon, 1997
- ▶ Coppersmith, Gamarnik, Hajiaghayi, Sorkin, 2004
- ▶ Díaz, Serna, and Wormald, 2007
- ▶ Daudé, Martínez, Rasendrasahina, Ravelomanana, 2012
- ▶ Gamarnik, Li, 2014
- ▶ ...

Typical result:

If $G \sim \mathcal{G}(n, \gamma/n)$ then, with high probability

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Insights from statistical physics

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The following limit exists, for $G_n \sim \mathcal{G}(n, \gamma/n)$, $\mathcal{G}^{\text{reg}}(n, \gamma)$

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A classical argument

(Bollobas 1984)

Fix $S \subseteq V$, $|S| = n/2$

- ▶ Each edge is cut with probability $1/2$

$$\mathbb{E} \text{cut}(S) = \frac{n\gamma}{4}.$$

- ▶ Azuma-Hoeffding argument

$$\mathbb{P}\left\{ \text{cut}(S) \geq \mathbb{E} \text{cut}(S) + \Delta \right\} \leq \exp\left(-\frac{\Delta^2}{4n\gamma}\right)$$

- ▶ Union bound

$$\mathbb{P}\left\{ \max_{S, |S|=n/2} \text{cut}(S) \geq \frac{n\gamma}{4} + \delta n\sqrt{\gamma} \right\} \leq 2^n e^{-n\delta^2/4}.$$

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Hence, with high probability

$$\text{MCUT}(G) \leq \frac{n\gamma}{4} + C_2 n \sqrt{\gamma}$$

In other words

The $n\gamma/4$ term is 'trivial'...

A new result

A new result

Theorem (Dembo, Montanari, Sen, 2015)

Assume $G \sim \mathcal{G}(n, \gamma/n)$ or $G \sim \mathcal{G}^{\text{reg}}(n, \gamma)$. Then, with high probability,

$$\frac{1}{n} \text{mcut}(G) = \frac{\gamma}{4} - P_* \sqrt{\frac{\gamma}{4}} + o_\gamma(\sqrt{\gamma}),$$

$$\frac{1}{n} \text{MCUT}(G) = \frac{\gamma}{4} + P_* \sqrt{\frac{\gamma}{4}} + o_\gamma(\sqrt{\gamma}),$$

$$\frac{1}{n} \text{MaxCut}(G) = \frac{\gamma}{4} + P_* \sqrt{\frac{\gamma}{4}} + o_\gamma(\sqrt{\gamma}).$$

where $P_* = \dots$ (wait a minute).

Remarks

- ▶ The $\sqrt{\gamma}$ term has a well defined coefficient.
- ▶ The coefficient has a formula.
- ▶ It is the same for 3 problems, 2 graph models.
- ▶ $P_* \approx 0.7632$

What is P_* ?

GOE random matrix:

$$J \in \mathbb{R}^{n \times n}, \quad J = J^T, \quad (J_{ij})_{i < j} \sim N(0, 1), \quad J_{ii} = 0.$$

Sherrington-Kirkpatrick spin-glass model

$$\mathcal{H}_J(\sigma) \equiv \frac{1}{2\sqrt{n}} \langle \sigma, J\sigma \rangle.$$

Finally

$$P_* \equiv \lim_{n \rightarrow \infty} \frac{1}{n} \mathbb{E} \max_{\sigma \in \{+1, -1\}^n} \mathcal{H}_J(\sigma).$$

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- ▶ Given by '*Parisi's formula*' (Talagrand, 2006)
- ▶ Clarifies why 'standard' combinatorial methods were unsuccessful

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(Informal) Implication

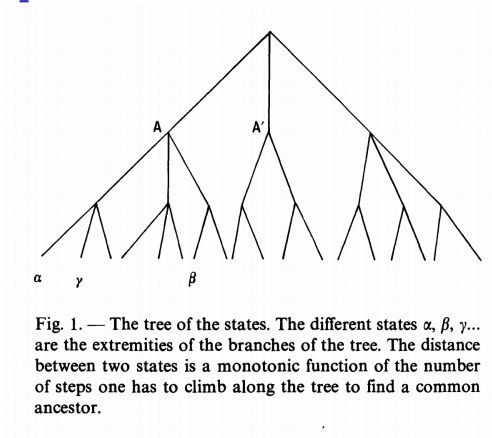


Fig. 1. — The tree of the states. The different states $\alpha, \beta, \gamma, \dots$ are the extremities of the branches of the tree. The distance between two states is a monotonic function of the number of steps one has to climb along the tree to find a common ancestor.

MaxCut, max-bisection, min-bisection have ∞ -RSB structure

Proof strategy: mcut

Two graph models

$$\text{SK model} \underset{\text{Lindeberg}}{\longleftrightarrow} \mathcal{G}(n, \gamma/n) \underset{\text{coupling}}{\leftrightarrow} \mathcal{G}^{\text{reg}}(n, \gamma)$$

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min-bisection

Hamiltonian $\mathcal{H}_{\text{mcut}} : \Omega_n \rightarrow \mathbb{R}$

$$\mathcal{H}_{\text{mcut}}(\boldsymbol{\sigma}) = \frac{1}{\sqrt{\gamma}} \sum_{(i,j) \in E} \sigma_i \sigma_j,$$

$$\Omega_n = \left\{ \boldsymbol{\sigma} \in \{+1, -1\}^n : \sum_{i=1}^n \sigma_i = 0 \right\}.$$

$$\begin{aligned} \text{mcut}(G) &= \min_{\boldsymbol{\sigma} \in \Omega_n} \sum_{(i,j) \in E} \left(\frac{1 - \sigma_i \sigma_j}{2} \right) \\ &= \frac{1}{2} |E| - \frac{1}{2} \max_{\boldsymbol{\sigma} \in \Omega_n} \sum_{(i,j) \in E} \sigma_i \sigma_j \\ &= \frac{n\gamma}{4} - \sqrt{\frac{\gamma}{4}} \max_{\boldsymbol{\sigma} \in \Omega_n} \mathcal{H}_{\text{mcut}}(\boldsymbol{\sigma}). \end{aligned}$$

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We want to show

$$\left| \frac{1}{n} \mathbb{E} \max_{\sigma \in \Omega_n} \mathcal{H}_{\text{mcut}}(\sigma) - \frac{1}{n} \mathbb{E} \max_{\sigma \in \{+1, -1\}^n} \mathcal{H}_J(\sigma) \right| \leq o_\gamma(1) + o_n(1).$$

\Rightarrow Universality result

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\Rightarrow Universality result

Construct $\mathcal{H}_{\text{mcut}}(\boldsymbol{\sigma})$ using iid random variables

