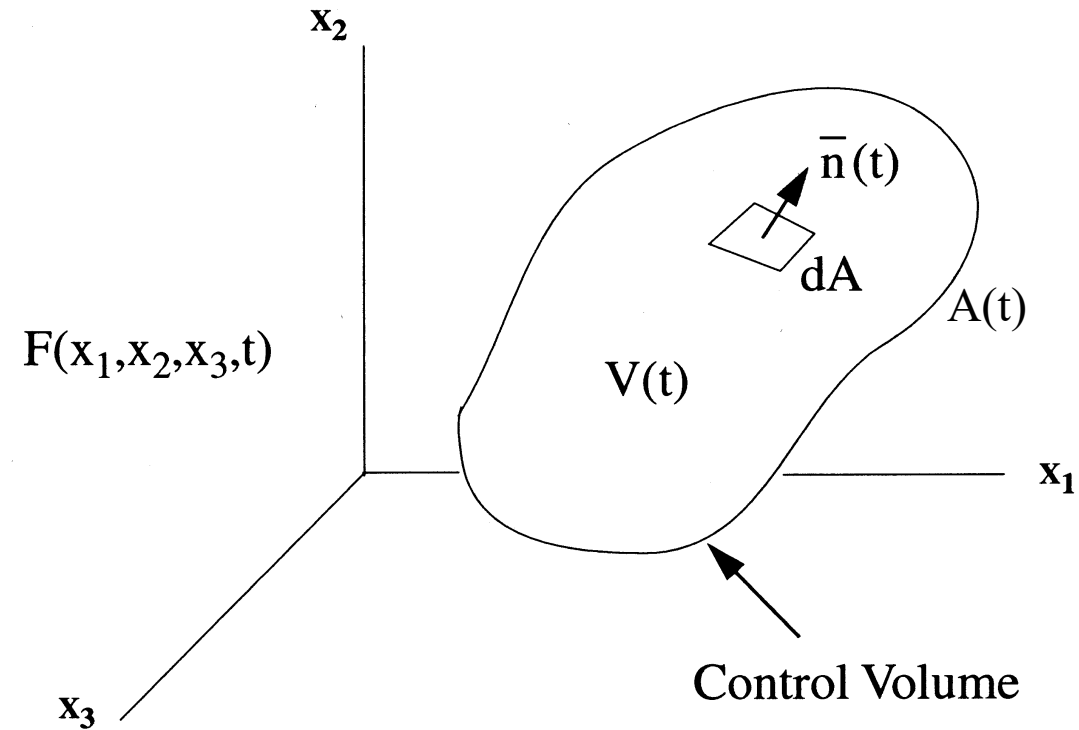


AA210A

Fundamentals of Compressible Flow

Chapter 3 - Control volumes, vector calculus

3.1 Control volume definition



The control volume is a closed, simply connected region in space.

3.2 Vector calculus

Gradient operator

$$\nabla \equiv \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) = \frac{\partial}{\partial x_i}$$

Gradient of a scalar

$$\nabla F = \left(\frac{\partial F}{\partial x}, \frac{\partial F}{\partial y}, \frac{\partial F}{\partial z} \right) = \frac{\partial F}{\partial x_i}$$

Gradient of a vector.

$$\nabla \bar{F} = \begin{pmatrix} \frac{\partial F_1}{\partial x_1} & \frac{\partial F_1}{\partial x_2} & \frac{\partial F_1}{\partial x_3} \\ \frac{\partial F_2}{\partial x_1} & \frac{\partial F_2}{\partial x_2} & \frac{\partial F_2}{\partial x_3} \\ \frac{\partial F_3}{\partial x_1} & \frac{\partial F_3}{\partial x_2} & \frac{\partial F_3}{\partial x_3} \end{pmatrix} = \frac{\partial F_i}{\partial x_j}$$

Divergence of a vector.

$$\nabla \bullet \bar{F} = \text{trace}(\nabla \bar{F}) = \delta_{ij} \frac{\partial F_i}{\partial x_j}$$

$$\frac{\partial F_1}{\partial x_1} + \frac{\partial F_2}{\partial x_2} + \frac{\partial F_3}{\partial x_3} = \frac{\partial F_i}{\partial x_i}$$

