

Lecture 4

TODAY

SMALL TIP ANGLE SOLUTION AS A K-SPACE  
INTEGRAL

2D SPIRAL PULSE DESIGN

GRADIENTS

RF

NEXT

PRACTICAL ISSUES FOR 2D SPIRAL PULSES

## SMALL-TIP-ANGLE SOLUTION AS A K-SPACE INTEGRAL

### SMALL-TIP-ANGLE SOLUTION

$$\begin{aligned}M_{xy}(\underline{k}, \omega) &= i\mu_0 \int_{-\infty}^t \delta B_1(\tau) e^{i2\pi \underline{k}(\tau, \omega) \cdot \underline{r}} d\tau \\ &= i\mu_0 \int_{-\infty}^t \delta B_1(\tau) \int_{\underline{k}} \delta(\underline{k}\tau - \underline{k}) e^{i2\pi \underline{k} \cdot \underline{r}} d\underline{k} d\tau \\ &= i\mu_0 \int_{\underline{k}} \left[ \int_{-\infty}^t \delta B_1(\tau) \delta(\underline{k}\tau - \underline{k}) d\tau \right] e^{i2\pi \underline{k} \cdot \underline{r}} d\underline{k} \\ &= i\mu_0 \int_{\underline{k}} P(\underline{k}) e^{i2\pi \underline{k} \cdot \underline{r}} d\underline{k}\end{aligned}$$

THE MAGNETIZATION IS THE INVERSE TRANSFORM OF  $P(\underline{k})$   
WHAT IS  $P(\underline{k})$ ?

$$P(\underline{k}) = \int_{-\infty}^t \delta B_1(\tau) \delta(\underline{k}\tau - \underline{k}) d\tau$$

WE WANT THIS TO BE A UNIT DELTA, MULTIPLIED  
BY A WEIGHTING FUNCTION.

MULTIPLY AND DIVIDE BY  $|k'(r, \epsilon)|$  (t constant)

$$P(\underline{k}) = \int_{-\infty}^t \underbrace{\frac{\delta B_1(r)}{|k'(r, \epsilon)|}}_{W(\underline{k}(r, \epsilon))} \underbrace{\delta(\underline{k}(r, \epsilon) - \underline{k})}_{\text{UNIT DELTA}} |k'(r, \epsilon)| dr$$

IF WE ASSUME  $W(\underline{k})$  IS SINGLE VALUED

$$P(\underline{k}) = W(\underline{k}) \int_{-\infty}^t \underbrace{\delta(\underline{k}(r, \epsilon) - \underline{k}) |k'(r, \epsilon)| dr}_{S(\underline{k})}$$

$$= W(\underline{k}) S(\underline{k})$$

THEN

$$m_{xy}(r, \epsilon) = i m_0 \int_{\underline{k}} W(\underline{k}) S(\underline{k}) e^{i \underline{k} \cdot r} d\underline{k}$$

WHERE

$$W(\underline{k}(r, \epsilon)) = \frac{\delta B_1(r)}{|k'(r, \epsilon)|} \quad \begin{array}{l} \text{k-SPACE WEIGHTING} \\ \text{(APPROXIMATE,} \\ \text{VOXNOL BETTER)} \end{array}$$

$$S(\underline{k}) = \int_{-\infty}^t \delta(\underline{k}(r, \epsilon) - \underline{k}) |k'(r, \epsilon)| dr$$

k-SPACE SAMPLING  
(UNIFORM)