For $\boldsymbol{\sigma} \in \Omega_n$

$$\begin{aligned}\mathcal{H}_{\text{mcut}}(\boldsymbol{\sigma}) &= \frac{1}{\sqrt{\gamma}} \sum_{i < j} \left(\mathbf{1}_{(i,j) \in E} - \frac{\gamma}{n} \right) \sigma_i \sigma_j \\ &= \frac{1}{2\sqrt{n}} \langle \boldsymbol{\sigma}, A\boldsymbol{\sigma} \rangle = \mathcal{H}_A(\boldsymbol{\sigma})\end{aligned}$$

where

$$A_{ij} = \begin{cases} \sqrt{\frac{n}{\gamma}} \left(1 - \frac{\gamma}{n} \right) & \text{with probability } \gamma/n, \\ -\sqrt{\frac{\gamma}{n}} & \text{with probability } 1 - \gamma/n. \end{cases}$$

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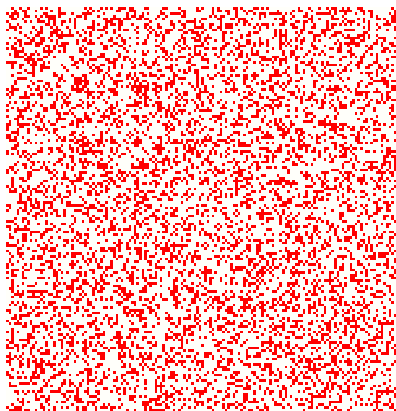
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Centered, normalized adjacency matrix



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Universality

We want to show

$$\left| \frac{1}{n} \mathbb{E} \max_{\sigma \in \Omega_n} \mathcal{H}_A(\sigma) - \frac{1}{n} \mathbb{E} \max_{\sigma \in \{+1, -1\}^n} \mathcal{H}_J(\sigma) \right| \leq o_\gamma(1) + o_n(1).$$

Challenges:

- ▶ $\Omega_n \neq \{+1, -1\}^n$
- ▶ Define

$$\phi(A) \equiv \frac{1}{n} \max_{\sigma \in \Omega_n} \mathcal{H}_A(\sigma)$$

Then $A \mapsto \phi(A)$ is not differentiable.

Fixing problem #1

$$\begin{aligned} & \left| \mathbb{E} \max_{\sigma \in \Omega_n} \mathcal{H}_A(\sigma) - \mathbb{E} \max_{\sigma \in \{\pm 1\}^n} \mathcal{H}_J(\sigma) \right| \leq \\ & \leq \left| \mathbb{E} \max_{\sigma \in \Omega_n} \mathcal{H}_A(\sigma) - \mathbb{E} \max_{\sigma \in \Omega_n} \mathcal{H}_J(\sigma) \right| + \left| \mathbb{E} \max_{\sigma \in \Omega_n} \mathcal{H}_J(\sigma) - \mathbb{E} \max_{\sigma \in \{\pm 1\}^n} \mathcal{H}_J(\sigma) \right| \end{aligned}$$

- ▶ $\sigma^* = \arg \max_{\sigma \in \{+1, -1\}^n} \mathcal{H}_J(\sigma)$ is uniformly random:

$$\langle \sigma^*, \mathbf{1} \rangle = \Theta(\sqrt{n})$$

- ▶ Prove that $\max_{\sigma \in \{+1, -1\}^n} \mathcal{H}_J(\sigma)$ is ‘almost’ achieved on $\Omega_n = \{\sigma : \langle \sigma, \mathbf{1} \rangle = 0\}$.

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Fixing problem #2

$$\phi(A) \equiv \frac{1}{n} \max_{\sigma \in \Omega_n} \mathcal{H}_A(\sigma)$$

Idea: Smooth max

$$\phi(\beta; A) \equiv \frac{1}{n\beta} \log \left\{ \sum_{\sigma \in \Omega_n} e^{\beta \mathcal{H}_A(\sigma)} \right\},$$
$$\phi(A) = \lim_{\beta \rightarrow \infty} \phi(\beta; A).$$

Need to:

- ▶ Bound $\partial_{A_{ij}}^r \phi(A; \beta)$
- ▶ Bound $|\phi(\beta; A) - \phi(\infty; A)|$

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It is a free energy!

$$\phi(\beta; A) \equiv \frac{1}{n\beta} \log \left\{ \sum_{\sigma \in \Omega_n} e^{\beta \mathcal{H}_A(\sigma)} \right\}$$

Associated Boltzmann measure on Ω_n

$$\mu_{\beta, A}(\sigma) \equiv \frac{1}{Z(\beta; A)} e^{\beta \mathcal{H}_A(\sigma)}$$

$E_\mu \equiv$ expectation wrt μ

Bounding $\partial_{A_{ij}}^r \phi(A; \beta)$

$$\phi(\beta; A) \equiv \frac{1}{n\beta} \log \left\{ \sum_{\sigma \in \Omega_n} \exp \left(\frac{\beta}{\sqrt{n}} \sum_{i < j} A_{ij} \sigma_i \sigma_j \right) \right\}$$

$$\partial_{A_{ij}} \phi(\beta; A) = \frac{1}{n^{3/2}} \mathbb{E}_\mu(\sigma_i \sigma_j) = O(n^{-3/2}),$$

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Bound $|\phi(\beta; A) - \phi(\infty; A)|$

$$\phi(\beta; A) \equiv \frac{1}{n\beta} \log \left\{ \sum_{\sigma \in \Omega_n} e^{\beta \mathcal{H}_A(\sigma)} \right\} = \frac{1}{n\beta} \log Z(\beta; A)$$

$$\begin{aligned} \frac{\partial \phi}{\partial \beta}(\beta; A) &\equiv -\frac{1}{n\beta^2} \log Z(\beta; A) + \frac{1}{n\beta} \mathbb{E}_\mu \mathcal{H}_A(\sigma) \\ &= \frac{1}{n\beta^2} \mathbb{E}_\mu \{ \beta \mathcal{H}_A(\sigma) - \log Z(\beta; A) \} \\ &= \frac{1}{n\beta^2} \mathbb{E}_\mu \log \mu_{\beta, A}(\sigma) \end{aligned}$$

$$\frac{\partial \phi}{\partial (\beta^{-1})}(\beta; A) = \frac{1}{n} H(\mu_{\beta, A}) \in [0, \log 2]$$

... put together the pieces

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... put together the pieces

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... put together the pieces

Semidefinite programs on random graphs

Basic remark

mcut }
MCUT } are NP-hard
MaxCut }

(and hard to approximate)
(... very rich theory)

Example: min bisection

Theorem (Khot 2004)

Assume SAT cannot be solved in (randomized) time below 2^{n^ϵ} . Then min-bisection cannot be approximated in polynomial time within a factor $1 + \delta(\epsilon)$.

