# What is Keke doing Now? Model Dog Behavior from Live Stream

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### Problem revisit

What we want to get out of the project?

- Is my dog active now?
- How long he/she sleeps everyday?
- When does him eat/drink?
- Is he/she in his play pan?

- ...

Sample rate: 1 frame per second

Motion scope: >= 20 seconds



€ 12

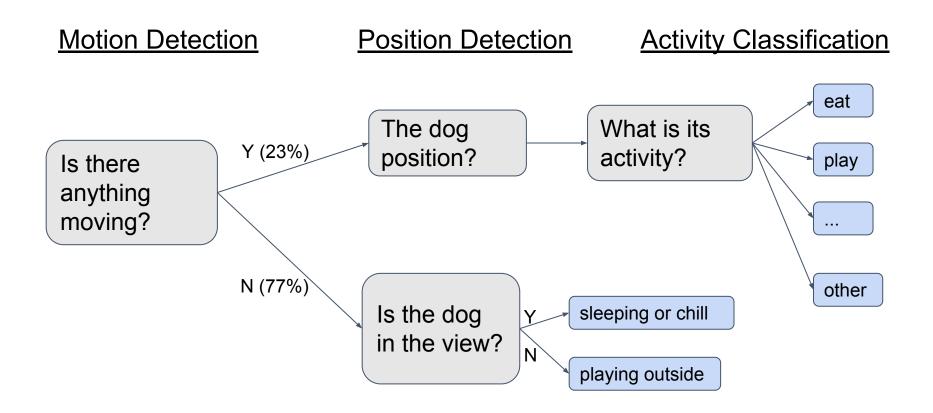
Hi, my name is Keke (科科 in Chinese, Kaká in French, ケケ in Japanese, Keke in Indonesian/Unicode, etc. ) -- I do support universal word embedding now.

I am a bug-free and active/online/several shots, general purpose intelligent system that moves around using 4 3-DOF(degree of freedom) brown/white legs (Aka. Shiba Inu Dog). I am originally from Arkansas and Hao flight with me for 5 hours to get back to my new home at Stanford. I am here to help Hao with his Ph.D. research in Al and Applied Research at Landing Al. I am very hands-on (or actually legs-on) and sometimes pull Hao too much to my direction. That been barked, Hao did an excellent job in the curriculum design -- we will see how the training goes.

Fun fact: I use a data structure of circle-dance as the counter for floors in the elevator, see the following:



# System Design



## Motion Detection - Problem

#### Difficulties:

- Fast changing light conditions
- Motion during sleep
- Fast computing (>15fps)

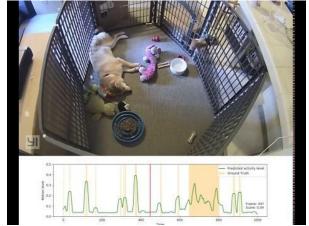
#### Algorithm:

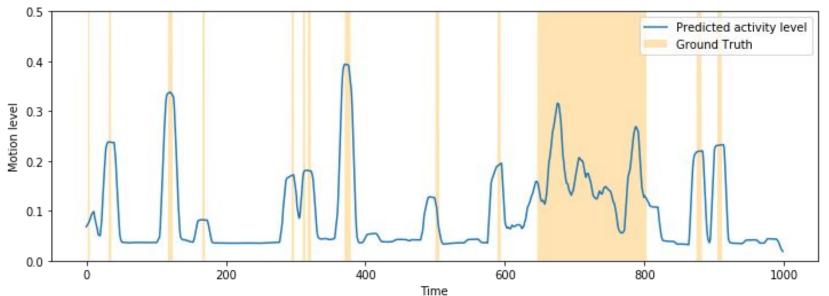
- Gaussian blur; Moving average; Gradient; Suppression
- Closing; Squared Sum; Moving average

## Motion Detection - Result

Speed: 164 frames/sec

Cross entropy score - 0.4459





# Position Detection I - Is dog in the view?





## Position Detection II - Where is the dog?

#### Steps:

- Two datasets based on mean
- Background subtraction:

```
Background[t] := m × Background[t-1] + (1 - m) × New[t]
```

- Binary erosion
- Centroid

#### Difficulty:

Light, accuracy

## **Position Detection**



Test Image from Dataset 1



Erosion



**Background Subtraction** 



Dog position

## **Position Detection**



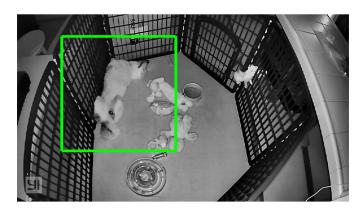
Test Image from Dataset 2



**Erosion** 



**Background Subtraction** 



**Dog Position** 

# **Activity Classification**

#### Eat:

- Edge detection
- Hough transform
- Difficulty: shadow

#### More activities

- Play
- ...

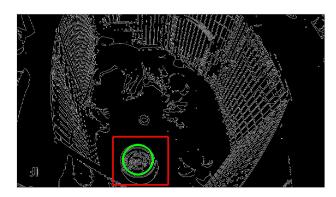
# Activity Classification: Eat



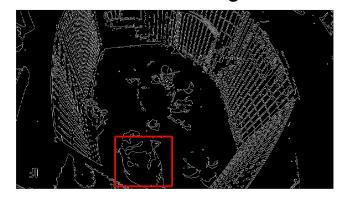
Test Image 1



Test Image 2



**Not Eating** 



Eating