

A NEW CLASS OF STRONGLY CONSISTENT VARIANCE ESTIMATORS FOR STEADY-STATE SIMULATIONS

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The principal problem associated with steady-state simulation is the estimation of the variance term in an associated central limit theorem. This paper develops several strongly consistent estimates for this term using the strong approximations available for Brownian motion. A comparison of rates of convergence is given for a variety of estimators.

Brownian motion * confidence intervals * rates of convergence * regenerative simulation * simulation output analysis * steady-state simulation * strong approximation laws * strongly consistent estimation

1. Introduction

Let $X = \{X(t): t \geq 0\}$ be a real-valued (measurable) stochastic process representing the output of a simulation. (To incorporate output sequences X_n into our framework, we set $X(t) = X_{[t]}$, where $[t]$ is the greatest integer less than or equal to t .) The process X is said to possess a steady-state if there exists a finite constant r such that

$$r(t) \equiv \frac{1}{t} \int_0^t X(s) ds \Rightarrow r \quad (1.1)$$

as $t \rightarrow \infty$, where \Rightarrow denotes weak convergence. The problem of consistently estimating and producing confidence intervals for the parameter r is known, in the simulation literature, as the steady-state simulation problem.

A similar problem arises when one is asked to statistically analyze the mean of a stationary process, given that the statistical data observed is the time series $\{X(s): 0 \leq s \leq t\}$. The results of this paper, although phrased in a simulation context, have obvious statistical analogues for this time series setting.

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The limit theorem (1.1) suggests that $r(t)$ can be used to consistently estimate r . It turns out that one can frequently establish that the output process X in fact satisfies a somewhat stronger relation, namely, there exist finite constants r and σ such that

$$t^{1/2}(r(t) - r) \Rightarrow \sigma N(0, 1). \quad (1.2)$$

Suppose now that one can construct an estimator $s(t)$ such that

$$s(t) \Rightarrow \sigma \quad (1.3)$$

as $t \rightarrow \infty$. Then, (1.2) and (1.3) together imply that if $\sigma > 0$, then the interval

$$\left[r(t) - z(\delta) \frac{s(t)}{t^{1/2}}, r(t) + z(\delta) \frac{s(t)}{t^{1/2}} \right] \quad (1.4)$$

is an asymptotic $100(1 - \delta)\%$ confidence interval for r , provided that $z(\delta)$ is chosen to solve the equation $P\{N(0, 1) \leq z(\delta)\} = 1 - \delta/2$.

The above discussion suggests that in the presence of an output process satisfying (1.2) with $\sigma > 0$, the steady-state simulation problem is, in principle, solved, once an estimator $s(t)$ for σ has been constructed. Thus, the determination of an estimator $s(t)$ for σ can be viewed as the fundamental problem of steady-state simulation output analysis. (It should, however, be noted that certain output analysis methods employ a different approach, which does not require explicit estimation of σ ; the methods of batch means (see pp. 85–89 of Bratley, Fox and Schrage (1983) for a description) and standardized time series (Schruben (1983)) fall into this category).

As a consequence of the above observation, a great deal of attention has been focused on the construction of such estimators for σ . In some sense, all currently available estimation methods make use of the fact that if X is well-behaved and approximately stationary, then (1.2) suggests that

$$\lim_{t \rightarrow \infty} E(t(r(t) - r))^2 = \sigma^2 E N(0, 1)^2$$

in which case the equality

$$2 \int_0^\infty E X_c(0) X_c(t) dt = \sigma^2 \quad (1.5)$$

should hold, where $X_c(t) \equiv X(t) - r$. Conditions guaranteeing (1.5) for regenerative processes appear on Glynn and Iglehart (1986). Spectral procedures (see pp. 95–98 of [3]) use kernel estimators to estimate the left-hand side of (1.5), whereas autoregressive methods (see pp. 98–101 of [3]) fit an autoregressive process to X , compute the analog of (1.5) for the fitted process, and use that quantity as an estimator of (1.5) for X . As for the regenerative method (see pp. 89–94 of [3]), it, loosely speaking, uses the special structure of a regenerative process to “truncate” the integral on the left-hand side of (1.5) at a regeneration time, thereby simplifying the estimation problem.

