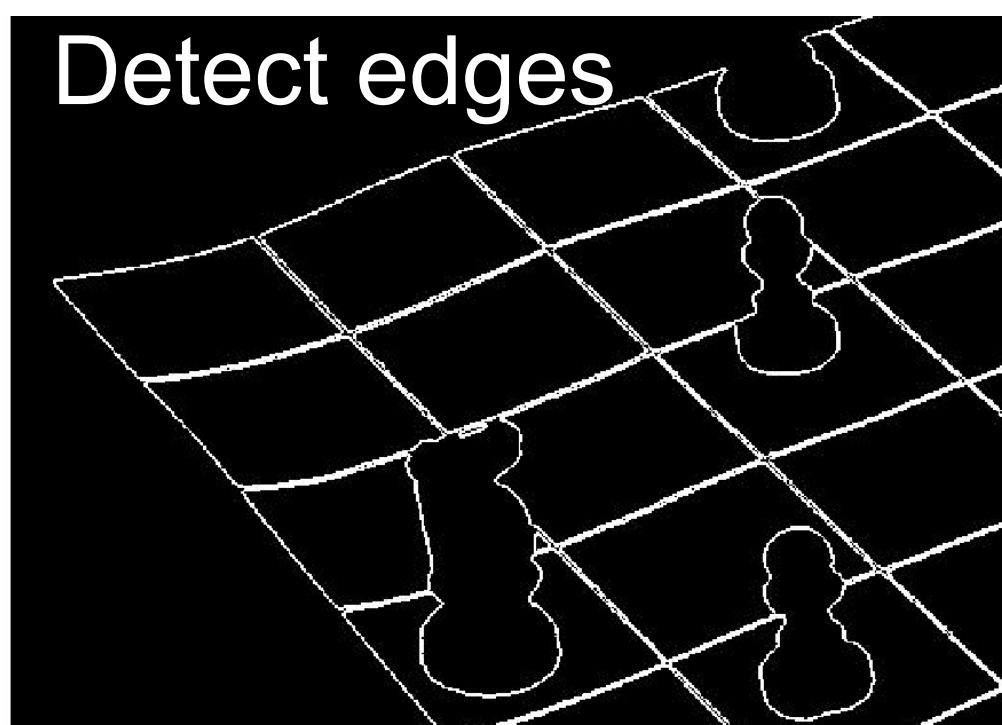
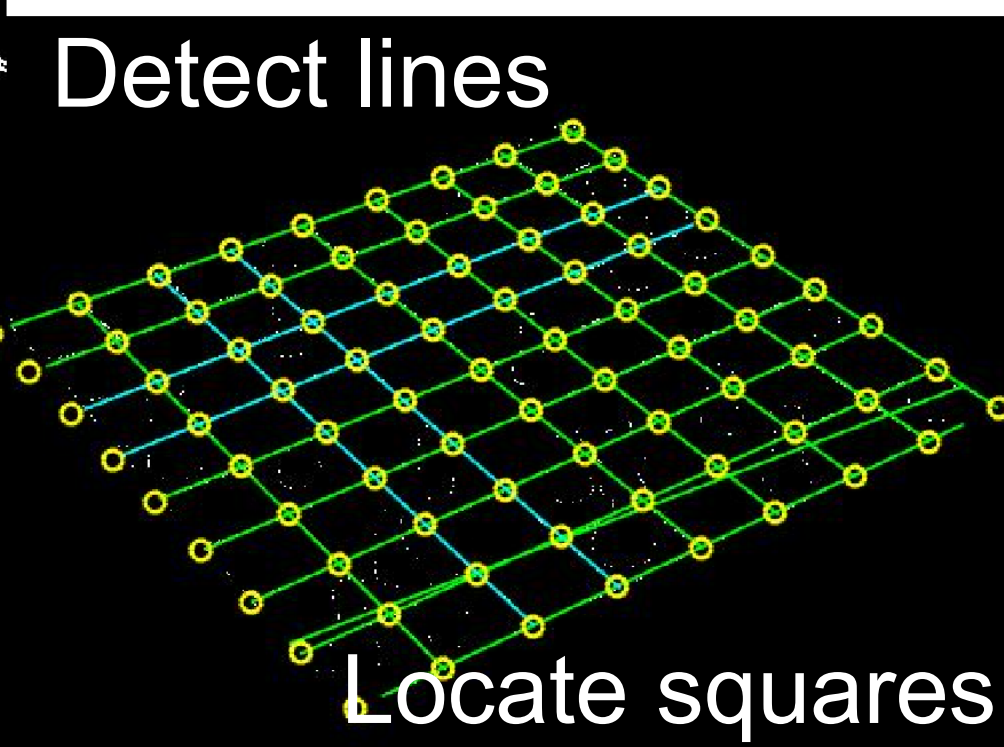