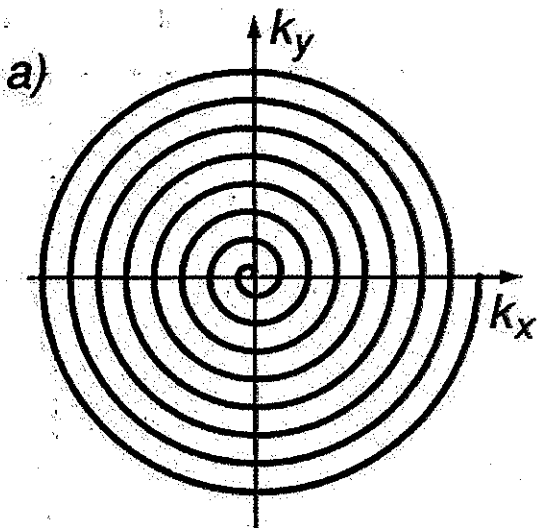
# 2D PULSE DESIGN

1) CHOOSE A K-SPACE TRAJECTORY THAT (APPROXIMATELY) UNIFORMLY COVERS K-SPACE

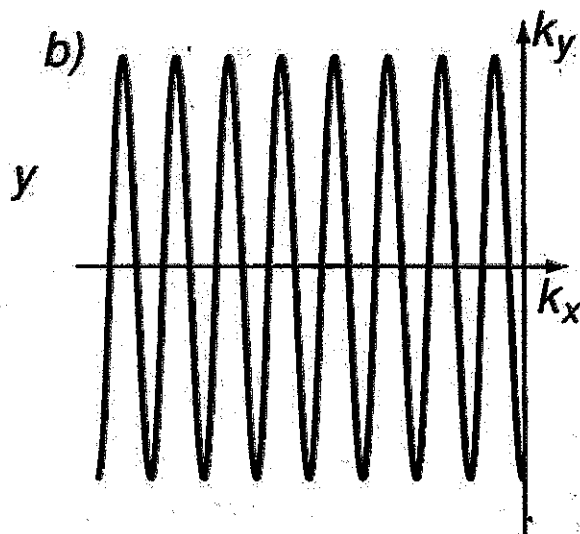
K-SPACE EXTENT  $\Rightarrow$  SPATIAL RESOLUTION

SAMPLING DENSITY  $\Rightarrow$  SPATIAL FOV

COMMON CHOICES



SPIRAL



EPI

SPIRAL COMMON FOR PENCIL BEAMS

EPI COMMON FOR SPECTRAL-SPATIAL PULSES

## 2) CHOOSE A WEIGHTING FUNCTION

THE INVERSE TRANSFORM OF WEIGHTING  
IS EXCITATION PROFILE

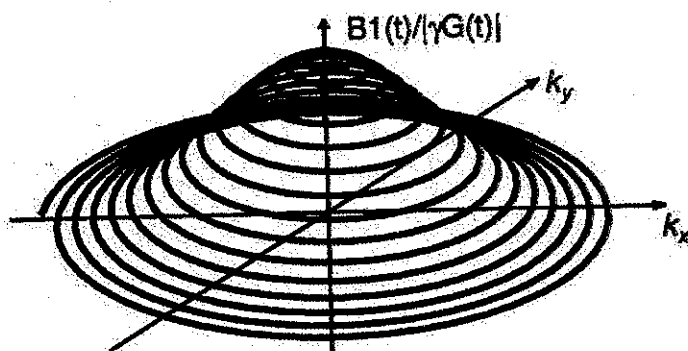
LOCALIZED EXCITATION

⇒ LOWPASS K-SPACE WEIGHTING

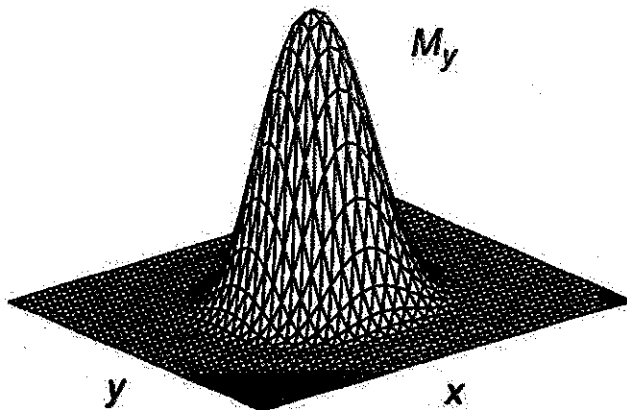
## 3) DESIGN THE RF

$$W(k(\tau, \epsilon)) = \frac{\delta B_1(\tau)}{|k'(\tau, \epsilon)|} = \frac{\delta B_1(\tau)}{|\delta G(\tau)|} = \frac{B_1(\tau)}{|G(\tau)|}$$