In this paper, we propose a new method for consistently estimating σ , which does not make any explicit use of relationship (1.5). Our estimators are based on known limit theorems about the increments of Brownian motion; the constant σ appears as a scaling constant in these limit theorems. We then use strong approximation methods to translate the resulting estimator for σ from the Brownian motion back to the original output process X ; the resulting estimator for σ depends only on the observed values of X , and not the Brownian motion.

In some respects, our method is similar to that of Schruben (1983). The method of standardized time series depends on the fact that σ appears as a scaling constant when one weakly approximates the original process by a Brownian motion; σ is not estimated but is instead “cancelled” out. By contrast our method involves strong approximation results and gives rise to strongly consistent estimators for σ . As proved in Glynn and Iglehart (1985), consistent estimation of σ enjoys certain asymptotic advantages over standardized time series.

In Section 2, we introduce our estimators $s(t)$ for σ ; our basic hypothesis on X is that a suitable strong approximation by Brownian motion is possible. Section 3 is devoted to discussion of processes X which satisfy the strong approximation hypothesis. In Section 4, the rate of convergence of $s(t)$ to σ is studied, and compared to that available via the regenerative method. Our main contribution here is to suggest that entirely new methods for estimating σ may be worth exploring. Further comparison of these new methods with the old methods should be carried out via numerical examples.

2. A new class of estimators for σ

Let $S = \{S(t) : t \geq 0\}$, where $S(t) = \int_0^t X(s) ds$. Throughout this section, we shall assume that:

- (2.1) there exists a probability space supporting a process S^* and a standard Brownian motion such that:
 - (i) the distribution of S equals that of S^*
 - (ii) $S^*(t) - rt = \sigma B(t) + O(t^{1/2-\lambda})$ a.s. for some constants r, σ , and λ ($0 < \lambda < \frac{1}{2}, \sigma > 0$) as $t \rightarrow \infty$.

We shall refer to (2.1) as our strong approximation assumption; it says that a process S^* , possessing precisely the same distribution as S , can be a.s. well approximated by a Brownian motion. Note that under (2.1) (ii),

$$t^{-1/2}(S^*(t) - rt) - t^{-1/2}\sigma B(t) \rightarrow 0 \quad \text{a.s.} \tag{2.2}$$

as $t \rightarrow \infty$. By (2.1)(i), it follows that (2.1) implies (1.2).

For $0 < p < 1$, let

$$s_1(t) = \sup_{0 \leq u \leq t-t^p} \frac{S(u+t^p) - r(t)t^p - S(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}}.$$

(2.3) Theorem. *If p is chosen so that $p + 2\lambda > 1$, $0 < p < 1$, then $s_1(t) \rightarrow \sigma$ a.s. as $t \rightarrow \infty$.*

Proof. Csörgő and Révész (1979a) showed that

$$\lim_{t \rightarrow \infty} \sup_{0 \leq u \leq t-t^p} \frac{B(u+t^p) - B(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}} = 1 \quad \text{a.s.} \quad (2.4)$$

Let $S_c^*(t) = S^*(t) - rt$. By (2.1)(ii), $S_c^*(t) = \sigma B(t) + O(t^{1/2-\lambda})$ a.s. so it follows that

$$\sup_{0 \leq u \leq t-t^p} |\sigma B(u+t^p) - \sigma B(u) - S_c^*(u+t^p) + S_c^*(u)| = O(t^{1/2-\lambda}) \quad \text{a.s.} \quad (2.5)$$

Relations (2.4) and (2.5), together with the condition $p + 2\lambda > 1$, imply that

$$\lim_{t \rightarrow \infty} \sup_{0 \leq u \leq t-t^p} \frac{S_c^*(u+t^p) - S_c^*(u)}{(2t^p \cdot (1-p) \log t)^{1/2}} = \sigma \quad \text{a.s.,} \quad (2.6)$$

i.e.,

$$\lim_{t \rightarrow \infty} \sup_{0 \leq u \leq t-t^p} \frac{S^*(u+t^p) - rt^p - S^*(u)}{(2t^p \cdot (1-p) \log t)^{1/2}} = \sigma \quad \text{a.s.}$$