Theorem (Räcke 2008)

There exists a polynomial-time algorithm that approximates the min-bisection within a factor $O(\log n)$.

Stronger assumption

Theorem (Khot, Kindler, Mossel, O'Donnell 2005)

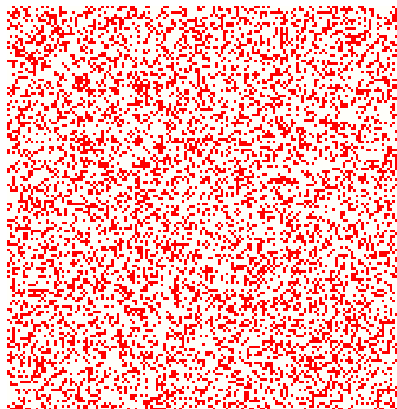
Under the Unique Games Conjecture, there is no polynomial-time algorithm that approximates MaxCut better than within a factor 0.878568.

What about random instances?

(relevant for machine learning, statistics, signal processing,...)

$$G \sim \mathcal{G}(n, \gamma/n)$$

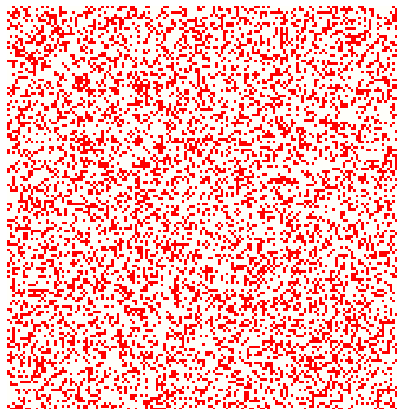
Centered adjacency matrix



$$(A_G)_{ij} = \begin{cases} 1 - \frac{\gamma}{n} & \text{if } (i, j) \in E, \\ -\frac{\gamma}{n} & \text{otherwise.} \end{cases}$$

Not normalized $\mathbb{E}\{(A_G)_{ij}^2\} = (\gamma/n)(1 + O(n^{-1}))$

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min bisection

$$\begin{aligned} & \text{maximize} && \langle \boldsymbol{\sigma}, A_G \boldsymbol{\sigma} \rangle, \\ & \text{subject to} && \langle \mathbf{1}, \boldsymbol{\sigma} \rangle = 0, \\ & && \sigma_i \in \{+1, -1\}. \end{aligned}$$

Note: $\langle \mathbf{1}, A_G \mathbf{1} \rangle = O(\sqrt{n}) \ll \max_{\boldsymbol{\sigma}} \langle \boldsymbol{\sigma}, A_G \boldsymbol{\sigma} \rangle$
 \Rightarrow can drop constraint $\langle \mathbf{1}, \boldsymbol{\sigma} \rangle = 0$

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Another way to look at it: Lagrangian

$$\begin{aligned} \text{maximize} \quad & 2 \sum_{(i,j) \in E} \sigma_i \sigma_j - \lambda \left(\sum_{i=1}^n \sigma_i \right)^2, \\ \text{subject to} \quad & \sigma_i \in \{+1, -1\}. \end{aligned}$$

λ = regularization parameter

As $\lambda \rightarrow \infty$, forces $\sum_{i=1}^n \sigma_i = 0$

Lagrangian

$$\begin{aligned} & \text{maximize} && \langle \boldsymbol{\sigma}, (A_G - (\lambda - (\gamma/n)) \mathbf{1} \mathbf{1}^T) \boldsymbol{\sigma} \rangle, \\ & \text{subject to} && \sigma_i \in \{+1, -1\}. \end{aligned}$$

λ = regularization parameter

Setting $\lambda = \gamma/n$ is sufficient

Typical value

$$\begin{aligned} & \text{maximize} && \langle \boldsymbol{\sigma}, A_G \boldsymbol{\sigma} \rangle, \\ & \text{subject to} && \sigma_i \in \{+1, -1\}. \end{aligned}$$

Value (last part of the talk)

$$\begin{aligned} \text{OPT}(G) &= 2nP_*\sqrt{\gamma} + n o_\gamma(\sqrt{\gamma}) \\ &\approx 1.5264 n\sqrt{\gamma} \end{aligned}$$

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Idea: Convex relaxations

Spectral relaxation

$$\begin{aligned} & \text{maximize} && \langle \sigma, A_G \sigma \rangle, \\ & \text{subject to} && \sigma_i \in \{+1, -1\} \quad . \end{aligned}$$

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Value

$$\lambda_{\max}(A_G) n$$

Spectral relaxation very bad in the sparse regime!

Theorem (Krivelevich, Sudakov 2003+Vu 2005)

If $G \sim \mathcal{G}(n, \gamma/n)$, then, with high probability,

$$\lambda_{\max}(A_G) = \begin{cases} 2\sqrt{\gamma}(1 + o(1)) & \text{if } \gamma \gg (\log n)^4, \\ \sqrt{\log n / (\log \log n)}(1 + o(1)) & \text{if } \gamma = O(1). \end{cases}$$

Compare with $\text{OPT}(G)/n \approx 1.5264 \sqrt{\gamma}$

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Where does this come from? 1. Dense graphs

Wigner heuristics:

Assume $A = A^\top$ with $(A_{i,j})_{i < j}$ independent, $\mathbb{E}\{A_{ij}\} = 0$,
 $\mathbb{E}\{A_{ij}^2\} = 1/n$. Then

$$\text{ESD}_n \equiv \frac{1}{n} \sum_{i=1}^n \delta_{\lambda_i} \xrightarrow{w} \mu_{\text{sc}}(dx) \equiv \frac{\sqrt{4-x^2}}{2\pi} \mathbf{1}_{|x| \leq 2} dx$$

Further $\lambda_{\max}(A) \rightarrow \sup\{x : x \in \text{supp}\mu_{\text{sc}}\}$,
 $\lambda_{\min}(A) \rightarrow \inf\{x : x \in \text{supp}\mu_{\text{sc}}\}$.

