## Stress and Texture

## Strain

## CRYSTAL LATTICE

DIFFRACTION LINE

- Two types of stresses:
- microstresses - vary from one grain to another on a microscopic scale.
- macrostresses - stress is uniform over large distances.
- Usually:
- macrostrain is uniform produces peak shift
- microstrain is nonuniform produces peak broadening

$$
b=\Delta 2 \theta=-2 \frac{\Delta d}{d} \tan \theta
$$



UNIFORM STRAIN


## Applied and Residual Stress

- Plastic flow can also set up residual stress.



## Methods to Measure Residual Stress

X-ray diffraction.

- Nondestructive for the measurements near the surface: $\mathrm{t}<2 \mu \mathrm{~m}$.
- Neutron diffraction.
- Can be used to make measurements deeper in the material, but the minimum volume that can be examined is quite large (several $\mathrm{mm}^{3}$ ) due to the low intensity of most neutron beams.
- Dissection (mechanical relaxation).
- Destructive.


## General Principles

- Consider a rod of a cross-sectional area A stressed in tension by a force $F$.

Stress: $\quad \sigma_{y}=\frac{F}{A}, \sigma_{x}, \sigma_{z}=0$
Stress $\sigma_{y}$ produces strain $\varepsilon_{y}$ :

$$
\varepsilon_{y}=\frac{\Delta L}{L}=\frac{L_{f}-L_{0}}{L_{0}}
$$

$L_{0}$ and $L_{f}$ are the original and final lengths of the bar. The strain is related to stress as:

$$
\sigma_{y}=E \varepsilon_{y}
$$

$L$ increases $D$ decreases so:

$$
\varepsilon_{x}=\varepsilon_{z}=\frac{\Delta D}{D}=\frac{D_{f}-D_{0}}{D_{0}}
$$


$\varepsilon_{x}=\varepsilon_{z}=-v \varepsilon_{y} \quad$ for isotropic
$v$ - Poisson's ratio usually $0.25<v<0.45$

## General Principles

- This provides measurement of the strain in the $z$ direction since:

$$
\varepsilon_{z}=\frac{d_{n}-d_{0}}{d_{0}}
$$

Then the required stress will be:

$$
\sigma_{y}=-\frac{E}{v}\left(\frac{d_{n}-d_{0}}{d_{0}}\right)
$$

Diffraction techniques do not measure stresses in materials directly

- Changes in d-spacing are measured to give strain
- Changes in line width are measured to give microstrain
- The lattice planes of the individual grains in the material act as strain gauges



## General Principles



Vector diagram of plane spacings $d$ for a tensile stress $\sigma_{\phi}$

$$
\sigma_{y}=-\frac{E}{v}\left(\frac{d_{n}-d_{0}}{d_{0}}\right)
$$

we do not know $d_{0}$ !

## Elasticity

- In general there are stress components in two or three directions at right angles to one another, forming biaxial or triaxial stress systems.
- Stresses in a material can be related to the set of three principal stresses $\sigma_{1}$, $\sigma_{2}$ and $\sigma_{3}$.
- To properly describe the results of a diffraction stress measurement we introduce a coordinate systems for the instrument and the sample. These two coordinate systems are related by two rotation angles $\psi$ and $\phi$.
$\mathbf{L}_{\mathbf{i}}$ - laboratory coordinate system
$\mathbf{S}_{\mathbf{i}}$ - sample coordinate system

By convention the diffracting planes are normal to $\mathrm{L}_{3}$


## Elasticity

- In an anisotropic elastic material stress tensor $\sigma_{\mathrm{ij}}$ is related to the strain tensor $\varepsilon_{\mathrm{kl}}$ as:

$$
\sigma_{i j}=C_{i j k l} \varepsilon_{k l}
$$

where $\mathrm{C}_{\mathrm{ijkl}}$ is elastic constants matrix.
Similarly:

$$
\varepsilon_{i j}=S_{i j k l} \sigma_{k l}
$$

where $\mathrm{S}_{\mathrm{ijkl}}$ is elastic compliance matrix.
For isotropic compound:

$$
\varepsilon_{i j}=\frac{1+v}{E} \sigma_{i j}-\delta_{i j} \frac{v}{E} \sigma_{k k}
$$

where $\delta_{\mathrm{ij}}$ is Kroenecker's delta, " kk " indicates the summation $\sigma_{11}+\sigma_{22}+\sigma_{33}$