$$B_1(\tau) = |G(\tau)| W(k(\tau, \epsilon))$$



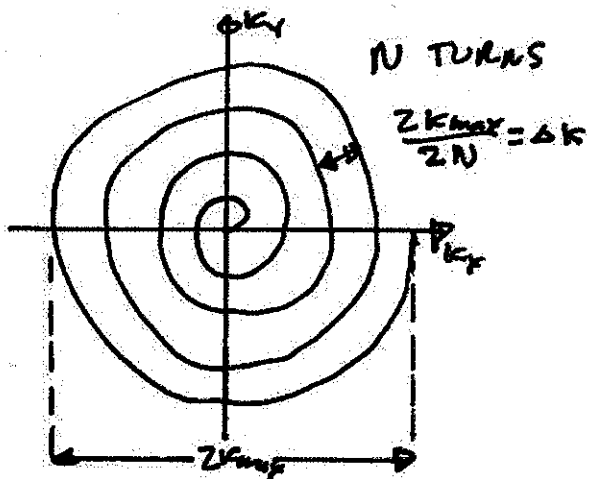
K-SPACE WEIGHTING



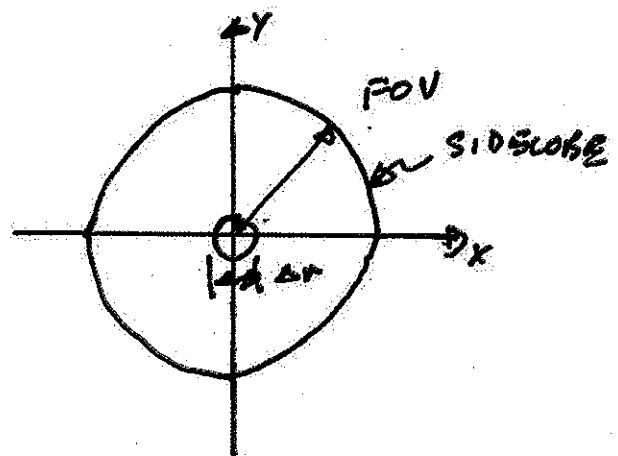
EXCITATION PROFILE

# 2D SPIRAL PULSE DESIGN

## k-SPACE TRAJECTORY DESIGN



k-SPACE



IMPULSE RESPONSE

TWO MAJOR CHOICES:

RESOLUTION  $\Delta r$

SMALLEST VOLUME

MINIMUM TRANSITION WIDTH

$$\Delta r = \frac{1}{z_{k_{max}}}$$

FOV

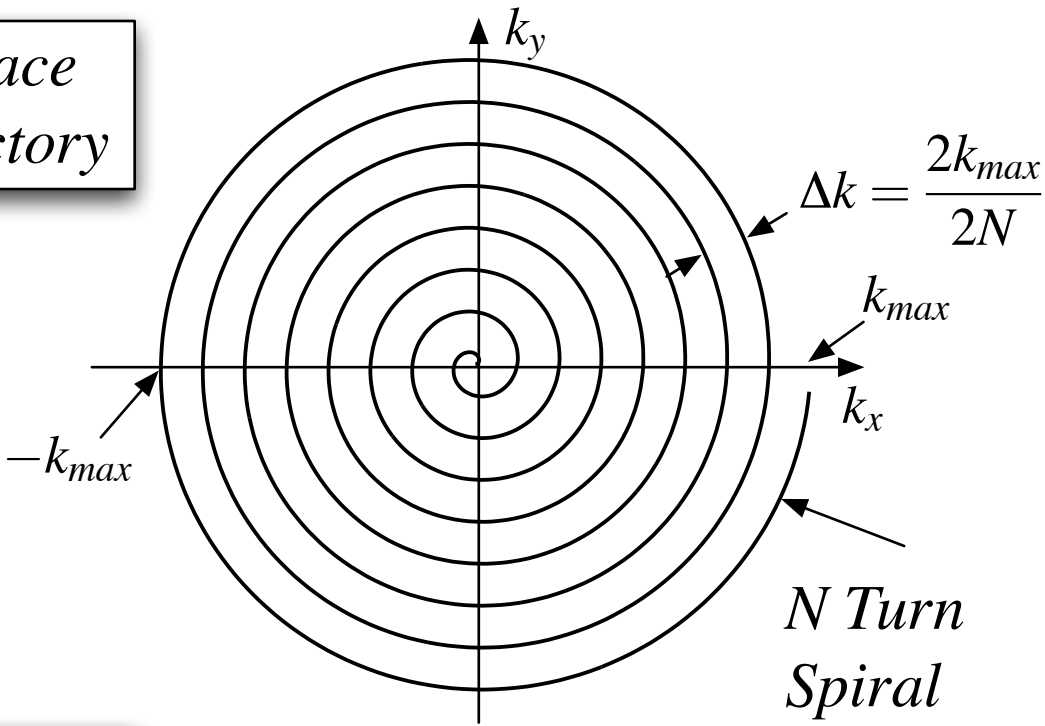
DISTANCE TO CENTER OF FIRST SIDELobe

$$FOV = \frac{1}{\Delta k} = \frac{zN}{z_{k_{max}}} = zN\Delta r$$

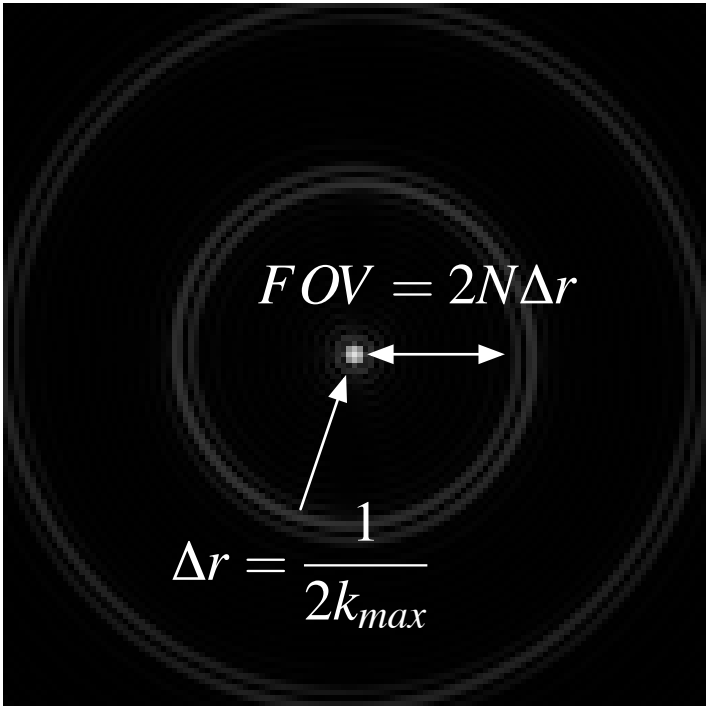
CHOOSING  $\Delta r$  DETERMINES  $k_{max}$

CHOOSING FOV DETERMINES N

*k*-Space  
Trajectory



Impulse  
Response



## ZD SPIRAL GRADIENT DESIGN

LIFT

$$k(t) = k_x(t) + i k_y(t)$$

(CONVENTIONAL  
 $k(t) = \frac{\lambda}{2\pi} \int_0^t G(s) ds$ )

CONSTANT ANGULAR RATE INWARD SPIRAL

$$k(t) = k_{\max} \left(1 - \frac{t}{T}\right) e^{i 2\pi N (1 - t/T)}$$

WHERE THE PULSE LENGTH IS  $T$ .