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Where does this come from? 1. Dense graphs

$$\mathbb{E}\{A_{ij}^2\} = \gamma(1 + O(1/n))$$

Wigner heuristics:

$$\lim_{n \rightarrow \infty} \frac{1}{\sqrt{\gamma}} \lambda_{\max}(A_G) = 2$$

Where does this come from? 2. Sparse graphs

$$\begin{aligned}\lambda_{\max}(A_G)^2 &\geq \langle \mathbf{e}_i, A_G^2 \mathbf{e}_i \rangle = \sum_{j=1}^n A_{ij}^2 \\ &\geq \sum_{j \in \partial i} A_{ij}^2 = \left(1 - \frac{\gamma}{n}\right)^2 \deg_G(i)\end{aligned}$$

Hence

$$\lambda_{\max}(A_G) \geq \sqrt{\max \deg_G(i)} (1 + O(1/n)) = \sqrt{\frac{\log n}{\log \log n}} (1 + O(1/n))$$

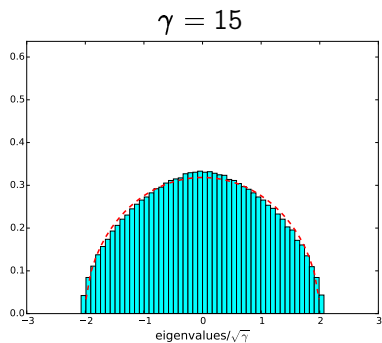
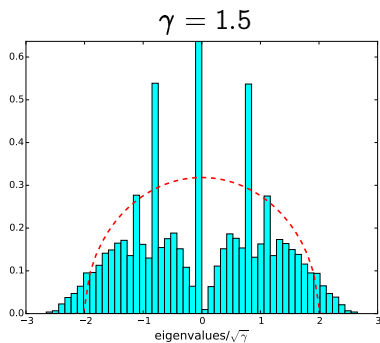
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Illustration: $n = 10,000$



What we learned

- ▶ Spectral relaxations are sensitive to degree heterogeneities
- ▶ Leading eigenvectors are highly localized/uninformative.

Idea: Enforce that solution has all entries of roughly same size!

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Semidefinite Programming (SDP)

$$\begin{aligned} & \text{maximize} && \langle A_G, \sigma\sigma^\top \rangle, \\ & \text{subject to} && \sigma_i \in \{+1, -1\}. \end{aligned}$$

SDP(A_G)

$$\begin{aligned} & \text{maximize} && \langle A_G, X \rangle, \\ & \text{subject to} && X_{ii} = 1, \\ & && X \succeq 0. \end{aligned}$$

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Does it work?

SDP is universal (sparse \approx dense)

Theorem (Montanari, Sen 2015)

If $G \sim \mathcal{G}(n; \gamma/n)$, $\gamma = O(1)$, then, with high probability,

$$\frac{1}{n} \text{SDP}(A_G) = 2\sqrt{\gamma} + o(\sqrt{\gamma})$$

- ▶ $\text{SDP}(A_G)$ behaves much better than the principal eigenvalue

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Proof idea

This is a universality result!

$$\frac{1}{\sqrt{\gamma}} \text{SDP}(A_G) \stackrel{\text{Lindeberg}}{\longleftrightarrow} \text{SDP}(W)$$

$W \sim \text{GOE}(n)$, i.e. $(W_{ij})_{i < j} \sim_{iid} \text{N}(0, 1/n)$

Following same strategy as before

- ▶ Prove $\lim_{n \rightarrow \infty} \text{SDP}(W) = 2$.
- ▶ Replace $\text{SDP}(A)$ by a suitable ‘smooth-max’ $\phi(\beta; A)$
- ▶ Bound $\partial_{A_{ij}}^r \phi(\beta; A)$.
- ▶ Bound $|\text{SDP}(A) - \phi(\beta; A)|$

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Does not quite work!

Where is the problem? Introducing the smooth max

SDP(A):

$$\begin{aligned} & \text{maximize} && \langle A, X \rangle, \\ & \text{subject to} && X_{ii} = 1, \\ & && X \succeq 0. \end{aligned}$$

Equivalent (non-convex) formulation

$$\begin{aligned} & \text{maximize} && \sum_{i,j=1}^n A_{i,j} \langle \sigma_i, \sigma_j \rangle, \\ & \text{subject to} && \sigma \in \mathbb{R}^n, \quad \|\sigma_i\|_2 = 1. \end{aligned}$$

Introducing the smooth max

$$\phi(\beta; A) \equiv \frac{1}{n\beta} \log \left\{ \int \exp \left(\beta \sum_{i,j=1}^n A_{i,j} \langle \sigma_i, \sigma_j \rangle \right) \nu_0(d\sigma) \right\}$$

- ▶ $\nu_0(d\sigma) \equiv$ uniform measure on $S^{n-1} \times \dots \times S^{n-1}$
- ▶ $S^{n-1} \equiv \{\mathbf{x} \in \mathbb{R}^n : \|\mathbf{x}\|_2 = 1\}$
- ▶ Easy to show $\lim_{\beta \rightarrow \infty} \phi(\beta; A) = \text{SDP}(A)$
- ▶ Associated Boltzmann measure

$$\mu_{\beta,A}(d\sigma) = \frac{1}{Z(\beta; A)} \exp \left\{ \beta \sum_{i,j=1}^n A_{ij} \langle \sigma_i, \sigma_j \rangle \right\} \nu_0(d\sigma)$$

Where is the problem?

We want to prove, *uniformly in n* , and for $A \in \{A_G, W\}$

$$\left| \mathbb{E}\phi(\beta; A, n) - \mathbb{E}\phi(\infty; A, n) \right| \leq \varepsilon(\beta)$$

with $\lim_{\beta \rightarrow \infty} \varepsilon(\beta) = 0$.

Let us try as before

$$\frac{\partial \phi(\beta; A)}{\partial (\beta^{-1})} = -\frac{1}{n} D(\mu_{\beta, A} \| \nu_0)$$

- ▶ $\mu_{\beta, A}$ distribution on a continuous space
- ▶ Dimension = $n(n - 1)$

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Idea

- ▶ Constrain $\text{rank}(X) = k = O_n(1)$
- ▶ Bound the error due to ‘rank truncation’

Concretely

Define $\text{OPT}_k(A)$

$$\begin{aligned} & \text{maximize} && \langle A, X \rangle, \\ & \text{subject to} && X_{ii} = 1, \\ & && X \succeq 0, \\ & && \text{rank}(X) = k \end{aligned}$$

For $A = A_G$

- ▶ $k = 1$: Minimum bisection
- ▶ $k = n$: SDP

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Equivalent (non-convex) definition

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Free energy

$$\phi_k(\beta; A) \equiv \frac{1}{n\beta} \log \left\{ \int \exp \left(\beta \sum_{i,j=1}^n A_{i,j} \langle \sigma_i, \sigma_j \rangle \right) \nu_{0,k}(\mathrm{d}\sigma) \right\}$$

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Proof strategy

- ▶ Prove $\lim_{n \rightarrow \infty} \text{SDP}(W) = 2$.
- ▶ Replace SDP by the rank-constrained problem OPT_k .
- ▶ Bound $|\text{SDP}(A) - \text{OPT}_k(A)| \leq o_k(1)$, uniformly in n .
- ▶ Replace $\text{OPT}_k(A)$ by the free energy $\phi_k(\beta; A)$
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- ▶ Bound $\partial_{A_{ij}}^r \phi(\beta; A)$.