Recognizing the Board

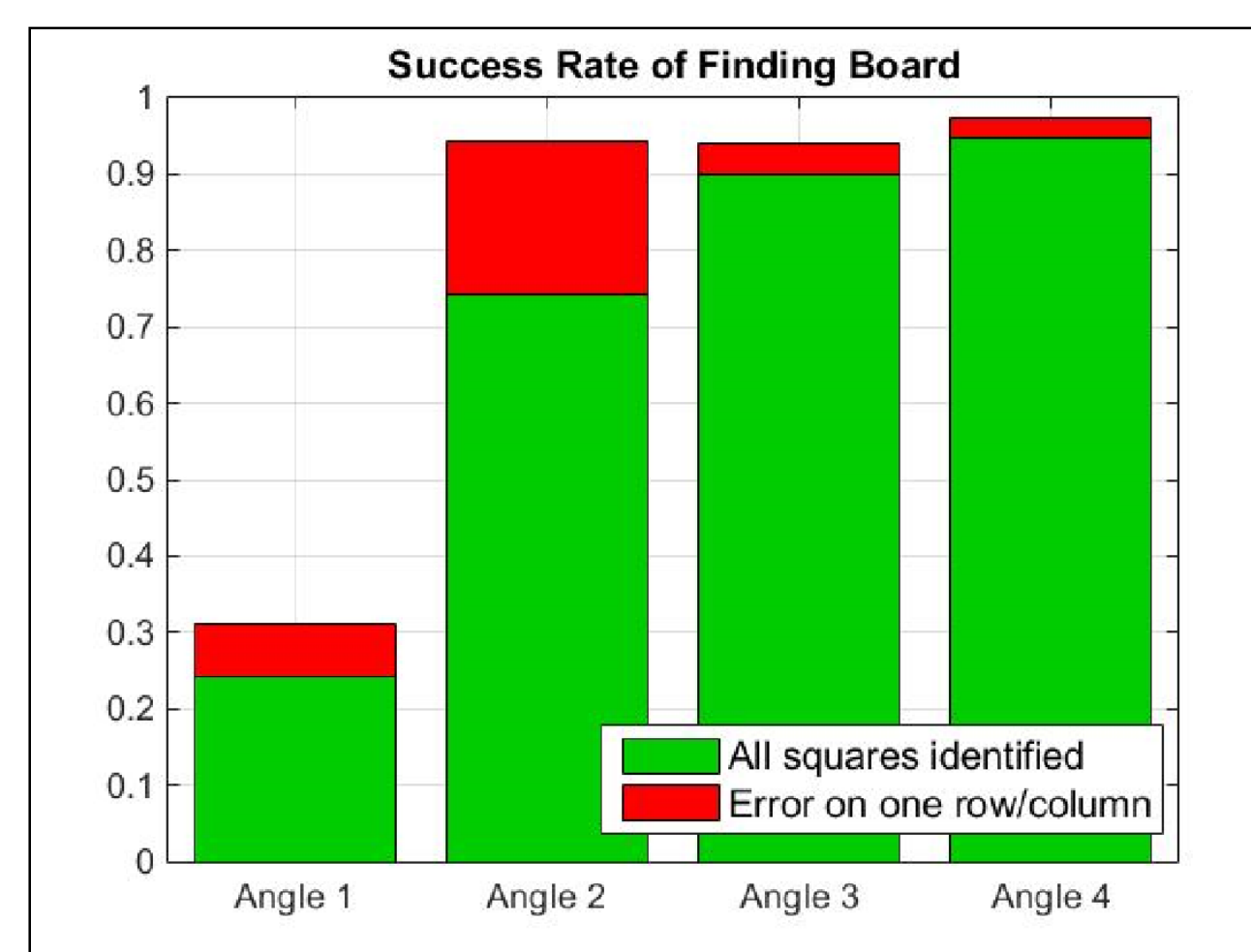


Binarize red and green channels
Morphological edge detection

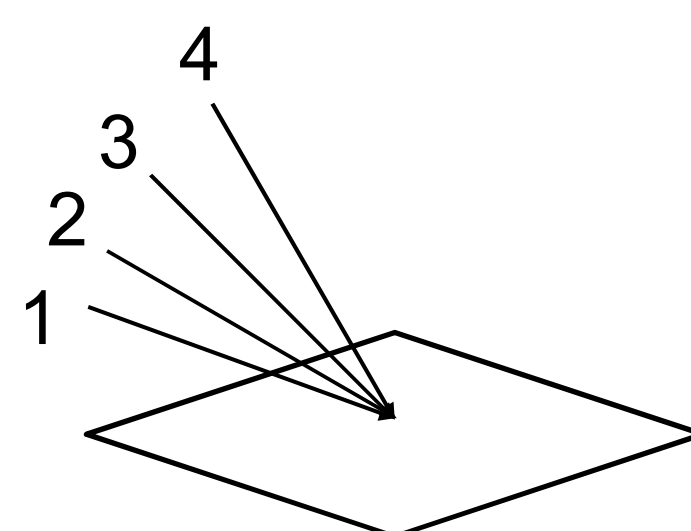