THE GRADIENT (COMPLEX,  $G = G_x(t) + i G_y(t)$ ) IS

$$k(t) = \frac{\lambda}{2\pi} \int_0^t G(s) ds \quad (\text{CYCLES/CM})$$

$$k'(t) = \frac{\lambda}{2\pi} G(t)$$

$$G(t) = \frac{2\pi}{\lambda} k'(t) \quad (G/\text{CM})$$

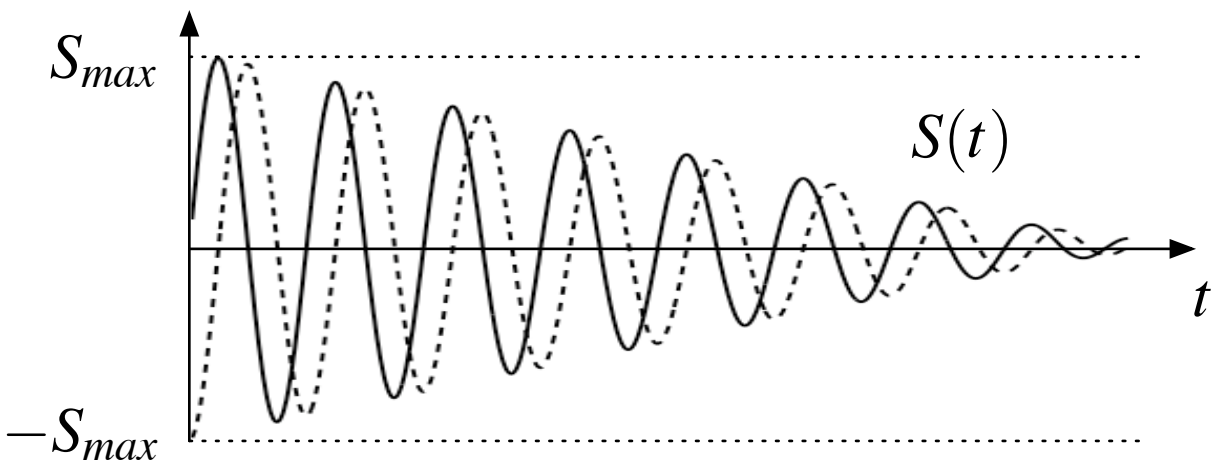
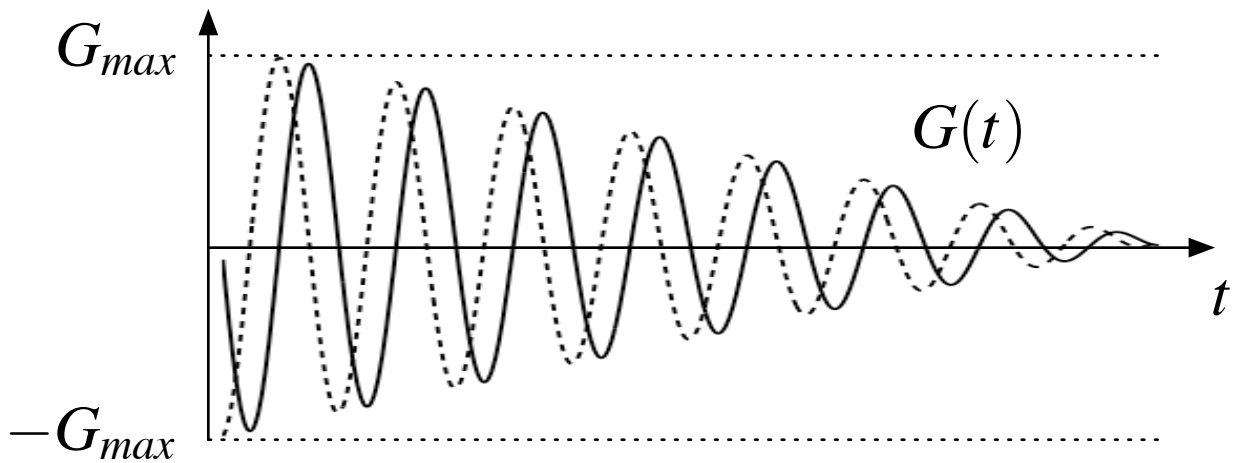
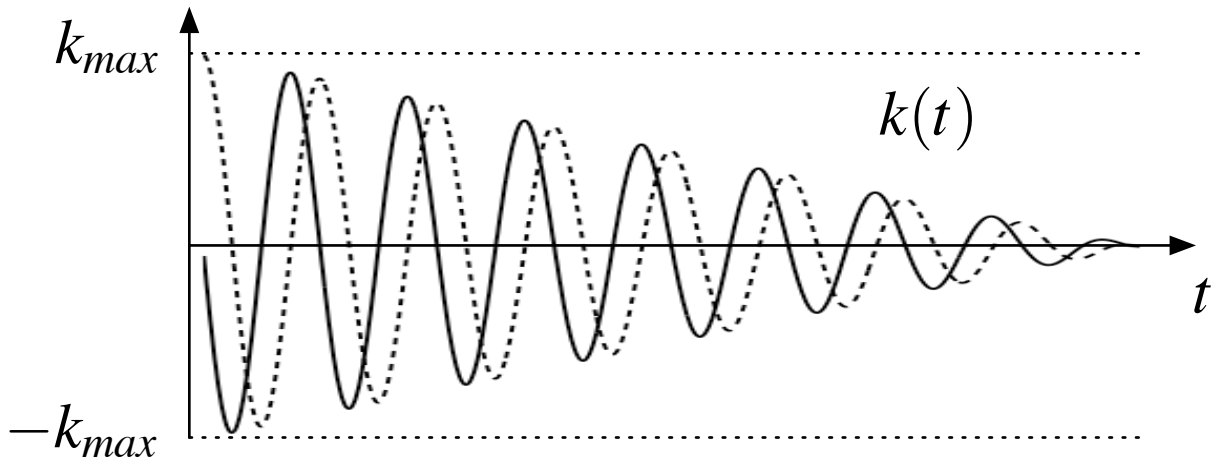
SLEW RATE

$$S(t) = G'(t)$$

$$= \frac{2\pi}{\lambda} k''(t)$$



# Constant Angular Rate Spiral



GRADIENT SYSTEM LIMITS ARE

$$|G(t)| \leq G_{\max}$$

$$|S(t)| \leq S_{\max}$$

CONSTANT ANGULAR RATE SPIRAL HITS  
THE LIMIT ONLY AT THE END

NOT EFFICIENT USE OF GRADIENT SYSTEM!