Now this works! (Details omitted)

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This works because the spins are bounded. (Details omitted)

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What about this? A new Grothendieck inequality

Grothendieck inequalities

- ▶ First proved by Alexander Grothendieck in 1956
- ▶ Connect non-convex quadratic programs to SDPs
- ▶ Very popular in CS Theory since Alon, Naor 2006
- ▶ We cannot use earlier inequalities:
 - ▶ Symmetric matrices
 - ▶ (Rank = k) \rightarrow (Rank = n)

Higher-rank Grothendieck inequality

Theorem (Montanari, Sen, 2015)

For $k \geq 1$, let $\mathbf{g} \sim \mathcal{N}(0, \mathbf{I}_{k \times k}/k)$ be a vector with i.i.d. centered normal entries with variance $1/k$, and define

$$\alpha_k \equiv (\mathbb{E}\|\mathbf{g}\|_2)^2.$$

Then, for any symmetric matrix B , we have the inequalities

$$\text{OPT}_k(B) \geq \left(2 - \frac{1}{\alpha_k}\right) \text{SDP}(B) + \left(\frac{1}{\alpha_k} - 1\right) \text{OPT}_k(-B).$$

Remarks

- ▶ $\alpha_k = 1 - O(k^{-1})$
- ▶ Obviously $\text{OPT}_k(B) \leq \text{SDP}(B)$
- ▶ The additive error can be bounded crudely:
 $\text{OPT}_k(-B) \geq 0$ with high probability.

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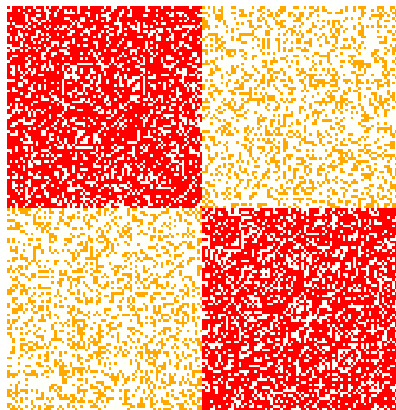
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One application

The hidden partition problem

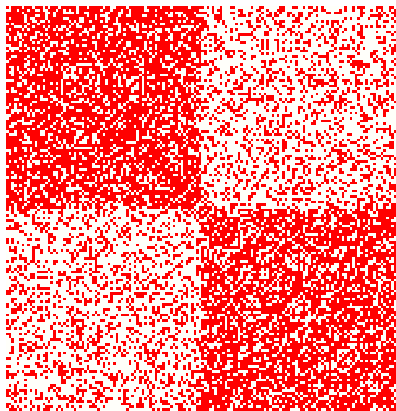
(a.k.a. community detection)



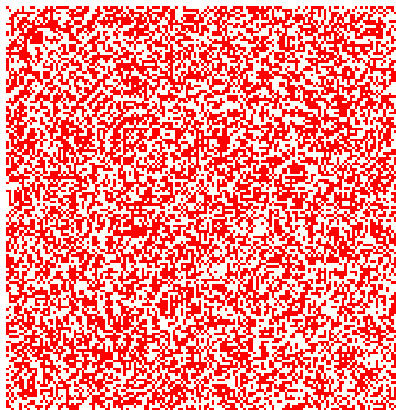
Vertices V , $|V| = n$, $V = S_1 \cup S_2$, $|S_1| = |S_2| = n/2$

$$\mathbb{P}\{(i, j) \in E\} = \begin{cases} p & \text{if } \{i, j\} \subseteq S_1 \text{ or } \{i, j\} \subseteq S_2, \\ q < p & \text{otherwise.} \end{cases}$$

Of course entries are not colored. . .



... and rows/columns are not ordered



Background: Hypothesis testing (sparse graph $p = a/n, q = b/n$)

Hypothesis H_0 :

$$\mathbb{P}\{(i, j) \in E\} = \frac{a + b}{2n}$$

Hypothesis H_1 : $V = S_1 \cup S_2, |S_1| = |S_2| = n/2$

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Detection thresholds

Classical Statistics / Information Theory:

Is there *any algorithm* that detects the hidden structure?

Computational:

Is there a *poly-time algorithm* that detects the hidden structure?

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Information theory threshold

Theorem (Mossel, Neeman, Sly, 2012)

There is a test that succeed with high probability if and only if $a + b > 2$ and

$$\frac{a - b}{\sqrt{2(a + b)}} > 1.$$

[Proves conjecture by Decelle, Krzakala, Moore, Zdeborova, 2011]

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Computational threshold

- ▶ Dyer, Frieze 1989
- ▶ Condon, Karp 2001
- ▶ McSherry 2001
- ▶ Coja-Oghlan 2010
- ▶ Massoulié 2013 and Mossel, Neeman, Sly, 2013

$$p = na > q = nb \text{ fixed.}$$

$$a - b \gg n^{1/2}$$

$$a - b \gg \sqrt{b \log n}$$

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Very ingenious algorithms!

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What if I am not ingenious?

Maximum Likelihood testing

OPT(A_G):

$$\begin{aligned} & \text{maximize} && \langle \boldsymbol{\sigma}, A_G \boldsymbol{\sigma} \rangle, \\ & \text{subject to} && \sigma_i \in \{+1, -1\} \quad . \end{aligned}$$

$$G \sim \mathcal{G}(n, \gamma/n) \Rightarrow \text{OPT}(A_G) \approx (2P_*\sqrt{\gamma} + o(\sqrt{\gamma}))n.$$

$$T_{\text{ML}}(G) = \begin{cases} 1 & \text{if } \text{OPT}(A_G) \geq (2 + \varepsilon)P_*\sqrt{\gamma}n, \\ 0 & \text{otherwise.} \end{cases}$$

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$T_{\text{ML}}(\cdot)$ is hard to compute!

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- ▶ This is really **off-the-shelf**
- ▶ How well does it work?

False positives

Under $H_0 : G \sim \mathcal{G}(n, \gamma/n)$, $\gamma = (a + b)/2$

$$\mathbb{P}_0(T_{\text{SDP}}(G) = 1) = \mathbb{P}_0(\text{SDP}(G) \geq (2 + \varepsilon)\sqrt{\gamma n}) \rightarrow 0$$

provided $\gamma \geq \gamma_0$

False negatives

Under $H_1 : G \sim \mathcal{G}(n, a/n, b/n)$,

$$\mathbb{P}_1(T_{\text{SDP}}(G) = 0) = \mathbb{P}_1(\text{SDP}(G) < (2 + \varepsilon)\sqrt{\gamma n})$$

we need a lower bound on $\text{SDP}(G)$...