Locate squares

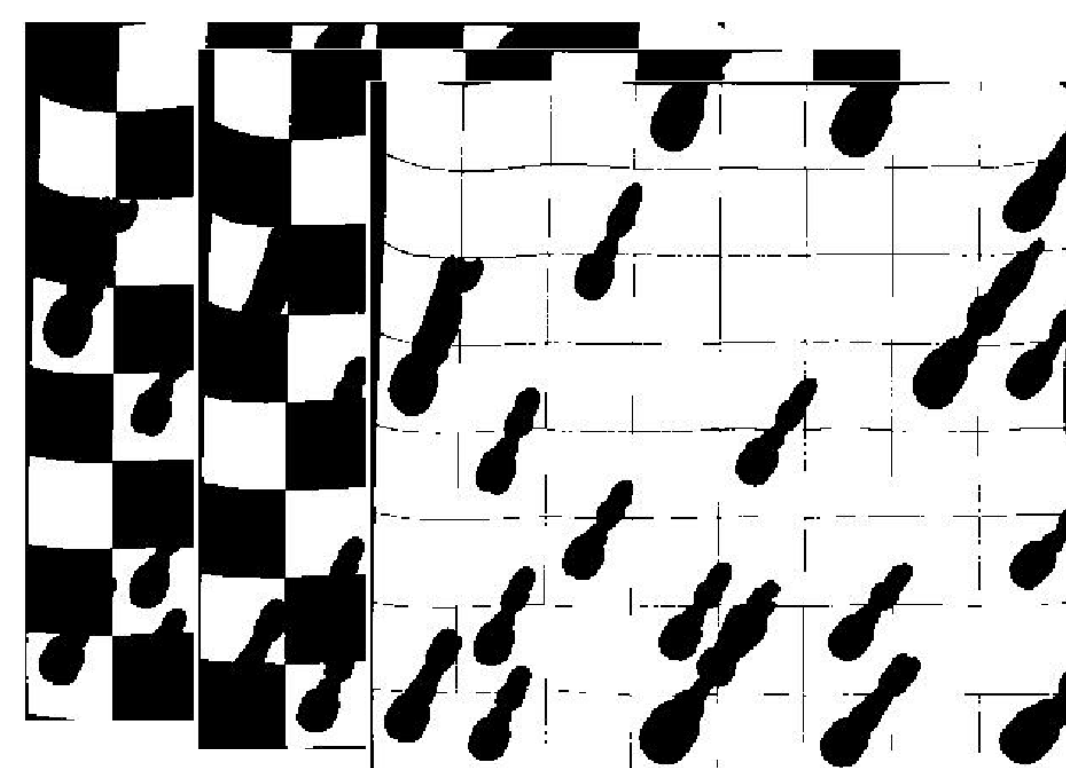
Hough transform
Separate lines into sets by theta value
Estimate homography