SOLUTION IS TO TRACE OUT TRAJECTORY  
AT A DIFFERENT RATE

$$K(r(t))$$

SPEED UP THE TRAJECTORY WHEN IT IS  
BELOW THE CONSTRAINT, SLOW IT  
DOWN WHEN IT IS OVER CONSTRAINT

$$G(t) = \frac{d}{dt} \left( \frac{z\dot{r}}{r} K(r(t)) \right) \leq G_{\max}$$

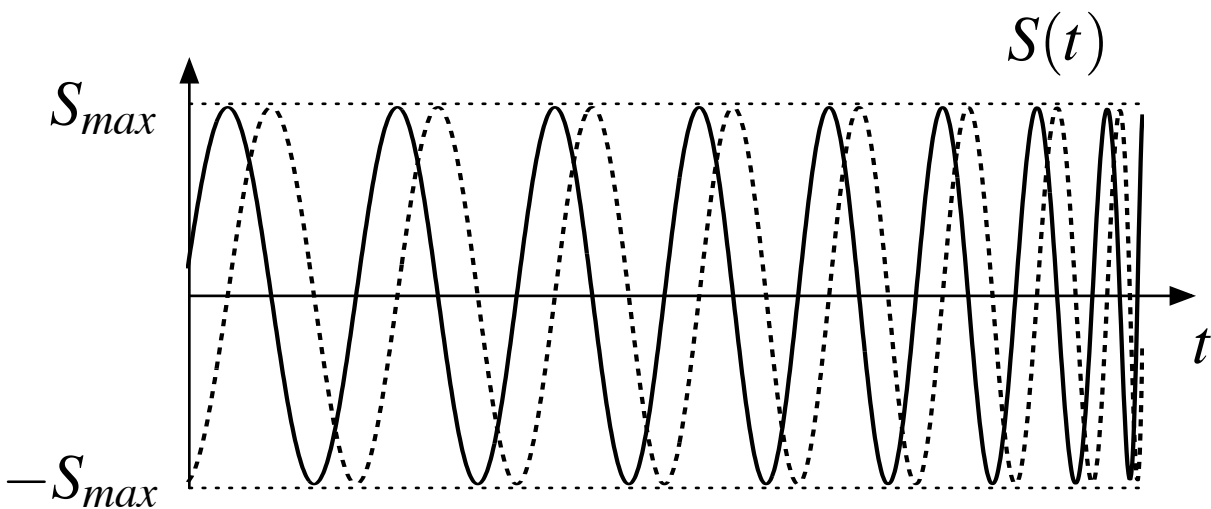
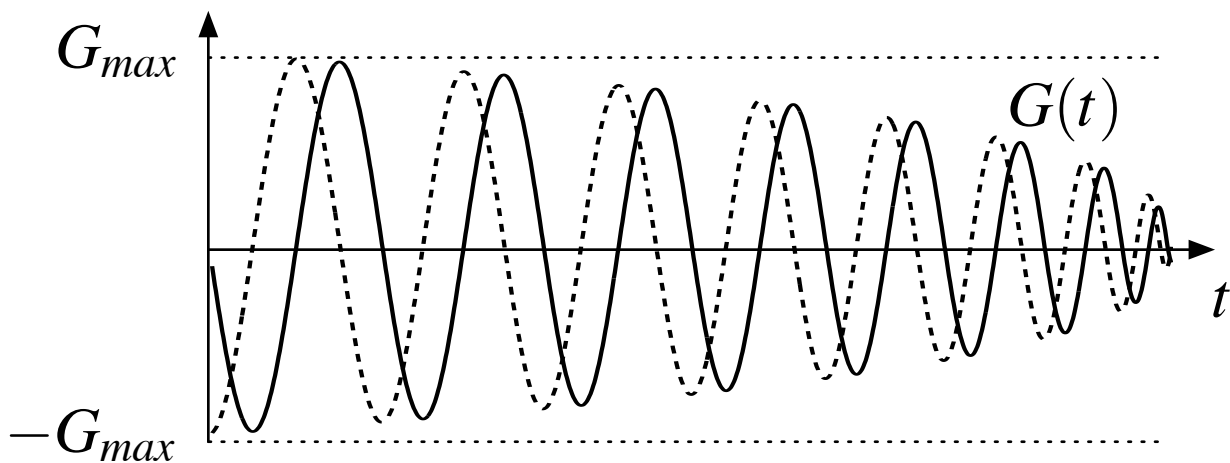
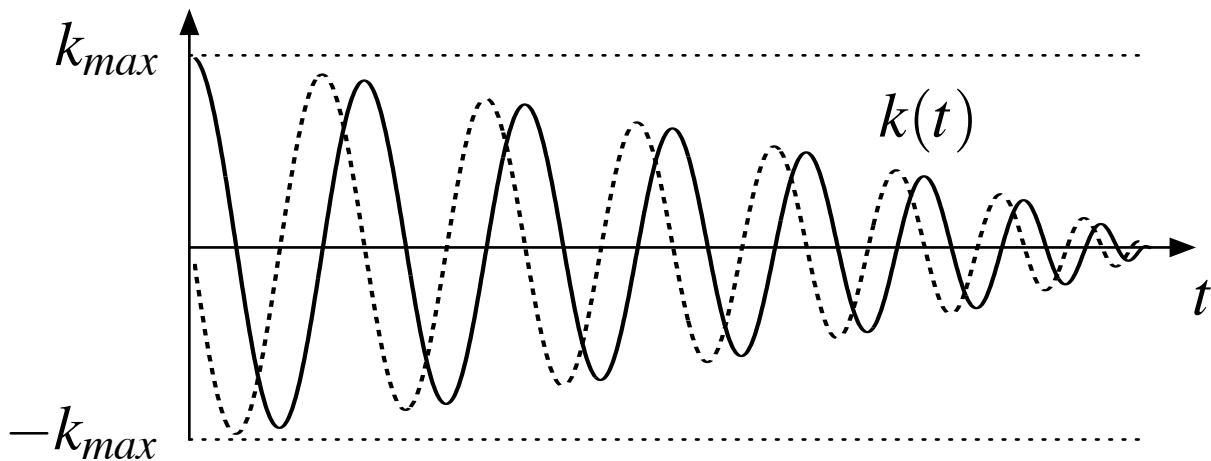
$$S(t) = \frac{d^2}{dt^2} \left( \frac{z\dot{r}}{r} K(r(t)) \right) \leq S_{\max}$$