The Kronecker unit tensor.

$$\delta_{ij} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

The dot product of a vector and a tensor.

$$\bar{F} \bullet \nabla \bar{F} = F_j \frac{\partial F_i}{\partial x_j} = \begin{pmatrix} F_1 \frac{\partial F_1}{\partial x_1} + F_2 \frac{\partial F_1}{\partial x_2} + F_3 \frac{\partial F_1}{\partial x_3} \\ F_1 \frac{\partial F_2}{\partial x_1} + F_2 \frac{\partial F_2}{\partial x_2} + F_3 \frac{\partial F_2}{\partial x_3} \\ F_1 \frac{\partial F_3}{\partial x_1} + F_2 \frac{\partial F_3}{\partial x_2} + F_3 \frac{\partial F_3}{\partial x_3} \end{pmatrix}$$

Curl of a vector.

$$\nabla \times \bar{F} = \begin{vmatrix} \bar{e}_1 & \bar{e}_2 & \bar{e}_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ F_1 & F_2 & F_3 \end{vmatrix} =$$

$$\left(\left(\frac{\partial F_3}{\partial x_2} - \frac{\partial F_2}{\partial x_3} \right), \left(\frac{\partial F_1}{\partial x_3} - \frac{\partial F_3}{\partial x_1} \right), \left(\frac{\partial F_2}{\partial x_1} - \frac{\partial F_1}{\partial x_2} \right) \right)$$

Curl in index notation

$$(\nabla \times \bar{F})_i = \epsilon_{ijk} \frac{\partial F_k}{\partial x_j}$$

The alternating unit tensor (Levi-Civita tensor)

$$\epsilon_{ijk} = \begin{cases} 0, & \text{if any two indices are the same} \\ 1, & \text{ijk an even permutation of 1,2,3} \\ -1, & \text{ijk an odd permutation of 1,2,3} \end{cases}$$

Useful identities involving the Kronecker and alternating tensors

$$\delta_{ij} \varepsilon_{ijk} = 0$$

$$\varepsilon_{ipq} \varepsilon_{jpq} = 2\delta_{ij}$$

$$\varepsilon_{ijk} \varepsilon_{ijk} = 6$$

$$\varepsilon_{ijk} \varepsilon_{pqk} = \delta_{ip} \delta_{jq} - \delta_{iq} \delta_{jp}$$

Some useful vector identities.

$$\nabla (\psi\phi) = \psi\nabla\phi + \phi\nabla\psi$$

$$\nabla \cdot (\phi\bar{U}) = \phi\nabla \cdot \bar{U} + \bar{U} \cdot \nabla\phi$$

$$\nabla \times (\phi\bar{U}) = \phi\nabla \times \bar{U} + \nabla\phi \times \bar{U}$$

$$\nabla (\bar{U} \cdot \bar{V}) = (\bar{U} \cdot \nabla) \bar{V} + (\bar{V} \cdot \nabla) \bar{U} + \bar{U} \times (\nabla \times \bar{V}) + \bar{V} \times (\nabla \times \bar{U})$$

$$\nabla \cdot (\bar{U} \times \bar{V}) = \bar{V} \cdot (\nabla \times \bar{U}) - \bar{U} \cdot (\nabla \times \bar{V})$$

$$\nabla \times (\bar{U} \times \bar{V}) = \bar{U} (\nabla \cdot \bar{V}) + (\bar{V} \cdot \nabla) \bar{U} - \bar{V} (\nabla \cdot \bar{U}) - (\bar{U} \cdot \nabla) \bar{V}$$

Some more vector identities - this time involving second derivatives.

$$\nabla \cdot (\nabla F) = \nabla^2 F$$

$$\nabla \cdot (\nabla \bar{F}) = \nabla^2 \bar{F}$$

$$\nabla \cdot (\nabla \times \bar{F}) = 0$$

$$\nabla \times (\nabla \times \bar{F}) = \nabla(\nabla \cdot \bar{F}) - \nabla^2 \bar{F}$$

