

E209A LECTURE 9

GOALS OF THIS LECTURE:

- to show how describing functions may be used in stability analysis of closed loop systems.

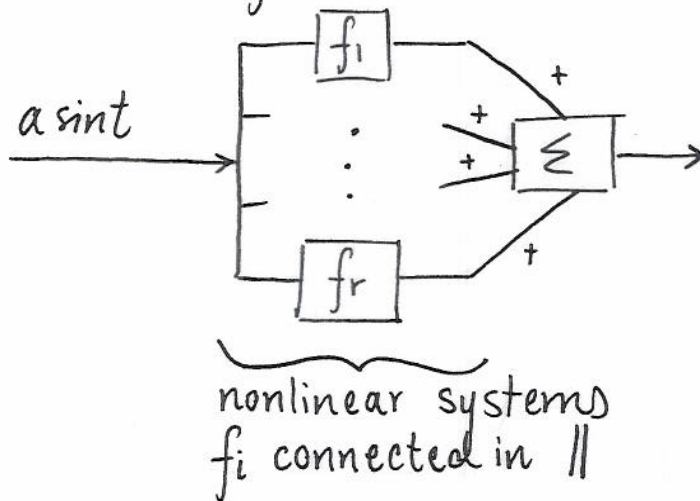
REFS

SASTRY § 4.1

KHALIL § 7.2

Using Describing Functions in Stability Studies

WARNING: block diagram manipulations for nonlinear systems.



first harmonic terms
from each f_i add to
give first harmonic
from f .

$$\Rightarrow N_f(a) = N_{f_1}(a) + N_{f_2}(a) + \dots + N_{f_r}(a)$$

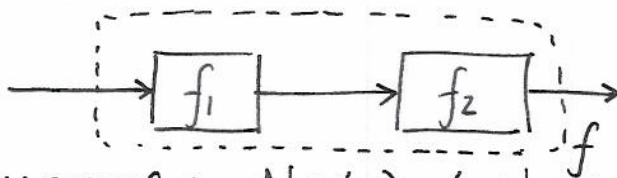
Application: if we can decompose a given f as

$$f(x) = \sum f_i(x)$$

for f_i having known N_{f_i} , then

$$N_f(a) = \sum N_{f_i}(a) \quad (\text{easy to find})$$

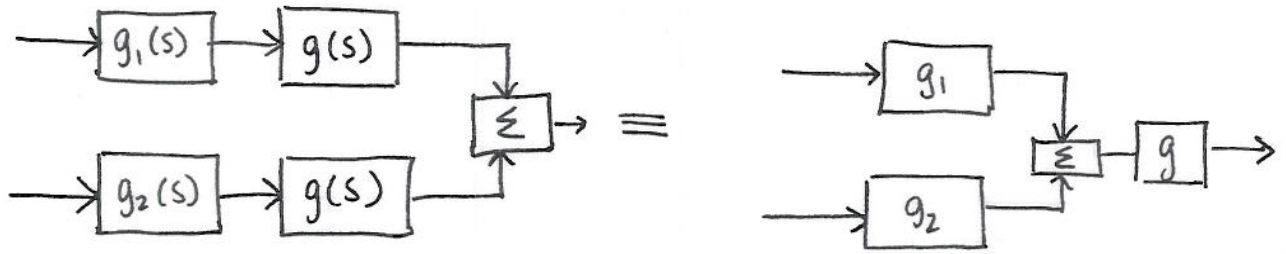
HOWEVER:



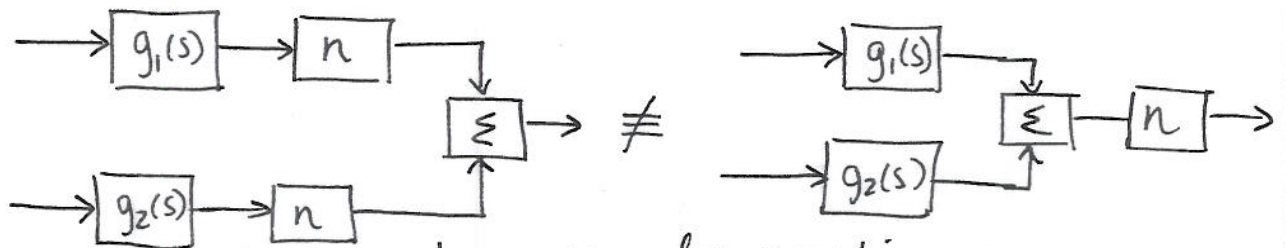
WARNING: $N_f(a) \neq N_{f_1}(a) \cdot N_{f_2}(a)$
 \uparrow in general

and similarly for several functions f_i in Series.