Furthermore, the law of the iterated logarithm for Brownian motion implies that

$$\overline{\lim}_{t \rightarrow \infty} \left| \frac{B(t)}{(2t \log \log t)^{1/2}} \right| = 1 \quad \text{a.s.} \quad (2.7)$$

Applying the strong approximation (2.1)(ii) to (2.7), we find that

$$|r^*(t) - r| = O\left(\frac{\log \log t}{t}\right)^{1/2} \quad \text{a.s.} \quad (2.8)$$

where $r^*(t) = S^*(t)/t$. Since $(\log \log t)^{1/2} \cdot t^{(p-1)} \rightarrow 0$, it follows from (2.6) and (2.8) that

$$\lim_{t \rightarrow \infty} \sup_{0 \leq u \leq t-t^p} \frac{S^*(u+t^p) - t^p r^*(t) - S^*(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}} = \sigma \quad \text{a.s.} \quad (2.9)$$

But S has the same distribution as S^* , so the theorem follows immediately from (2.9).

We can further define the following estimators:

$$s_2(t) = \sup_{0 \leq u \leq t-t^p} \left| \frac{S(u+t^p) - r(t)t^p - S(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}} \right|,$$

$$s_3(t) = \sup_{0 \leq u \leq t-t^p} \sup_{0 \leq v \leq t^p} \frac{S(u+v) - r(t)v - S(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}},$$

$$s_4(t) = \sup_{0 \leq u \leq t-t^p} \sup_{0 \leq v \leq t^p} \left| \frac{S(u+v) - r(t)v - S(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}} \right|,$$

$$s_5(t) = \inf_{0 \leq u \leq t-t^p} \sup_{0 \leq v \leq t^p} \left| \frac{S(u+v) - r(t)v - S(u)}{\alpha(t)} \right|,$$

where

$$\alpha(t) = (8 \cdot (1-p) \cdot \log t / \pi^2 t^p)^{1/2}.$$

(2.10) Theorem. *If p is chosen so that $p + 2\lambda > 1$, $0 < p < 1$, then $s_i(t) \rightarrow \sigma$, a.s. as $t \rightarrow \infty$, $2 \leq i \leq 5$.*

The proof of this theorem follows exactly as for Theorem 2.4; the key is to have available an analog to (2.4) for Brownian motion, for each of the estimators $s_i(t)$, $2 \leq i \leq 5$. For $s_i(t)$, $2 \leq i \leq 4$, we refer to Csörgő and Révész (1979a); for $s_5(t)$, the result can be found in Csörgő and Révész (1979b).

3. Strong approximation of stochastic processes

We now proceed to discuss conditions under which Assumption 2.1 holds.

Setting 1. Let $Y = \{Y(t) : t \geq 0\}$ be a (possibly) delayed regenerative process with regeneration times $0 \leq T(0) < T(1) < \dots$. If f is a real-valued function defined on the state space of Y , set $X(t) = f(Y(t))$. Let $\tau(k) = T(k) - T(k-1)$ for $k \geq 1$, and assume that Y is positive recurrent in the sense that $E\tau(1) < \infty$. Suppose further that there exists $0 < \delta < 2$ such that

$$\begin{aligned}
 \text{(i)} \quad & E \left(\int_{T(0)}^{T(1)} |X(s)| \, ds \right)^{2+\delta} < \infty \\
 \text{(ii)} \quad & E\tau(1)^{1+\delta/2} < \infty \\
 \text{(iii)} \quad & EZ^2(1) > 0, \text{ where}
 \end{aligned}
 \tag{3.1}$$

$$Z(n) = \int_{T(n-1)}^{T(n)} (X(s) - \mu) \, ds \quad \text{and} \quad \mu \equiv E \left(\int_{T(0)}^{T(1)} X(s) \, ds \right) / E\tau(1).$$

Then, (2.1) is satisfied with $r = \mu$, $\sigma^2 = EZ^2(1) / E\tau(1)$, and λ satisfying $0 < \lambda < \delta / (4 + 2\delta)$; see pp. 117-122 of Philipp and Stout (1975) for a proof in the case where Y is a countable state irreducible Markov chain (their argument easily adapts to the more general regenerative setting described above).