THE MATLAB MFILE CSQ.M DOES THIS

$$K = \text{CSQ}(K_0, G_{\max}, S_{\max})$$

TYPICALLY  $1/\sqrt{2}$  SHORTER (CONSTANT SPEED RATE)

# Constant Slew Rate Spiral



## DESIGN $W(k)$

### UNIFORM k-SPACE WEIGHTING

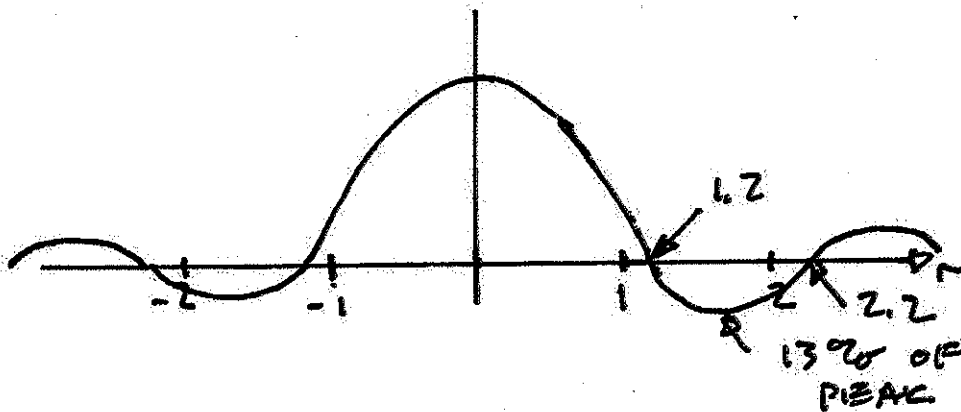
$$W(k) = \text{rect}\left(\frac{k}{2k_{\max}}\right)$$