Also: for linear systems.



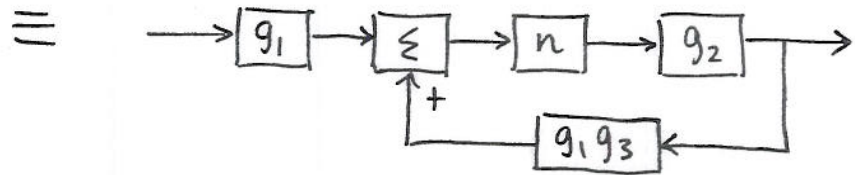
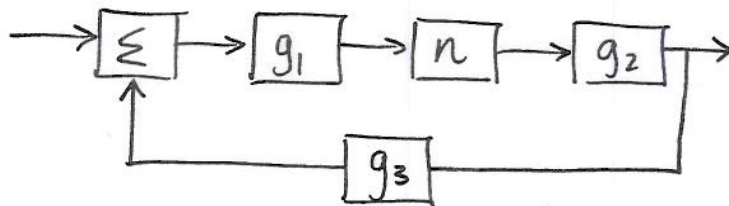
but for nonlinear systems



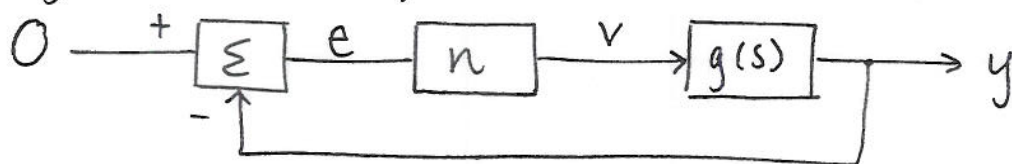
because, for nonlinear n , superposition is not valid.

For nonlinear systems, manipulations are OK iff inputs to nonlinearities remain unaltered.

eg.



Many nonlinear systems can be written as:



where n is a SVSS or DVSS function.

Concentrate on error e : \rightarrow since if we know what happens to e , we can determine what happens elsewhere in the system, easily.

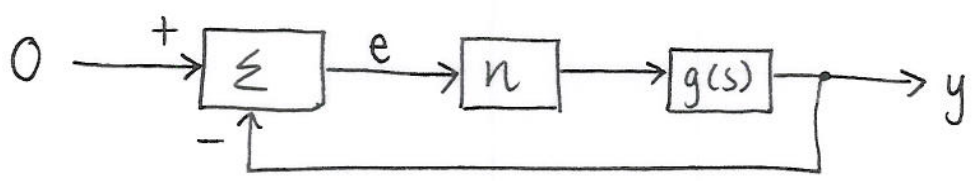
- will it oscillate?
- what amplitude?
- what ω ?

Assume $e \cong$ sustained sinusoidal oscillation

$\Rightarrow e(t) \cong a \sin(\omega t + \theta)$ for some $\underbrace{a, \omega, \theta}_{\text{to be estimated}}$

$$\begin{aligned} \text{Then } v(t) &= n(e(t)) \\ &\cong n(a \sin(\omega t + \theta)) \\ &= a |N(a)| \sin(\omega t + \theta + \phi(a)) \\ &\quad + \text{higher order terms} \end{aligned}$$