Lower bound on $\text{SDP}(A_G)$

Ground truth

$$\sigma_{*,i} = \begin{cases} +1 & \text{if } i \in S_1, \\ -1 & \text{if } i \in S_2, \end{cases}$$

$$\begin{aligned} \text{SDP}(A_G) &\geq \langle A_G, \sigma_* \sigma_*^T \rangle \\ &= \sum_{i,j \in S_1} \mathbf{1}_{(i,j) \in E} + \sum_{i,j \in S_2} \mathbf{1}_{(i,j) \in E} - 2 \sum_{i \in S_1, j \in S_2} \mathbf{1}_{(i,j) \in E} \\ &= \left(\frac{a-b}{2} \right) + O(1/\sqrt{n}) \end{aligned}$$

$\mathbb{P}_1(T_{\text{SDP}}(G) = 0) \rightarrow 0$ provided

$$\frac{a-b}{2} \geq (2 + \varepsilon')\sqrt{\gamma}$$

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Conclusion: It works well

Theorem (Montanari, Sen 2015)

The test based on SDP works with high probability if

$$\frac{a - b}{\sqrt{2(a + b)}} > 2 + o_{a+b}(1).$$

- ▶ At most suboptimal by factor $2 + o_{a+b}(1)$
- ▶ Forthcoming: $2 \rightarrow 1$
- ▶ Earlier result by Guedon, Vershynin 2015: $(a - b) \geq 10^4 \sqrt{a + b}$.
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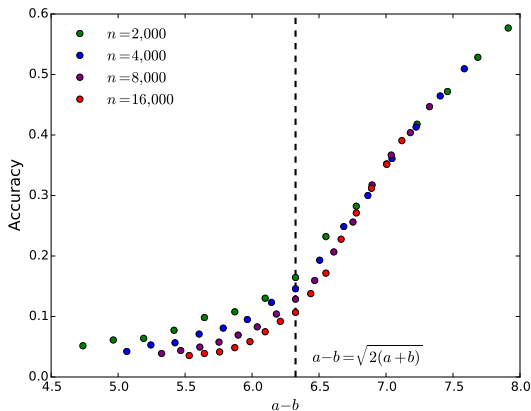
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It works very well in practice!



► Average degree $\gamma \equiv (a + b)/2 = 10$.

[Javanmard, Montanari, Ricci-Tersenghi, in preparation]

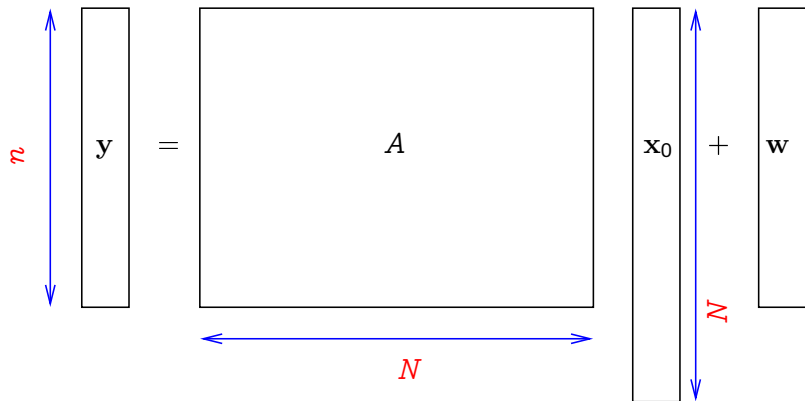
Compressed sensing

Linear observation model

$$\mathbf{y} = A \mathbf{x}_0 + \mathbf{w}$$

Estimate $\mathbf{x}_0 \in \mathbb{R}^N$ given $\mathbf{y} \in \mathbb{R}^n$, $A \in \mathbb{R}^{n \times N}$.
Noise: $\mathbf{w} \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_n)$

Setting



The LASSO

$$\hat{\mathbf{x}}(A, \mathbf{y}) = \operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^N} \mathcal{L}_{A, \mathbf{y}}(\mathbf{x})$$

$$\mathcal{L}_{A, \mathbf{y}}(\mathbf{x}) = \lambda \|\mathbf{x}\|_1 + \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2$$

Finds sparse solutions
[Tibshirani 96; Chen, Donoho 95]

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Random sensing mechanism

- ▶ **IID model:** A_{ij} iid, $\mathbb{E}[A_{ij}] = 0$, $\mathbb{E}[A_{ij}^2] = 1/n$, $\mathbb{E}[A_{ij}^6] \leq C/n^3$
- ▶ **Gaussian model:** $A_{ij} \sim_{iid} \mathcal{N}(0, 1/n)$

Why?

- ▶ ‘Nearly ideal’ sensing mechanism
- ▶ ‘Designed’ sensing matrices are pseudo-random
- ▶ Connections with random polytope geometry
[Donoho, Tanner, Chandrasekaran, Hassibi, Stojnic, Tropp, ...]

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Asymptotically exact characterization for Gaussian model

Gaussian model : Asymptotic characterization

Theorem (Bayati, Montanari, 2010)

Assume the Gaussian model with, $n/N \rightarrow \delta$ and

$$\text{EmpiricalLaw}(\mathbf{x}_0) \equiv \frac{1}{N} \sum_{i=1}^N \delta_{x_{0,i}} \xrightarrow{w} p_{X_0}.$$

Let $(\tau^2, \theta) \in \mathbb{R}_{\geq 0}^2$ be the solution of $(X_0 \sim p_{X_0}, Z \sim N(0, 1))$

$$\begin{aligned}\tau^2 &= \sigma^2 + \frac{1}{\delta} \mathbb{E}\{[\eta(X_0 + \tau Z; \theta) - X_0]^2\}, \\ \lambda &= \theta\{1 - (1/\delta)\mathbb{P}\{|X_0 + \tau Z| \geq \theta\}\}.\end{aligned}$$

Then,

$$\lim_{N \rightarrow \infty} \frac{1}{N} \|\widehat{\mathbf{X}}^{\text{LASSO}}(\lambda) - \mathbf{x}_0\|^2 \stackrel{\text{a.s.}}{=} (\tau_\infty^2 - \sigma^2)\delta.$$

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More generally

Theorem (Bayati, Montanari, 2010)

... same assumptions ...