Test angles



Invert transform on red and green channels
Detect square color
Locate pieces



Objective

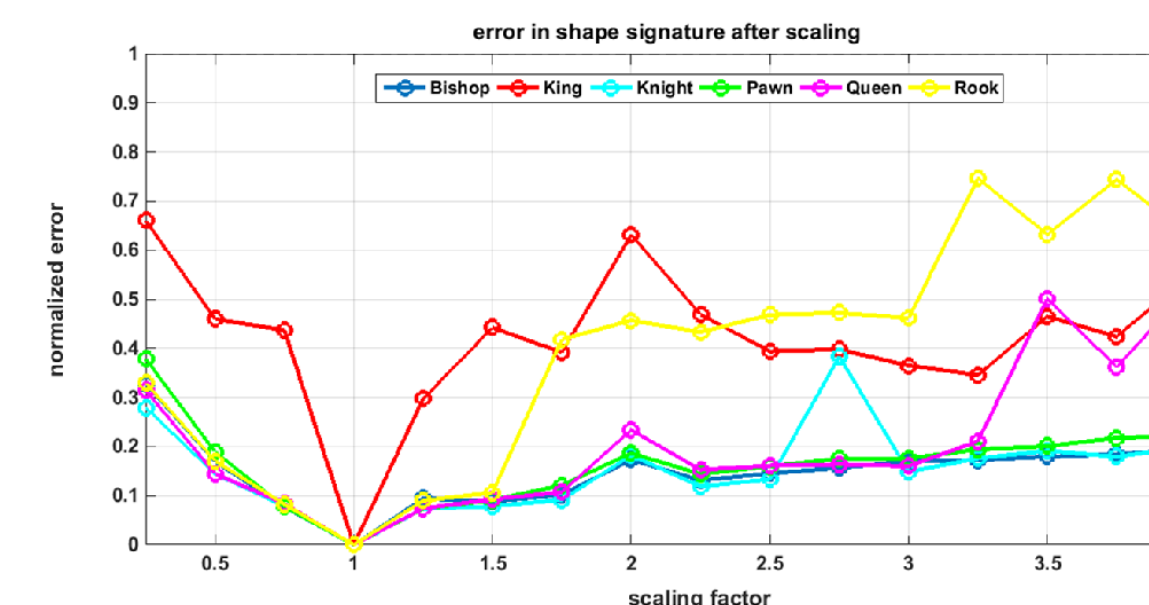