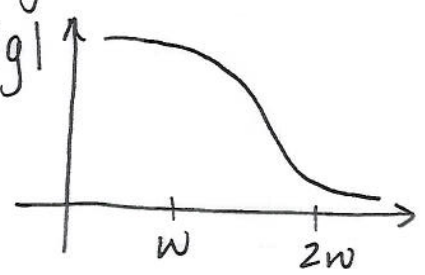
where $N(a)$ is the transfer function between the input to n and the 1st harmonic in the output of n , and $\phi(a)$ is the phase angle associated with $N(a)$.



$$e(t) \cong a \sin(\omega t + \theta)$$

$$v(t) \cong a |N(\omega)| \sin(\omega t + \theta + \phi(\omega)) + \text{higher harmonics.}$$

Assume: $g(s)$ attenuates higher harmonics, in that g looks like:



Then $y(t) \cong$ result of g operating on 1st harmonic in v

$$\cong |g(j\omega)| a |N(\omega)| \sin(\omega t + \theta + \phi(\omega) + \psi(\omega))$$

phase angle associated to $g(j\omega)$

So $e(t) = -y(t)$

$$\Rightarrow a \sin(\omega t + \theta) \cong -|g(j\omega)| a |N(\omega)| \sin(\omega t + \theta + \phi(\omega) + \psi(\omega))$$

↑
assume this is actually =

$$\therefore a \sin(\omega t + \theta) = -|g(j\omega)| a |N(\omega)| \sin(\omega t + \theta + \phi(\omega) + \psi(\omega))$$

In phaser form:

$$a e^{j(\omega t + \theta)} = -|g(j\omega)| a |N(\omega)| e^{j(\omega t + \theta + \phi(\omega) + \psi(\omega))}$$

$$= -a |g(j\omega)| e^{j\psi(\omega)} \cdot |N(\omega)| e^{j\phi(\omega)} e^{j(\omega t + \theta)}$$

i.e. $1 = \underbrace{-|g(j\omega)|}_{g(j\omega)} \cdot \underbrace{|N(a)|}_{N(a)} e^{j\psi(\omega)} \cdot e^{j\phi(a)}$

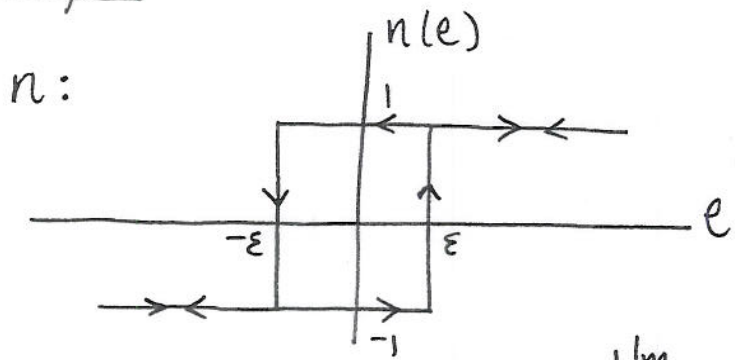
↑
harmonic balance equation

i.e. $g(j\omega) = -\frac{1}{N(a)}$ relationship between ω and a

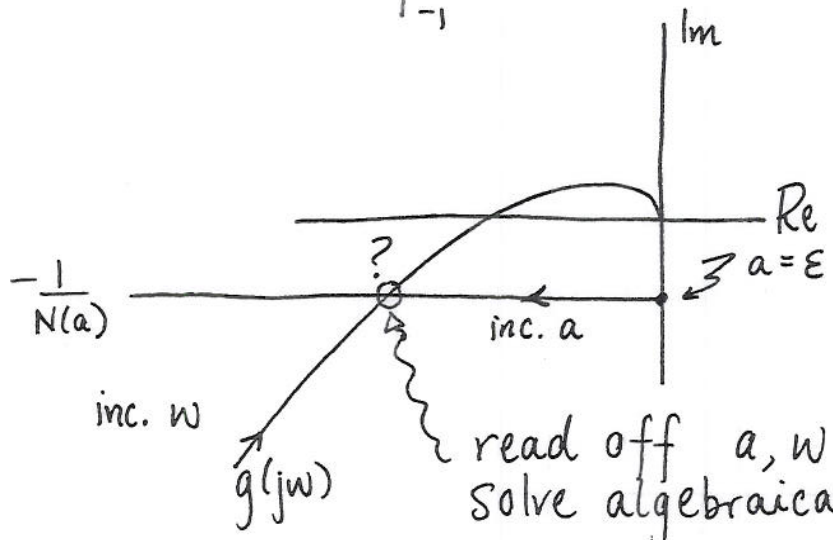
Assumptions made:

- $e(t) \cong a \sin(\omega t + \theta)$
- g attenuates higher frequencies
- describing function is exact.

example:



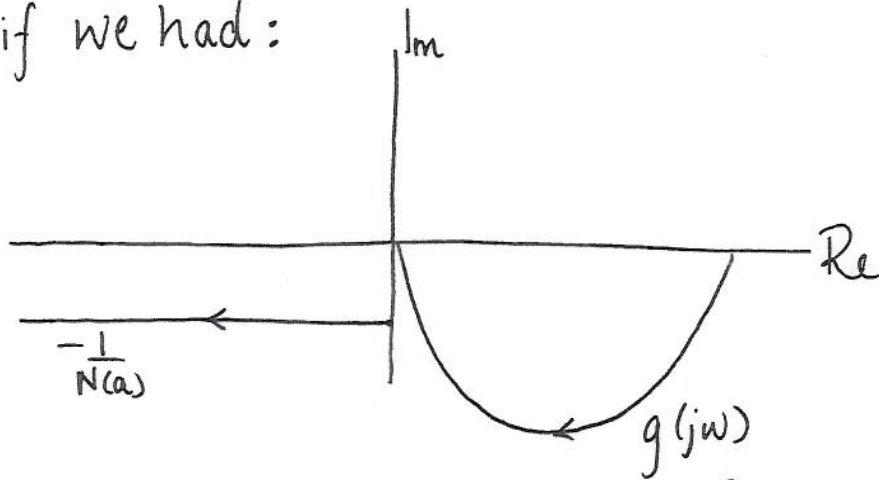
Assume:
 $g(s) = \frac{40}{s(s+2)(s+8)}$



Suggests: if intersection takes place, then oscillations may occur in e with the ω, a associated with the intersection point.

read off a, ω or solve algebraically

But if we had:



Then $g(j\omega) = -\frac{1}{N(a)}$ not true for any ω, a ,
 which suggests no oscillation (because if
 $e(t) \cong a \sin(\omega t + \theta)$ and assumptions all
 valid, then $g(j\omega) = -\frac{1}{N(a)}$ must be true
 for some ω, a .

NOTE: predictions not foolproof in that,
 owing to the approximations involved in
 the analysis:

- predicted oscillations might not happen
- predicted no-oscillations might be false

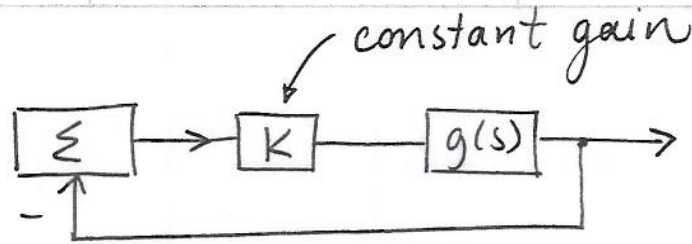
Nonetheless, this is often a useful tool.

Q: Can we predict whether oscillations will

- decay
- be sustained ?
- explode

A: Yes... using an extension of Nyquist.