RESOLUTION LIMIT

$$\begin{aligned} m_{\text{ny}}(\underline{r}) &= (2k_{\max})^2 \text{jinc}\left(2k_{\max}r\right) \\ &= \left(\frac{1}{\Delta r}\right)^2 \text{jinc}\left(\frac{r}{\Delta r}\right) \end{aligned}$$

WHERE

$$\text{jinc}(r) = \frac{J_1(\pi r)}{2r}$$



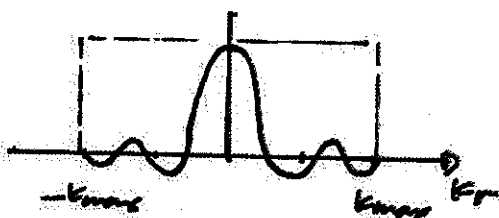
SLIGHTLY BROADER THAN SINC  
DECAYS FASTER  $\sim r^{-3/2}$

## TRUNCATED SINC WEIGHTING

$$W(k) = \text{sinc}\left(N \frac{k_r}{k_{max}}\right) \cdot \text{rect}\left(\frac{k_r}{2k_{max}}\right)$$

$$M_{xy}(r) \sim \text{rect}\left(\frac{2k_{max}}{2N} r\right) * \text{sinc}(2k_{max} r)$$

$$= \text{rect}\left(\frac{r}{2N\Delta r}\right) * \text{sinc}\left(\frac{r}{\Delta r}\right)$$



MINIMUM TRANSITION WIDTH

"SPACE - BANDWIDTH" IS (WIDTH IN SPACE)  
TIMES (WIDTH IN SPATIAL FREQUENCY)

FOR THIS CASE

$$\begin{aligned} \text{SBW} &= (2N\Delta r)(2k_{max}) = 2N\left(\frac{1}{2k_{max}}\right)2k_{max} \\ &= 2N \end{aligned}$$

SAME AS TIME BANDWIDTH, BUT DOESN'T  
FALL ON ZEROS OF  $\text{sinc}(\cdot)$

## WINDOWED SINC WEIGHTING

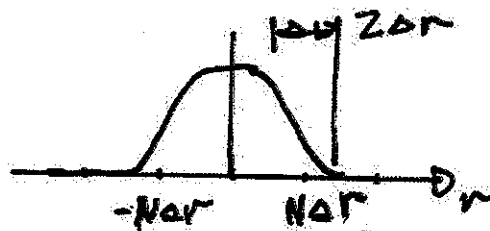
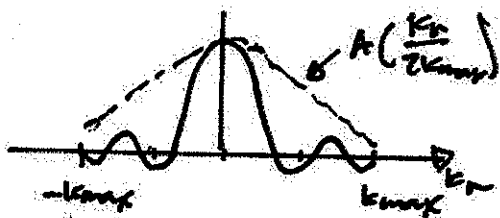
$$W(\underline{k}) = \text{jinc}\left(N \frac{k_r}{k_{max}}\right) \cdot A\left(\frac{k_r}{2k_{max}}\right)$$

WHERE  $A(\cdot)$  IS A WINDOW FUNCTION

CONVENTIONAL 1D WINDOWS WORK (HAMMING)  
BUT ARE NOT OPTIMAL

THEN

$$M_{xy}(\underline{r}) \sim \text{rect}\left(\frac{r}{2\Delta r}\right) * a\left(\frac{r}{\Delta r}\right)$$



DOUBLE TRANSITION WIDTH  
SMOOTHER RESPONSE

## CALCULATION OF THE RF WAVEFORM

GIVEN  $W(k)$  AND  $k(t)$

$$\begin{aligned} W(k(t)) &= \frac{\gamma B_1(t)}{|k'(t)|} = \frac{\gamma B_1(t)}{|\gamma G(t)|} \\ &= \frac{B_1(t)}{|G(t)|} \end{aligned}$$

SO

$$\underline{B_1(t) = |G(t)| W(k(t))}$$

THIS NEEDS TO BE SCALED FOR FLIP ANGLE.

NOTE THAT  $|k'(t)|^{-1}$  IS AN ESTIMATE OF  
THE DENSITY COMPENSATION FUNCTION  $d(t)$

GOOD IF TRAJECTORY IS GEOMETRICALLY  
UNIFORM

ADAPTABLE FOR SINGLE SHOT SPIRALS

NOT ADAPTABLE FOR INTERLEAVED SPIRALS