## Elasticity

- Or we can write it as:

$$
\begin{aligned}
& \varepsilon_{11}=\frac{1}{E}\left[\sigma_{11}-v\left(\sigma_{22}+\sigma_{33}\right)\right], \\
& \varepsilon_{22}=\frac{1}{E}\left[\sigma_{22}-v\left(\sigma_{11}+\sigma_{33}\right)\right], \\
& \varepsilon_{33}=\frac{1}{E}\left[\sigma_{33}-v\left(\sigma_{11}+\sigma_{22}\right)\right], \\
& \varepsilon_{23}=\frac{1}{2 \mu} \sigma_{23}, \\
& \varepsilon_{31}=\frac{1}{2 \mu} \sigma_{31}, \\
& \varepsilon_{12}=\frac{1}{2 \mu} \sigma_{12}
\end{aligned}
$$

## Elasticity

Lets relate $\varepsilon_{\mathrm{mn}}$ in one coordinate system to that in another system through transformation matrix:

$$
\varepsilon_{m n}^{L}=M_{m i}^{S L} M_{n j}^{S L} \varepsilon_{i j}^{S}
$$

The transformation matrix is:

$$
M^{S L}=\left[\begin{array}{ccc}
\cos \phi \cos \psi & -\sin \phi & \cos \phi \sin \psi \\
\sin \phi \cos \psi & \cos \phi & \sin \phi \sin \psi \\
-\sin \psi & 0 & \cos \psi
\end{array}\right]
$$

so that we find

$$
\begin{aligned}
\left(\varepsilon_{33}^{L}\right)_{\phi \psi} & =M_{3 i}^{S L} M_{3 j}^{S L} \varepsilon_{i j}^{S} \\
& =\varepsilon_{11}^{S} \cos ^{2} \phi \sin ^{2} \psi+\varepsilon_{12}^{S} \sin 2 \phi \sin ^{2} \psi \\
& +\varepsilon_{22}^{S} \sin ^{2} \phi \sin ^{2} \psi+\varepsilon_{33}^{S} \cos ^{2} \psi \\
& +\varepsilon_{13}^{S} \cos \phi \sin 2 \psi+\varepsilon_{23}^{S} \sin \phi \sin 2 \psi
\end{aligned}
$$

## Elasticity

- In terms of stresses:

$$
\begin{aligned}
\left(\varepsilon_{33}^{L}\right)_{\phi \psi} & =\frac{1+v}{E}\left\{\sigma_{11}^{S} \cos ^{2} \phi+\sigma_{12}^{S} \sin 2 \phi+\sigma_{22}^{S} \sin ^{2} \phi-\sigma_{33}^{S}\right\} \sin ^{2} \psi+\frac{1+v}{E} \sigma_{33}^{S} \\
& -\frac{v}{E}\left(\sigma_{11}^{S}+\sigma_{22}^{S}+\sigma_{33}^{S}\right)+\frac{1+v}{E}\left\{\sigma_{13}^{S} \cos \phi+\sigma_{23}^{S} \sin \phi\right\} \sin 2 \psi \\
& =\frac{d_{\phi \psi}-d_{0}}{d_{0}}
\end{aligned}
$$

## Biaxial and Triaxial Stress Analysis

- Biaxial stress tensor is in the form:

$$
\left[\begin{array}{ccc}
\sigma_{11} & 0 & 0 \\
0 & \sigma_{22} & 0 \\
0 & 0 & 0
\end{array}\right]
$$

since stress normal to a free surface must be zero: $\quad \sigma_{i j} \mathbf{n}_{j}=0$
For our tensor lets define:

$$
\sigma_{\phi}^{S}=\sigma_{11}^{S} \cos ^{2} \phi+\sigma_{22}^{S} \sin ^{2} \phi
$$

Then the equation for strain becomes:

$$
\varepsilon_{\psi \phi}^{L}=\frac{d_{\phi \psi}-d_{0}}{d_{0}}=\frac{1+v}{E} \sigma_{\phi}^{S} \sin ^{2} \psi-\frac{v}{E}\left(\sigma_{11}^{S}+\sigma_{22}^{S}\right)
$$

## The $\sin ^{2} \psi$ Method

Stress $\sigma_{33}$ is zero, but strain $\varepsilon_{33}$ is not zero. It has finite value given by the Poisson contractions due to $\sigma_{11}$ and $\sigma_{22}$ :

$$
\varepsilon_{33}^{S}=-v\left(\varepsilon_{11}^{S}+\varepsilon_{22}^{S}\right)=-\frac{v}{E}\left(\sigma_{11}^{S}+\sigma_{22}^{S}\right)
$$