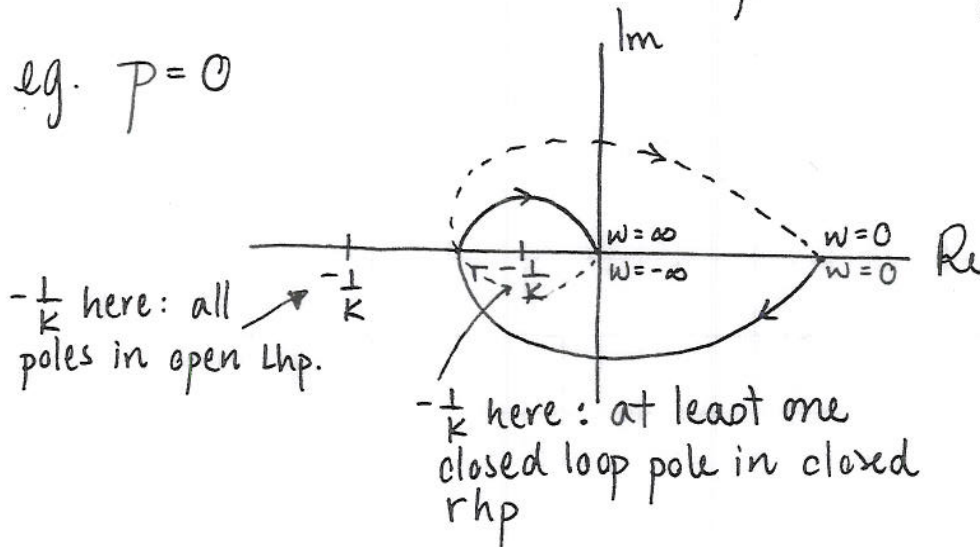
Nyquist :



Then: closed loop poles are in open left half plane iff complete $g(j\omega)$ -locus encircles $[-\frac{1}{K} + j0]$ P times (anticlockwise)

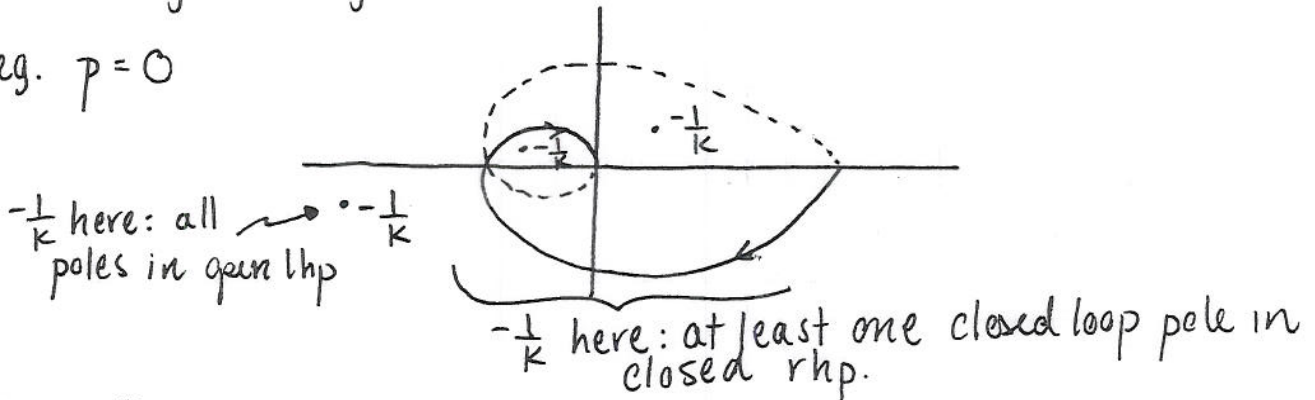
OL poles in open RHP

eg. $P=0$

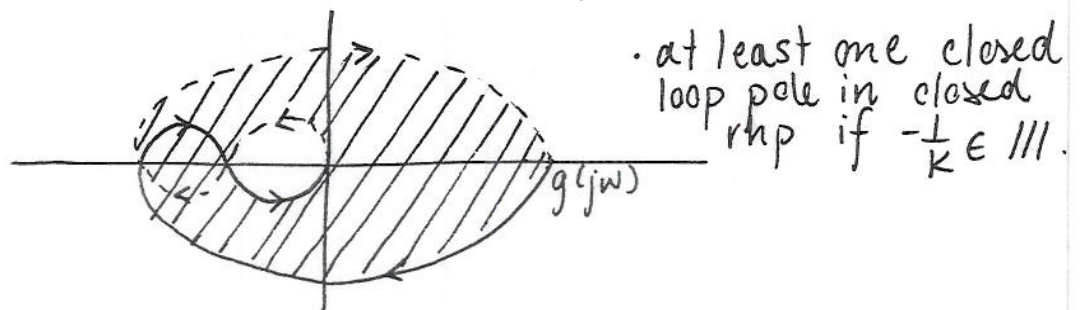


Actually, true for all $K \in \mathbb{C}$:

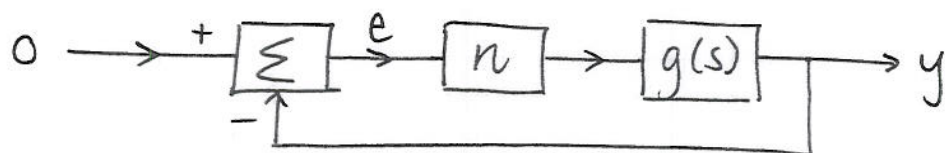
eg. $P=0$



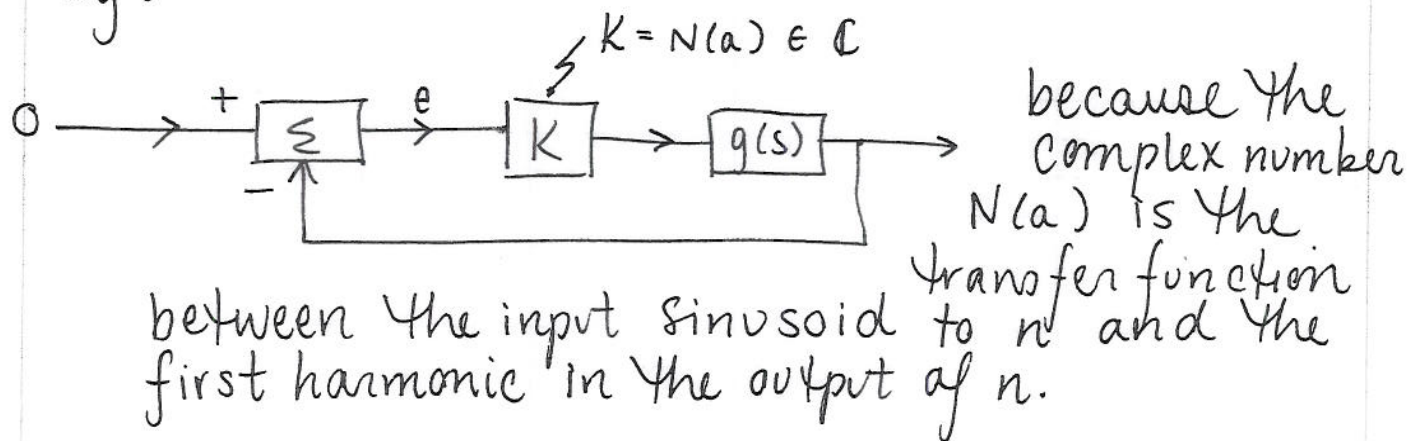
eg. $P=0$



Application to:

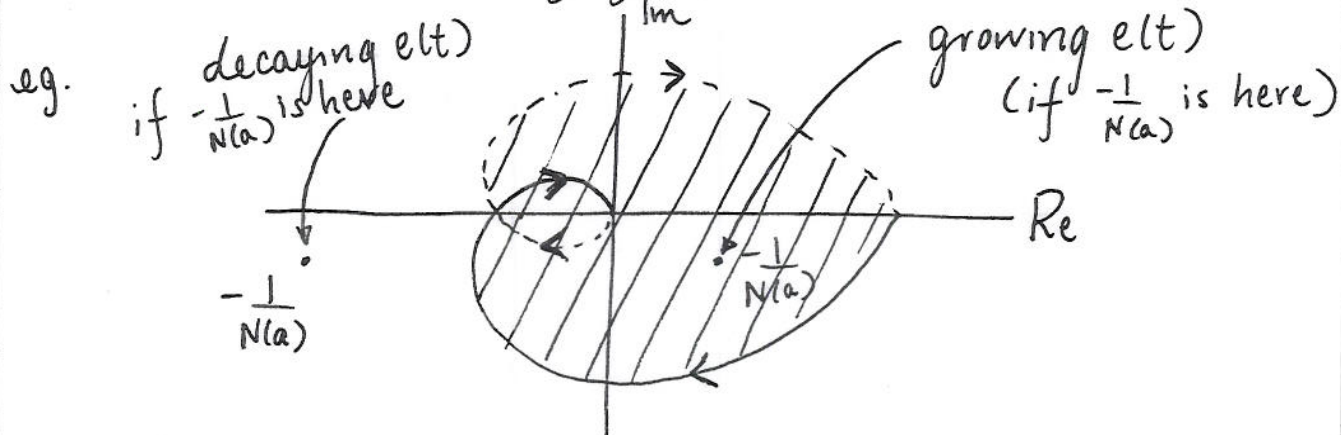


For $e(t) \approx a \sin(\omega t + \theta)$ view \nearrow as approximated by:

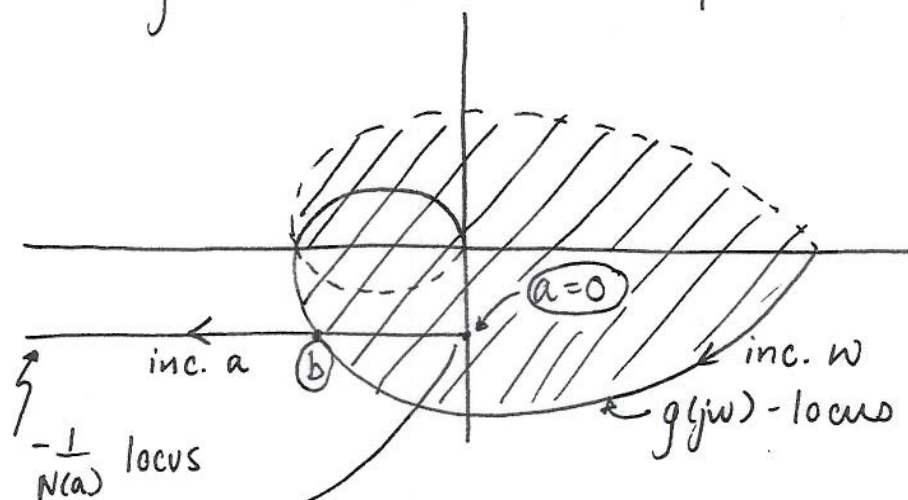


Also, assume $N(a)$ works for $e(t)$ of the form $a e^{\lambda t} \sin(\omega t + \theta)$ [as well as the case we just did - for $e(t)$ of the form $a \sin(\omega t + \theta)$]

Then, growth or decay of $e(t)$ is predictable from position of $-\frac{1}{K} = -\frac{1}{N(a)}$ with respect to $g(j\omega)$ -locus.



Hence can predict $e(t)$ behavior:
 eg. Say $e(0) = 0$ and $p = 0$



start here as $e(0) = 0$; corresponds to $a = 0$
 initially oscillation grows as $-\frac{1}{N(a)} \in \text{III}$
 $\approx \Rightarrow a$ increases

$\approx \Rightarrow -\frac{1}{N(a)}$ moved to b , but stops at b as
 $e(t)$ and hence a decreases on left of b #

$\approx \Rightarrow$ sustained oscillation with a, w values
 those at b .

$\approx \Rightarrow$ means "implied, more or less"

Since:

$-\frac{1}{N(a)} \in \text{III} \Rightarrow$ growing amplitude a of assumed sinusoid e

$-\frac{1}{N(a)} \in \text{unshaded area} \Rightarrow$ decaying amplitude a of
 assumed sinusoid e .

WARNING:

describing function analysis based on many approximations

⇒ predictions not necessarily correct

Can redo theory for:

$$e(t) = \sum_{i=1}^r \alpha_i \sin(\omega_i t + \theta_i)$$

↓
multiple-input describing functions

↓
for which, can be shown: if a closed loop oscillation exists, it can be predicted for some finite r ,

and for which:

error bounds can be obtained.