Setting 2. Let $X = \{X_n : n \geq 0\}$ be a strictly stationary sequence of r.v.'s for which there exists $0 < \delta \leq 1$ such that $E|X_0|^{2+\delta} < \infty$. Suppose, in addition, that X is ϕ -mixing (see Section 20 of Billingsley (1968) for a discussion) with mixing coefficients satisfying

$$\sum_{n=1}^{\infty} \phi(n)^{1/2} < \infty.$$

If

$$\alpha = 2 \int_0^{\infty} EX_c(0)X_c(s) \, ds > 0
 \tag{3.2}$$

(the integral (3.2) converges absolutely under the current hypotheses), then (2.1) is satisfied with $r = EX(0)$, $\sigma^2 = \alpha$, and λ satisfying $0 < \lambda < \delta / (24 + 12\delta)$ (if X_0 is bounded a.s., then λ can be chosen to be $1/12$). This result can be found on pp. 26-38 of [11]. (For a version of this result in the case when $\sum_{n=1}^{\infty} \phi(n)^{1/2} < \infty$, see Berkes and Philipp (1979).)

Further strong approximation theorems are also available for lacunary trigonometric series, martingale processes, Gaussian sequences, and strongly mixing processes; see [11] for a complete description of such results. Thus, the assumption (2.1) is satisfied by a large class of stochastic processes exhibiting weak time dependencies.

We should also comment that the convergence rates (i.e., the size of λ) quoted above for regenerative processes and ϕ -mixing sequences can probably be improved. For example, much better results are available for sequences of independent and identically distributed (i.i.d.) r.v.'s. In particular, it is reasonable to expect that results for regenerative processes can be obtained for λ arbitrarily close to $\frac{1}{2}$.

Setting 3. Let $X = \{X_n : n \geq 0\}$ be a sequence of non-degenerate i.i.d.r.v.'s with $E|X_0|^\beta < \infty$ for $\beta > 2$. Then, (2.1) is satisfied with $r = EX_0$, $\sigma^2 = \text{var}(X_0)$, and $\lambda = 1 - 1/\beta$; see Komlós, Major and Tusnády (1975, 1976) and Major (1976) for proofs.

These strong approximation results indicate the general flavor of the theory. The quality of the strong approximation is determined by λ , in the sense that the larger is λ , the more that one can infer about the process by comparison with Brownian motion. The size of λ depends, roughly speaking, on two factors. First, if the process has weak time-dependent correlations, then λ will tend to be large. Second, a good strong approximation (i.e., large λ) is possible only if the process is relatively insensitive to outliers. To see the second point, observe that if $S_n - rn = \sigma B(n) + O(n^{1/2-\lambda})$ a.s., then $X_n \equiv S_n - S_{n-1} = \sigma(B(n) - B(n-1)) + O(n^{1/2-\lambda})$ a.s. Since

$$\max_{1 \leq k \leq n} |B(k) - B(k-1)| = O(\log n) \quad \text{a.s.}$$

(apply the Borel-Cantelli lemma), it follows that

$$\max_{1 \leq k \leq n} |X_k| = O(n^{1/2-\lambda}) \quad \text{a.s.}$$

Thus, if λ is close to $\frac{1}{2}$, the extreme fluctuations of the $|X_k|$'s cannot be too large. This "outlier" analysis proves the necessity of the moment conditions in Setting 3.

As for the implications of these results on the practical implementation of the procedures described in Section 2, it appears unrealistic to expect that one can numerically estimate the maximal value of λ for a given simulation or time series. This suggests that a conservative implementation of Section 2's procedures would involve choosing p fairly close to one, since such a choice is valid over a large range of λ , namely $\lambda \in ((1-p)/2, \frac{1}{2})$.

4. Comparison of convergence rates

It has been shown by Révész (1980) that if $0 < p < 1$, then

$$\overline{\lim}_{t \rightarrow \infty} (\log t)^{1/2+\delta} \left| \sup_{0 \leq u \leq t-t^p} \frac{B(u+t^p) - B(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}} - \sigma \right| = 0 \quad \text{a.s.,}$$

$$\overline{\lim}_{t \rightarrow \infty} (\log t)^{1/2+\delta} \left| \sup_{0 \leq u \leq t-t^p} \sup_{0 < v \leq t^p} \frac{B(u+v) - B(u)}{(2t^p \cdot (1-p) \cdot \log t)^{1/2}} - \sigma \right| = 0 \quad \text{a.s.}$$

for $\delta = 0$; it is further indicated in Csörgő and Steinebach (1981) that for $\delta > 0$, the above lim sup's are infinite.