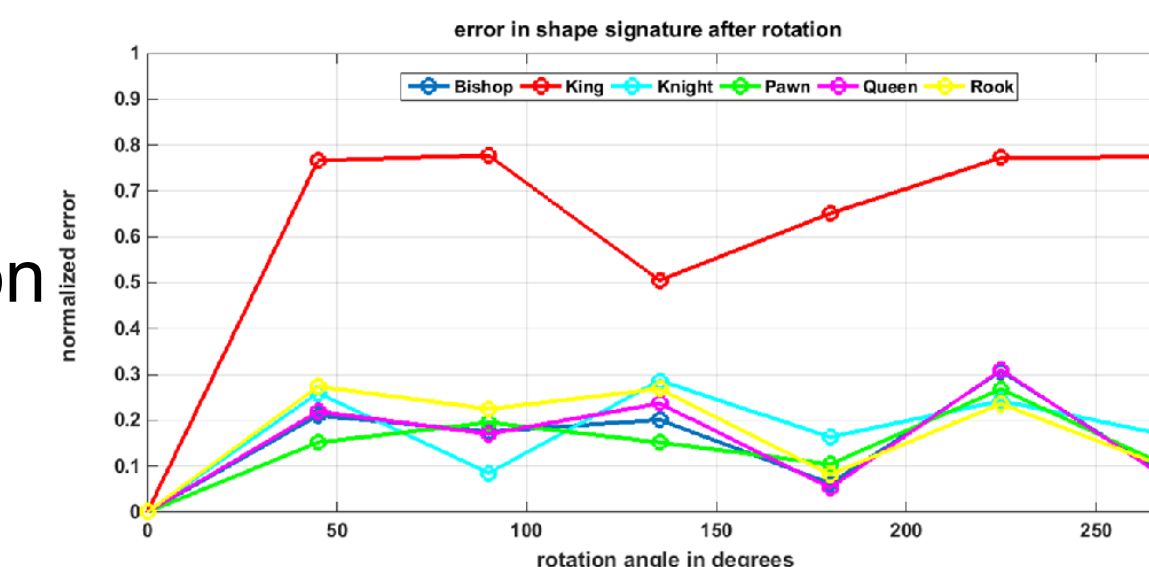
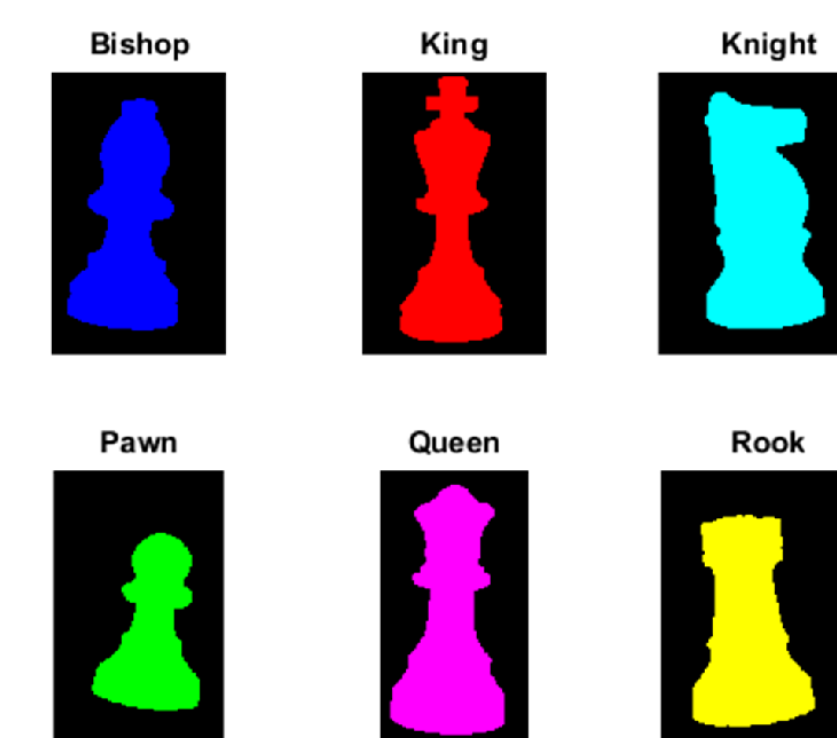
Detect a chessboard and identify pieces on it using image processing techniques