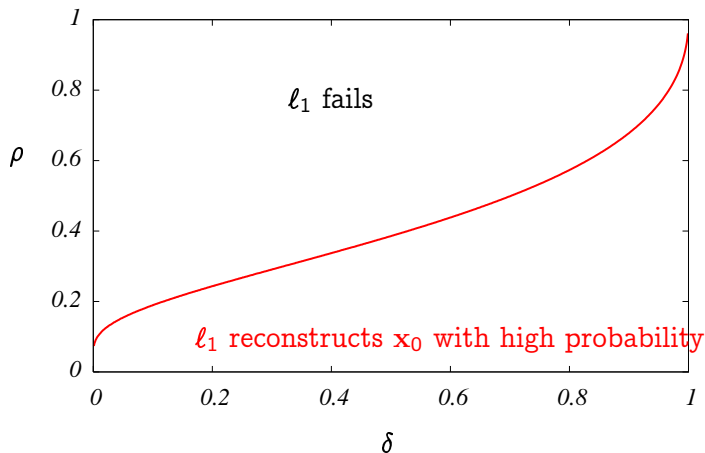
Let $\psi : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ locally Lipschitz, $\psi(a, b) \leq C(1 + a^2 + b^2)$. Then

$$\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \psi(\hat{x}_i^{\text{LASSO}}(\lambda), x_{0,i}) \stackrel{\text{a.s.}}{=} \mathbb{E}\{\psi(\eta(X_0 + \tau Z; \theta), X_0)\}.$$

Setting $\sigma = 0$: ' ℓ_0 - ℓ_1 equivalence'

$$N, n \rightarrow \infty, n/N = \delta,$$

$$|\text{supp}(\mathbf{x}_0)|/N = \delta\rho$$



[Donoho 2006, Affentranger-Schneider 1992]

What about other sensing matrices?

Conjecture (Donoho, Taner, 2009)

The above predictions are universal for a broad range of random matrices.

Conjecture (Weak form)

Universality holds of the IID model.

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Numerical evidence: Random Fourier measurements

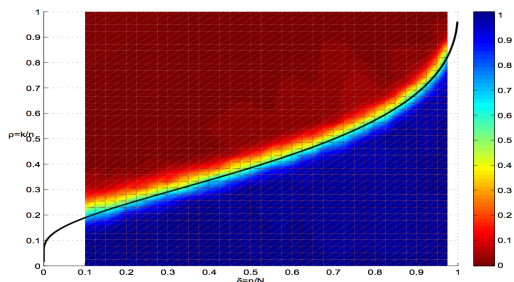
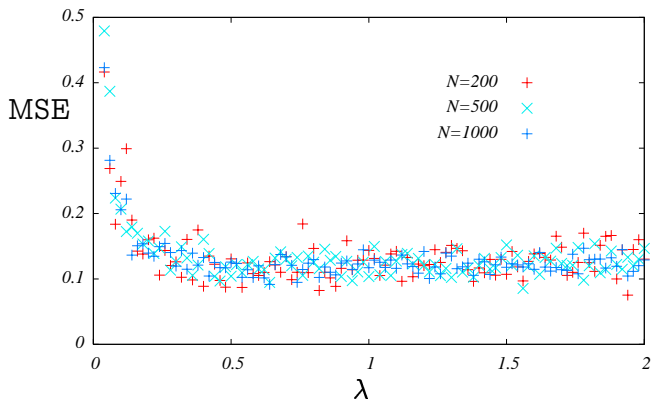


FIGURE 3. *Compressed Sensing from random Fourier measurements.* Shaded attribute: fraction of realizations in which ℓ_1 minimization (1.2) reconstructs an image accurate to within six digits. Horizontal axis: undersampling fraction $\delta = n/N$. Vertical axis: sparsity fraction $\rho = k/n$.

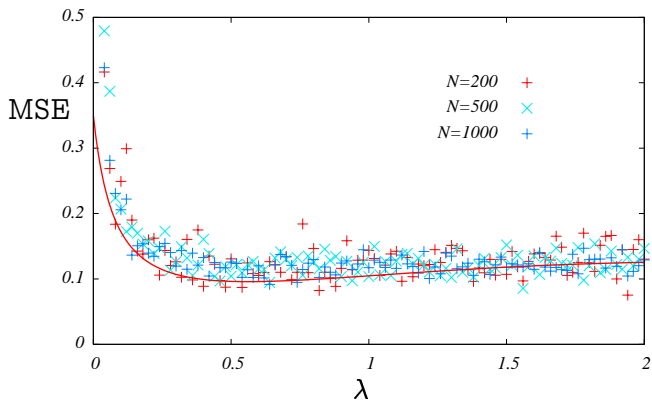
[Donoho, Tanner 2009]

Numerical evidence: Clinical data



A is $n \times N$, $n = 0.64N$

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Universality: Rigorous results

- ▶ Korada, Montanari, 2011:
Universality of the cost $\min \mathcal{L}_{A,y}(\mathbf{x})$
(Lindeberg method)

- ▶ Bayati, Lelarge, Montanari 2012:
Universality of the $\ell_0 - -\ell_1$ phase transition
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Statement

$$\mathcal{L}_{A,\mathbf{y}}(\mathbf{x}) = \lambda \|\mathbf{x}\|_1 + \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2$$
$$\mathcal{L}_M^*(A, \mathbf{y}) = \frac{1}{n} \min \{ \mathcal{L}_{A,\mathbf{y}}(\mathbf{x}) : \mathbf{x} \in \mathbb{R}^N, \|\mathbf{x}\|_\infty \leq M \}$$

Theorem (Korada, Montanari, 2011)

Let $A^{(n)} = (A_{ij})_{1 \leq i \leq n, 1 \leq j \leq N}$ and $B^{(n)} = (B_{ij})_{1 \leq i \leq n, 1 \leq j \leq n}$ denote two sensing matrices from the IID model and the Gaussian model, and assume $\|\mathbf{x}_0\|_\infty \leq M = O_n(1)$.

Consider the limit $n, N \rightarrow \infty$ with $n/N \rightarrow \delta$ fixed. Then

$$\lim_{n, N \rightarrow \infty} \left\{ \mathbb{E} \mathcal{L}_M^*(A^{(n)}, \mathbf{y}) - \mathbb{E} \mathcal{L}_M^*(B^{(n)}, \mathbf{y}) \right\} = 0.$$

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Remarks

$$\lim_{n, N \rightarrow \infty} \left\{ \mathbb{E} \mathcal{L}_M^*(A^{(n)}, \mathbf{y}) - \mathbb{E} \mathcal{L}_M^*(B^{(n)}, \mathbf{y}) \right\} = 0.$$

- ▶ Not hard: $\mathcal{L}_M^*(A^{(n)}, \mathbf{y})$ concentrates around its expectation.
- ▶ From [BayatiMontanari2010]: $\lim_{n, N \rightarrow \infty} \mathbb{E} \mathcal{L}_M^*(A^{(n)}, \mathbf{y})$ exists and depends non-trivially on $\delta, p_{X_0}, \sigma^2$