Using the strong approximation (2.1), it follows that

$$\overline{\lim}_{t \rightarrow \infty} (\log t)^{(1/2)+\delta} |s_i(t) - \sigma| = 0 \quad \text{a.s.}$$

for $\delta = 0$ ($i = 1, 3$), whereas divergence occurs if $\delta > 0$. Thus, the rate of convergence of $s_i(t)$ ($i = 1, 3$) to σ is, roughly speaking, of order $(\log t)^{-1/2}$.

It is instructive to compare this rate of convergence to that available when σ is estimated via the regenerative method of simulation (we choose this method as a basis for comparison, since we can do the convergence rate analysis easily in this setting).

Let Y be a regenerative process with regeneration times $0 \leq T(0) < T(1) < \dots$; set $X(t) = f(Y(t))$, where f is a real-valued function defined on the state space of Y . Put $T(-1) = 0$ and let $N(t) = \max\{k \geq -1: T(k) \leq t\}$. The basic regenerative estimator for σ is given by

$$s(t) = \begin{cases} 0, & N(t) \leq 0, \\ \left[\frac{1}{t} \sum_{i=1}^{N(t)} (V_i - r(t)\tau_i)^2 \right]^{1/2}, & N(t) \geq 1, \end{cases}$$

where

$$V_i = \int_{T(i-1)}^{T(i)} X(s) ds \quad \text{and} \quad \tau_i = T(i) - T(i-1).$$

(4.2) Theorem. *If*

$$E \left(\int_{T(i-1)}^{T(i)} (|X(s)| + 1) ds \right)^4 < \infty,$$

then

$$\overline{\lim}_{t \rightarrow \infty} \sqrt{\frac{t}{2 \log \log t}} |s(t) - \sigma| = \beta^{1/2} \quad \text{a.s.,}$$

where

$$\beta = \frac{1}{4\sigma^2 \cdot E\tau_1} \cdot E[A_1 - \lambda Z_1]^2,$$

$$Z_n = V_n - r\tau_n,$$

$$A_n = Z_n^2 - \sigma^2\tau_n,$$

and

$$\lambda = 2EZ_1\tau_1/E\tau_1.$$

Recall that, for regenerative processes,

$$r = EV_1/E\tau_1 \quad \text{and} \quad \sigma^2 = EZ_1^2/E\tau_1,$$

so that Z_n and A_n are mean-zero r.v.'s; we will need this fact in our proof of Theorem 4.2. Also, we remark that Theorem 4.2 is a statement of the law of the iterated logarithm for the estimator $s(t)$.

Proof (of Theorem 4.2). On the event $\{N(t) \geq 1\}$, observe that if $v(t) = s^2(t)$, then

$$\begin{aligned} v(t) - \sigma^2 &= \frac{1}{t} \sum_{i=1}^{N(t)} Z_i^2 + 2(r - r(t)) \cdot \frac{1}{t} \sum_{i=1}^{N(t)} Z_i\tau_i \\ &\quad + (r - r(t))^2 \cdot \frac{1}{t} \sum_{i=1}^{N(t)} \tau_i^2 \\ &= \frac{1}{t} \sum_{i=1}^{N(t)} (A_i - \lambda Z_i) - 2 \int_{T(N(t))}^t (X(s) - r) ds \cdot \frac{1}{t^2} \sum_{i=1}^{N(t)} Z_i\tau_i \\ &\quad + 2(r - r(t)) \cdot \left(\frac{1}{t} \sum_{i=1}^{N(t)} Z_i\tau_i - \frac{EZ_1\tau_1}{E\tau_1} \right) \\ &\quad + (r - r(t))^2 \cdot \frac{1}{t} \sum_{i=1}^{N(t)} \tau_i^2. \end{aligned} \tag{4.3}$$