Then strain equation can be written as:

$$
\begin{aligned}
\varepsilon_{\phi \psi}^{L}-\varepsilon_{33}^{S} & =\frac{(1+v) \sigma_{\phi}^{S}}{E} \sin ^{2} \psi \\
\varepsilon_{\phi \psi}^{L}-\varepsilon_{33}^{S} & =\frac{d_{\phi \psi}-d_{0}}{d_{0}}-\frac{d_{n}-d_{0}}{d_{0}} \\
& =\frac{d_{\phi \psi}-d_{n}}{d_{0}}=\frac{(1+v) \sigma_{\phi}^{S}}{E} \sin ^{2} \psi
\end{aligned}
$$

## The $\sin ^{2} \psi$ Method

- We make ingenious approximation (by Glocker et al. in 1936):
- $\mathrm{d}_{\mathrm{n}}, \mathrm{d}_{\mathrm{i}}$ and $\mathrm{d}_{0}$ are very nearly equal to one another,
- $\left(d_{i}-d_{n}\right)$ is small compared to $d_{0}$,
- unknown $\mathrm{d}_{0}$ is replaced by $\mathrm{d}_{\mathrm{i}}$ or $\mathrm{d}_{\mathrm{n}}$ with negligible error.

$$
\begin{gathered}
\frac{d_{\phi \psi}-d_{n}}{d_{n}}=\frac{(1+v) \sigma_{\phi}}{E} \sin ^{2} \psi \\
\sigma_{\phi}=\frac{E}{(1+v) \sin ^{2} \psi}\left(\frac{d_{\phi \psi}-d_{n}}{d_{n}}\right)
\end{gathered}
$$

- The stress in a surface can be determined by measuring the $d$-spacing as a function of the angle $\psi$ between the surface normal and the diffracting plane normal
- Measurements are made in the back-reflection regime $\left(2 \theta \rightarrow 180^{\circ}\right)$ to obtain maximum accuracy


## The $\sin ^{2} \psi$ Method



Vector diagram of plane spacings $d$ for a tensile stress $\sigma_{\phi}$

$$
\frac{d_{\phi \phi}-d_{n}}{d_{n}}=\frac{(1+v) \sigma_{\phi}}{E} \sin ^{2} \psi
$$




Measurement of $d_{i}$

## The $\sin ^{2} \psi$ Method

- Lets assume that stresses in zx plane are equal. This is referred to as an equal-biaxial stress state. We can write sample frame stress as:

$$
\left[\begin{array}{lll}
\sigma & 0 & 0 \\
0 & \sigma & 0 \\
0 & 0 & 0
\end{array}\right]
$$

No stress dependence on $\phi$

$$
\frac{d_{\psi}-d_{n}}{d_{n}}=\frac{(1+v) \sigma}{E} \sin ^{2} \psi
$$



Biaxial or uniaxial stress


Triaxial stresses present


Texture present

## The $\sin ^{2} \psi$ Method

$$
d_{\psi}=\frac{(1+v) \sigma}{E} d_{n} \sin ^{2} \psi+d_{n}
$$

Slope of the plot is:

$$
\frac{\partial d_{\psi}}{\partial \sin ^{2} \psi}=\frac{(1+v)}{E} \sigma d_{n}
$$

Generally $v$ and $E$ are well-known constants


Linear dependence of $d$ (311) upon $\operatorname{Sin}^{2} \psi$ for shot peened 5056-0 aluminum.

## Diffractometer Method

$$
\frac{D}{R}=\frac{\sin (\theta-\psi)}{\sin (\theta-\psi)}
$$

focusing circle

(a) $\psi=0$
(b) $\psi=\psi$

## Diffractometer Method

- The effect of sample or $\psi$-axis displacement can be minimized if a parallel beam geometry is used instead of focused beam geometry.