As in previous examples

- ▶ Replace $\mathcal{L}_M^*(A)$ by free energy $\phi(\beta; A)$.
- ▶ Bound $|\mathcal{L}_M^*(A) - \phi(\beta; A)|$
- ▶ Bound $|\phi(\beta; A^{(n)}) - \phi(\beta; B^{(n)})|$ (Lindeberg)

Free energy

$$\phi(\beta; A) = \frac{1}{N\beta} \log \left\{ \int_{B_M} e^{-\beta \mathcal{L}_{A,y}(\mathbf{x})} d\mathbf{x} \right\}$$
$$B_M \equiv [-M, M]^N$$
$$\mathcal{L}_{A,y}(\mathbf{x}) = \lambda \|\mathbf{x}\|_1 + \frac{1}{2} \|\mathbf{w} - A(\mathbf{x} - \mathbf{x}_0)\|_2^2$$

Associated Boltzmann measure

$$\mu_{\beta,A}(d\mathbf{x}) = \frac{1}{Z(\beta, A)} e^{-\beta \mathcal{L}_{A,y}(\mathbf{x})} d\mathbf{x}$$

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Taking derivatives

$$\partial_{A_{ij}} \phi(\beta; A) = -\frac{1}{N} \mathbb{E}_{\mu} \{ \partial_{A_{ij}} \mathcal{L}_{A,y}(\mathbf{x}) \}$$

$$\mathcal{L}_{A,y}(\mathbf{x}) = \lambda \|\mathbf{x}\|_1 + \frac{1}{2} \|\mathbf{w} - A(\mathbf{x} - \mathbf{x}_0)\|_2^2$$

$$\partial_{A_{ij}} \mathcal{L}_{A,y}(\mathbf{x}) = -[\mathbf{w} - A(\mathbf{x} - \mathbf{x}_0)]_i (x_j - x_{0,j})$$

Naive bound:

$$\begin{aligned} |\partial_{A_{ij}} \mathcal{L}_{A,y}(\mathbf{x})| &\leq 2M |[A(\mathbf{x} - \mathbf{x}_0)]_i| + \dots \\ &\leq 4M^2 \|A_{i,\cdot}\|_1 + \dots \leq C N^{1/2} \end{aligned}$$

Taking derivatives

$$\partial_{A_{ij}} \phi(\beta; A) = -\frac{1}{N} \mathbb{E}_{\mu} \{ \partial_{A_{ij}} \mathcal{L}_{A,y}(\mathbf{x}) \}$$

$$\mathcal{L}_{A,y}(\mathbf{x}) = \lambda \|\mathbf{x}\|_1 + \frac{1}{2} \|\mathbf{w} - A(\mathbf{x} - \mathbf{x}_0)\|_2^2$$

$$\partial_{A_{ij}} \mathcal{L}_{A,y}(\mathbf{x}) = -[\mathbf{w} - A(\mathbf{x} - \mathbf{x}_0)]_i (x_j - x_{0,j})$$

Naive bound:

$$\begin{aligned} |\partial_{A_{ij}} \mathcal{L}_{A,y}(\mathbf{x})| &\leq 2M |[A(\mathbf{x} - \mathbf{x}_0)]_i| + \dots \\ &\leq 4M^2 \|A_{i,\cdot}\|_1 + \dots \leq C N^{1/2} \end{aligned}$$

Second/third derivatives

$$\begin{aligned}\partial_{A_{ij}}^2 \phi(\beta; A) &= \dots + \frac{\beta}{N} \mathbb{E}_\mu \{ \partial_{A_{ij}} \mathcal{L}_{A, \mathbf{y}}(\mathbf{x}) \}^2, \\ \partial_{A_{ij}}^3 \phi(\beta; A) &= \dots + \frac{\beta^2}{N} \mathbb{E}_\mu \{ \partial_{A_{ij}} \mathcal{L}_{A, \mathbf{y}}(\mathbf{x}) \}^3.\end{aligned}$$

Naive bound:

$$\| \partial_{A_{ij}}^2 \phi(\beta; A) \|_\infty \leq C, \quad \| \partial_{A_{ij}}^3 \phi(\beta; A) \|_\infty \leq C N^{1/2}.$$

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Lindeberg Bound

$$\begin{aligned} & |\mathbb{E}\phi(\beta; A^{(n)}) - \mathbb{E}\phi(\beta; B^{(n)})| \leq \\ & \leq \|\partial_{A_{ij}}^2 \phi(\beta; A)\|_\infty \sum_{i,j} \mathbb{E}\{|A_{ij}|^2 \mathbf{1}_{|A_{ij}| > K/\sqrt{n}}\} \\ & \quad + \|\partial_{A_{ij}}^3 \phi(\beta; A)\|_\infty \sum_{i,j} \mathbb{E}\{|A_{ij}|^3 \mathbf{1}_{|A_{ij}| \leq K/\sqrt{n}}\} + \dots \\ & \leq C \cdot Nn \cdot \frac{K^2}{n} e^{-K^2/2} + CN^{1/2} \cdot Nn \cdot \frac{K^3}{n^{3/2}} \end{aligned}$$

Where is the issue?

$$\begin{aligned}\partial_{A_{ij}}^2 \phi(\beta; A) &= \dots + \frac{\beta}{N} \mathbb{E}_\mu \{ \partial_{A_{ij}} \mathcal{L}_{A, \mathbf{y}}(\mathbf{x}) \}^2, \\ \partial_{A_{ij}} \mathcal{L}_{A, \mathbf{y}}(\mathbf{x}) &= -[\mathbf{w} - A(\mathbf{x} - \mathbf{x}_0)]_i (x_j - x_{0,j})\end{aligned}$$

For instance, consider $\mathbb{E}_\mu \{ [A(\mathbf{x} - \mathbf{x}_0)]_i \}$

Naive bound:

$$|\mathbb{E}_\mu \{ [A(\mathbf{x} - \mathbf{x}_0)]_i \}| \leq \mathbb{E}_\mu \{ \|A_{i, \cdot}\|_1 \} \|\mathbf{x} - \mathbf{x}_0\|_\infty \leq C N^{1/2}$$

Independent vectors heuristics

$$|\mathbb{E}_\mu \{ [A(\mathbf{x} - \mathbf{x}_0)]_i \}| \approx \frac{1}{N^{1/2}} \mathbb{E}_\mu \{ \|A_{i, \cdot}\|_2^2 \}^{1/2} \mathbb{E}_\mu \{ \|\mathbf{x} - \mathbf{x}_0\|_2^2 \}^{1/2} \leq C$$

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The independent vectors heuristics is kroughly correct!

Proof: Read the paper!

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Conclusion

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- ▶ **Universality!!**

A model is not really predictive unless it has some degree of universality

- ▶ **Lindeberg!!**

A tool you should put in your backpack

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