But $s(t) = g(v(t))$ where $g(x) = x^{1/2}$, so by Taylor's theorem, we have

$$s(t) = \sigma + g'(\xi(t))(v(t) - \sigma^2)$$

where $\xi(t)$ lies between $v(t)$ and σ^2 and $g'(x) = 1/(2x^{1/2})$. Since $v(t) \rightarrow \sigma^2$ a.s., it follows that $g'(\xi(t)) \rightarrow 1/(2\sigma)$ a.s. Thus, to prove the theorem, it suffices to show that

$$\overline{\lim}_{t \rightarrow \infty} \sqrt{\frac{t}{2 \log \log t}} |v(t) - \sigma^2| = 2\sigma\beta^{1/2} \quad \text{a.s.} \tag{4.4}$$

By the Hartman-Wintner law of the iterated logarithm and the fact that $N(t) \rightarrow \infty$ a.s., we have that

$$\overline{\lim}_{t \rightarrow \infty} \sqrt{\frac{N(t)}{2 \log \log N(t)}} \left| \frac{1}{N(t)} \sum_{i=1}^{N(t)} (A_i - \lambda Z_i) \right| = 2\sigma\beta^{1/2} (E\tau_1)^{1/2} \quad \text{a.s.}$$

But $N(t)/t \rightarrow 1/E\tau_i$ a.s. as $t \rightarrow \infty$, so

$$\overline{\lim}_{t \rightarrow \infty} \sqrt{\frac{t}{2 \log \log t}} \left| \frac{1}{t} \sum_{i=1}^{N(t)} (A_i - \lambda Z_i) \right| = 2\sigma\beta^{1/2} \quad \text{a.s.}, \tag{4.5}$$

$$\overline{\lim}_{t \rightarrow \infty} \frac{t}{\log \log t} \left| (r - r(t)) \cdot \left(\frac{1}{t} \sum_{i=1}^{N(t)} Z_i \tau_i - \frac{EZ_1 \tau_1}{E\tau_1} \right) \right| < \infty \quad \text{a.s.}, \text{ and} \tag{4.6}$$

$$\overline{\lim}_{t \rightarrow \infty} \frac{t}{\log \log t} \left| (r - r(t))^2 \cdot \left(\frac{1}{t} \sum_{i=1}^{N(t)} \tau_i^2 \right) \right| < \infty \quad \text{a.s.} \tag{4.7}$$

Furthermore,

$$\int_{T(N(t))}^t |X(s) - r| ds \leq \max_{1 \leq k \leq N(t)+1} \left(\int_{T(k-1)}^{T(k)} |X(s)| ds + |r| \tau_k \right).$$

Our moment hypothesis allows one to apply the Borel-Cantelli lemma to obtain

$$\left(\int_{T(k-1)}^{T(k)} |X(s)| ds + |r| \tau_k \right) / k^{1/4} \rightarrow 0 \quad \text{a.s.}$$

as $k \rightarrow \infty$; this shows that

$$\frac{1}{t^{1/4}} \cdot \max_{1 \leq k \leq N(t)+1} \left(\int_{T(k-1)}^{T(k)} |X(s)| ds + |r| \tau_k \right) \rightarrow 0 \quad \text{a.s.}$$

as $t \rightarrow \infty$. Hence

$$\overline{\lim}_{t \rightarrow \infty} t^{3/4} \left| \int_{T(N(t))}^t (X(s) - r) ds \cdot \frac{1}{t^2} \sum_{i=1}^{N(t)} Z_i \tau_i \right| = 0 \quad \text{a.s.} \tag{4.8}$$

as $t \rightarrow \infty$. Combining (4.5), (4.6), (4.7), and (4.8), we see that the decomposition (4.3) yields (4.4).

Roughly speaking, Theorem 4.2 says that $s(t)$ converges to σ at rate $(\log \log t/t)^{1/2}$. By comparison with the previously obtained convergence rate for $s_i(t)$ ($i = 1, 3$), this is *much* faster. This does not necessarily, however, imply that the estimators $s_i(t)$ for σ will behave worse than the regenerative estimator for purposes of confidence interval generation, since the coverage of the interval depends on many additional factors.

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