## Measurement of Line Position

- Sample must remain on the diffractometer axis as $\psi$ is changed (even if the sample is large)
- Radial motion of the detector to achieve focussing must not change the measured $2 \theta$
- L-P factor may vary significantly across a (broad) peak
- Absorption will vary when $\Psi \neq 0$
- Measurement of peak position often requires fitting the peak with a parabola:

$$
2 \theta_{0}=2 \theta_{1}+\frac{\Delta 2 \theta}{2}\left(\frac{3 a+b}{a+b}\right)
$$

$a=I_{2}-I_{1}$
$b=I_{2}-I_{3}$
$\Delta 2 \theta=2 \theta_{2}-2 \theta_{1}=2 \theta_{3}-2 \theta_{2}$


## Measurements of Stress in Thin Films

- Thin films are usually textured. No difficulty with moderate degree of preferred orientation.
- Sharp texture has the following effects:
- Diffraction line strong at $\psi=0$ and absent at $\psi=45^{\circ}$.
- If material anisotropic E will depend on direction in the specimen. Oscillations of $d$ vs $\sin ^{2} \psi$.


## Measurements of Stress in Thin Films

- In thin films we have a biaxial stress, so:

$$
\frac{d_{\phi \psi}-d_{n}}{d_{n}}=\frac{(1+v) \sigma_{\phi}}{E} \sin ^{2} \psi
$$

If we have equal-biaxial stress then it is even simpler:

$$
\frac{a_{\psi \psi}-a_{n}}{a_{n}}=\frac{d_{h k l}^{\psi}-d_{h k l}^{n}}{d_{h k l}^{n}}=\frac{(1+v) \sigma}{E} \sin ^{2} \psi
$$

We can calculate $\psi$ for any unit cell and any orientation. For cubic:

$$
\psi=a \cos \left(\frac{h_{\perp} h+k_{\perp} k+l_{\perp} l}{\sqrt{\left(h_{\perp}^{2}+k_{\perp}^{2}+l_{\perp}^{2}\right)\left(h^{2}+k^{2}+l^{2}\right)}}\right)
$$

Symbols $h_{\perp}, k_{\perp}$ and $l_{\perp}$ define (hkl) - oriented film

## Texture Analysis

The determination of the lattice preferred orientation of the crystallites in a polycrystalline aggregate is referred to as texture analysis.

- The term texture is used as a broad synonym for preferred crystallographic orientation in a polycrystalline material, normally a single phase.
- The preferred orientation is usually described in terms of pole figures.



## The Pole Figures

- Let us consider the plane ( h k I) in a given crystallite in a sample. The direction of the plane normal is projected onto the sphere around the crystallite.
- The point where the plane normal intersects the sphere is defined by two angles: pole distance $\alpha$ and an azimuth $\beta$.
- The azimuth angle is measured counter clock wise from the point X .



## The Pole Figures

- Let us now assume that we project the plane normals for the plane (h k I) from all the crystallites irradiated in the sample onto the sphere.
- Each plane normal intercepting the sphere represents a point on the sphere. These points in return represent the Poles for the planes ( hkl ) in the crystallites. The number of points per unit area of the sphere represents the pole density.


Random orientation


Preferred orientation

## The Pole Figures



## The Stereographic Projection



As we look down to the earth


The stereographic projection

## The Stereographic Projection



## The Pole Figures



## The Pole Figures



## The Pole Figures

We now project the sphere with its pole density onto a plane. This projection is called a pole figure.

- A pole figure is scanned by measuring the diffraction intensity of a given reflection with constant $2 \theta$ at a large number of different angular orientations of a sample.
- A contour map of the intensity is then plotted as a function of the angular orientation of the specimen.
- The intensity of a given reflection is proportional to the number of hkl planes in reflecting condition.
- Hence, the pole figure gives the probability of finding a given (h k I) plane normal as a function of the specimen orientation.
- If the crystallites in the sample have random orientation the contour map will have uniform intensity contours.


## The Pole Figures



## The Pole Figures



## Texture Measurements

- Requires special sample holder which allows rotation of the specimen in its own plane about an axis normal to its surface, $\phi$, and about a horizontal axis, $\chi$.


Reflection


Transmission

## Schulz Reflection Method

- In the Bragg-Brentano geometry a divergent x-ray beam is focused on the detector.
- This no longer applies when the sample is tilted about $\chi$.


Advantage: rotation in around $\chi$ in the range $40^{\circ}<\chi<90^{\circ}$ does not require absorption correction.

## Field and Merchant Reflection Method

- The method is designed for a parallel incident beam.



## Defocusing Correction

- As sample is tilted in $\chi$, the beam spreads out on a surface.
- At high $\chi$ values not all the beam enters the detector.
- Need for defocusing correction.


Change in shape and orientation of the irradiated spot on a sample surface for different sample inclinations as a function of tilt angle $\alpha$ and Bragg angle 2 $\theta$. The incident beam is cylindrical.


Intensity correction for $x$-ray pole figure determination in reflection geometry. Selected reflections for quartz.