Show that $\nabla \times (\nabla \times \bar{F}) = \nabla(\nabla \cdot \bar{F}) - \nabla^2 \bar{F}$

Let $A_k = \epsilon_{kpq} \frac{\partial F_q}{\partial x_p}$ $B_i = \epsilon_{ijk} \frac{\partial A_k}{\partial x_j}$

$$\nabla \times (\nabla \times F)|_i = B_i = \epsilon_{ijk} \frac{\partial A_k}{\partial x_j} = \epsilon_{ijk} \epsilon_{kpq} \frac{\partial^2 F_q}{\partial x_j \partial x_p}$$

Use the identity $\epsilon_{ijk} \epsilon_{pqk} = \delta_{ip} \delta_{jq} - \delta_{iq} \delta_{jp}$

Which is the same as $\epsilon_{ijk} \epsilon_{kpq} = \delta_{ip} \delta_{jq} - \delta_{iq} \delta_{jp}$

$$\nabla \times (\nabla \times F)|_i = \delta_{ip} \delta_{jq} \frac{\partial^2 F_q}{\partial x_j \partial x_p} - \delta_{iq} \delta_{jp} \frac{\partial^2 F_q}{\partial x_j \partial x_p}$$

$$\nabla \times (\nabla \times F)|_i = \frac{\partial^2 F_j}{\partial x_j \partial x_i} - \frac{\partial^2 F_i}{\partial x_j \partial x_j} = \frac{\partial}{\partial x_i} \left(\frac{\partial F_j}{\partial x_j} \right) - \frac{\partial^2 F_i}{\partial x_j \partial x_j} = (\nabla(\nabla \cdot \bar{F}) - \nabla^2 \bar{F})|_i$$

The Laplacian.

$$\nabla^2 = \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial x_3^2} = \frac{\partial^2}{\partial x_i \partial x_i}.$$

3.3 Gauss' theorem

This famous theorem in vector calculus can be used to convert a volume integral involving the gradient to a surface integral.

$$\int_V \nabla F \, dV = \int_A F \bar{n} \, dA$$

$$\int_V (\nabla \cdot \bar{F}) \, dV = \int_A \bar{F} \cdot \bar{n} \, dA$$

$$\int_V \frac{\partial F_{ij}}{\partial x_j} \, dV = \int_A F_{ij} n_j \, dA$$

The variable F can be a scalar, vector or tensor.

A volume integral involving the curl can be converted to a surface integral.

$$\int_V (\nabla \times \bar{F}) dV = \int_A \bar{n} \times \bar{F} dA$$

Recall the development of the continuity equation

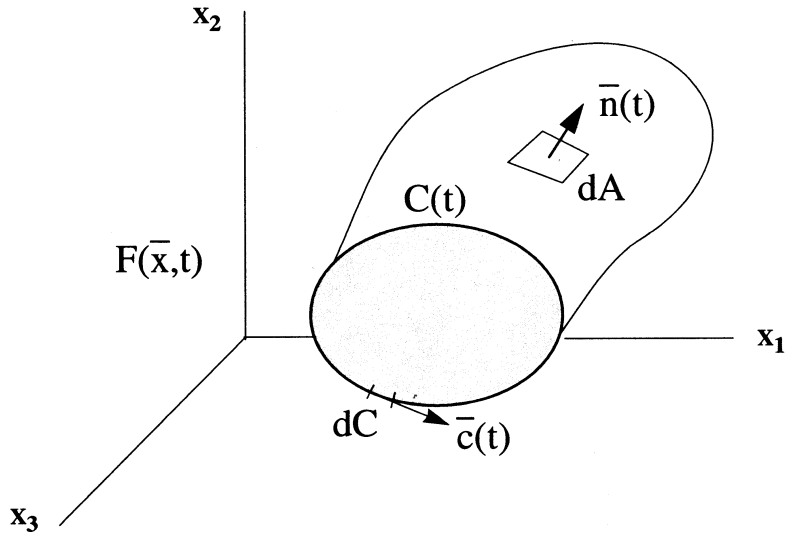
$$\Delta x \Delta y \Delta z \left(\frac{\partial \rho}{\partial t} \right) + \Delta y \Delta z (\rho U|_{x + \Delta x} - \rho U|_x) +$$