## Absorption Correction

Diffracted intensities must be corrected for change in absorption due to change in $\alpha$.

$$
d I_{D}=\frac{I_{0} a b}{\sin \gamma} e^{-\mu x(1 / \sin \gamma+1 / \sin \beta)} d x
$$

$a$ - volume fraction of a specimen containing particles having correct orientation for reflection of the incident beam. $b$ - fraction of the incident energy which is diffracted by unit volume
substitute

$$
\gamma=\theta+\left(90^{\circ}-\alpha\right), \beta=\theta-\left(90^{\circ}-\alpha\right)
$$



Integrate $0<x<\infty$

$$
I_{D}=\frac{I_{0} a b}{\mu\{1-[\cos (\alpha-\theta) / \cos (\alpha+\theta)]\}}
$$

We interested in the intensity at angle $\alpha$, relative to intensity at $\alpha=90^{\circ}$ :

$$
S=\frac{I_{D}(\alpha=\alpha)}{I_{D}\left(\alpha=90^{\circ}\right)}=1-\cot \alpha \cot \theta
$$

## Pole Figure Measurement

- Pole figure diffractometer consists of a four-axis single-crystal diffractometer.

Rotation axes:
$\theta, \omega, \chi$, and $\phi$


## Example: Rolled Copper



- Texture measurements were performed on Cu disk $\varnothing=22 \mathrm{~mm}, \mathrm{t}=0.8 \mathrm{~mm}$.
- Four pole figures (111), (200), (220) and (311) were collected using Schulz reflection method.
- Background intensities were measured next to diffraction peaks with offset $2 \theta= \pm 40$.
- Defocusing effects were corrected using two methods:
- measured texture free sample
- calculated (FWHM of the peaks at $\psi=0^{\circ}$ is required - obtained from $\theta-2 \theta$ scan.
- X'Pert Texture program was used for quantitative analysis.


## Example: Rolled Copper



- Measure $\theta-2 \theta$ scan in order to determine the reflections used for the pole figure measurements.
- Use FWHM of the peaks to calculate the defocusing curve.


## Example: Rolled Copper

## Background Correction

- Pole figure intensities include background.
- Correction for background radiation is performed by measuring the intensity vs. $\psi$-tilt next to the diffraction peak.



## Example: Rolled Copper

## Corrections

- Experimental pole figures are corrected for background intensities.
- Either experimental or theoretical defocusing correction curve is applied.


Measured and calculated defocusing corrections for $\mathrm{Cu}(220)$ pole figure

## Example: Rolled Copper

## Corrections



- 2D representation of $\mathrm{Cu}(220)$ pole figure as (a) measured and (b) corrected.
- The most noticeable effect is at higher $\psi$-tilt angles.


## Example: Rolled Copper

## Pole Figure Measurements

- Four pole figures have been measured.
- Symmetry of rolling process is obtained from the pole figures:
- pole figure is symmetrical around

- The symmetry is called orthorhombic sample symmetry.



## Example: Rolled Copper



## Inverse Pole Figures



## Inverse Pole Figures



## Engineering Cu surfaces for the electrocatalytic conversion of $\mathrm{CO}_{2}$



X-ray pole figures for:
(A) Cu on $\mathrm{Al}_{2} \mathrm{O}_{3}(0001) ; \mathrm{Cu}(200)$ intensities are shown.
(B) Cu on $\mathrm{Si}(100) ; \mathrm{Cu}(111)$ intensities are shown.
(C) Cu on $\mathrm{Si}(111) ; \mathrm{Cu}(111)$ intensities are shown.
(D) Inverse pole figure shows highest intensities for the (751) plane, indicating that Cu on $\mathrm{Si}(111)$ is predominantly oriented in the [517] direction out-of-plane.

## TaN Thin Film





## TaN Thin Film

- $\phi$-scan of TaN (202) and MgO (202) reflections.



## TaN Thin Film

- TEM reveals additional structure.


## TaN Thin Film

## XRD 002 pole figure of TaN film



## TaN Thin Film



## TaN Thin Film

- Atomic Force Microscopy images of TaN films prepared under different $\mathrm{N}_{2}$ partial pressure

$\mathrm{p}_{\mathrm{N}}=2 \mathrm{mTorr}$
$\mathrm{p}_{\mathrm{N}}=2.5 \mathrm{mTorr}$
$\mathrm{p}_{\mathrm{N}}=4 \mathrm{mTorr}$