$$\Delta x \Delta z (\rho V|_{y + \Delta y} - \rho V|_y) + \Delta x \Delta y (\rho W|_{z + \Delta z} - \rho W|_z) = 0$$

$$\frac{\partial \rho}{\partial t} + \frac{\rho U|_{x + \Delta x} - \rho U|_x}{\Delta x} + \frac{\rho V|_{y + \Delta y} - \rho V|_y}{\Delta y} + \frac{\rho W|_{z + \Delta z} - \rho W|_z}{\Delta z} = 0$$

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho U}{\partial x} + \frac{\partial \rho V}{\partial y} + \frac{\partial \rho W}{\partial z} = 0$$

3.4 Stokes' theorem



$$\int_A (\nabla \times \bar{F}) \cdot \bar{n} dA = \oint_C \bar{F} \cdot \bar{c} dC$$

$$\int_A \epsilon_{ijk} \frac{\partial F_k}{\partial x_j} n_i dA = \oint_C F_k c_k dC$$

$$\int_A (\bar{n} \times \nabla F) dA = \oint_C F \bar{c} dC.$$

3.5 Problems

Problem 1 - Working in Cartesian coordinates and using index notation, prove each of the following the vector identities

$$\nabla \cdot (\rho \bar{F}) = \bar{F} \cdot \nabla \rho + \rho \nabla \cdot \bar{F} \quad (3.26)$$

$$\nabla \times (\nabla \times \bar{F}) = \nabla(\nabla \cdot \bar{F}) - \nabla^2 \bar{F} \quad (3.27)$$

$$\bar{F} \cdot \nabla \bar{F} = (\nabla \times \bar{F}) \times \bar{F} + \nabla \left(\frac{\bar{F} \cdot \bar{F}}{2} \right) \quad (3.28)$$

Problem 2 - Let \bar{e}_i , \bar{e}_j and \bar{e}_k be the unit vectors in a right hand orthogonal coordinate system. Show that

$$\varepsilon_{ijk} = \bar{e}_i \cdot (\bar{e}_j \times \bar{e}_k) \quad (3.29)$$

Problem 3 - Demonstrate Stokes' theorem by integration of the curl of some smooth vector field variable over a square boundary.

Problem 4 - Find a unit vector normal to each of the following surfaces.

i) $x + y + z = 2$

ii) $ax^2 + by^2 + cz^2 = 1$

iii) $xyz = 1$

Problem 5 - Show that the unit vector normal to the plane

$$ax + by + cz = d \quad (3.30)$$

has the components

$$\bar{n} = \left(\frac{a}{\sqrt{a^2 + b^2 + c^2}}, \frac{b}{\sqrt{a^2 + b^2 + c^2}}, \frac{c}{\sqrt{a^2 + b^2 + c^2}} \right) \quad (3.31)$$

Why doesn't \bar{n} depend on d ?

Problem 6 - Verify Gauss's theorem

$$\int_V (\nabla \cdot \bar{F}) dV = \int_A \bar{F} \cdot \bar{n} dA \quad (3.33)$$

in each of the following cases,

i) $\bar{F} = (x, y, z)$ and V is a cube of side b aligned with the x, y, z axes,

ii) $\bar{F} = \bar{n}_r r^2$ where \bar{n}_r is a unit vector in the radial direction, V is a sphere of radius b surrounding the origin and $r^2 = x^2 + y^2 + z^2$.

Problem 7 - Verify Stokes' theorem

$$\int_A (\nabla \times \bar{F}) \cdot \bar{n} dV = \oint_C \bar{F} \cdot \bar{c} dC \quad (3.34)$$

where $\bar{F} = (x, y, z)$ and A is the surface of a cube of side b aligned with the x, y, z axes. The open face of the cube has an outward normal aligned with the positive x -axis.