Recognizing the Pieces

Shape signature

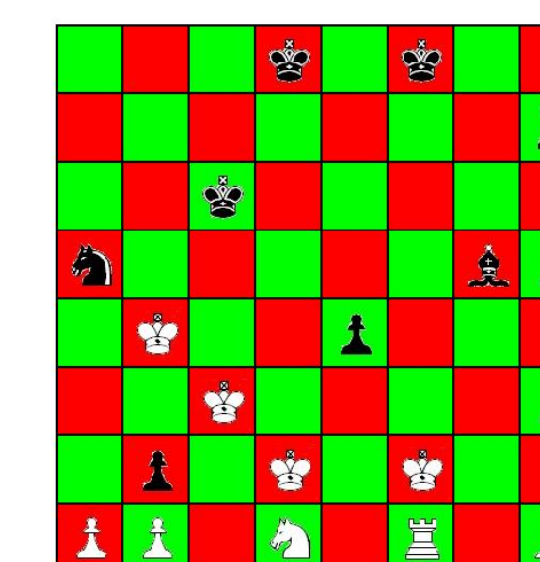
Fourier descriptors with tangent space transformation



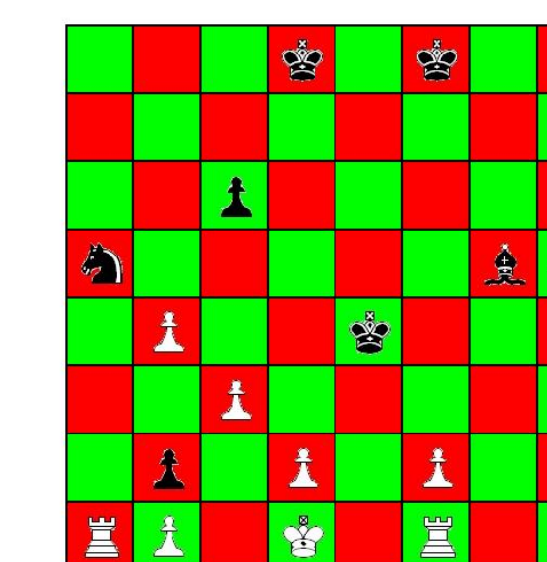
Pieces recognition

Nearest neighbor search

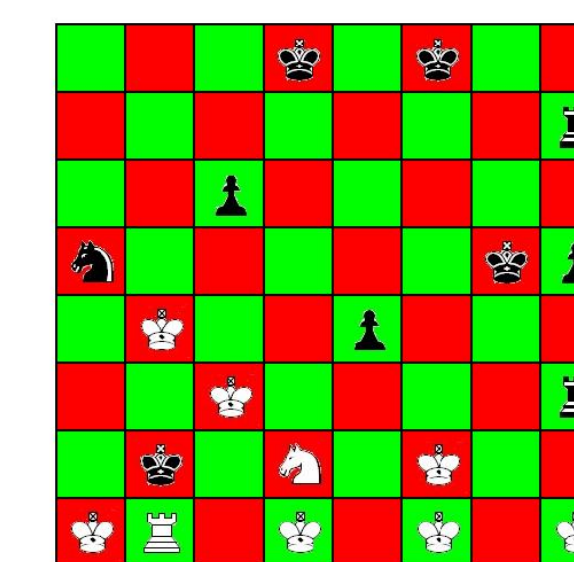
Segmentation



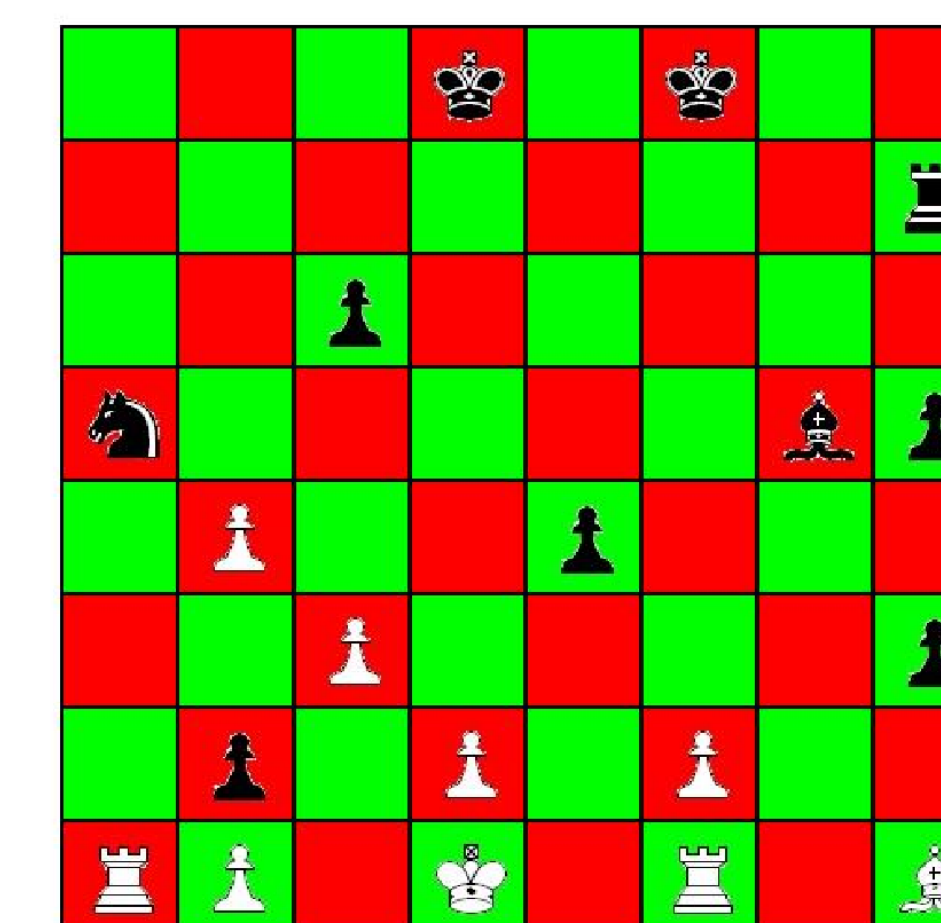
Edge detection



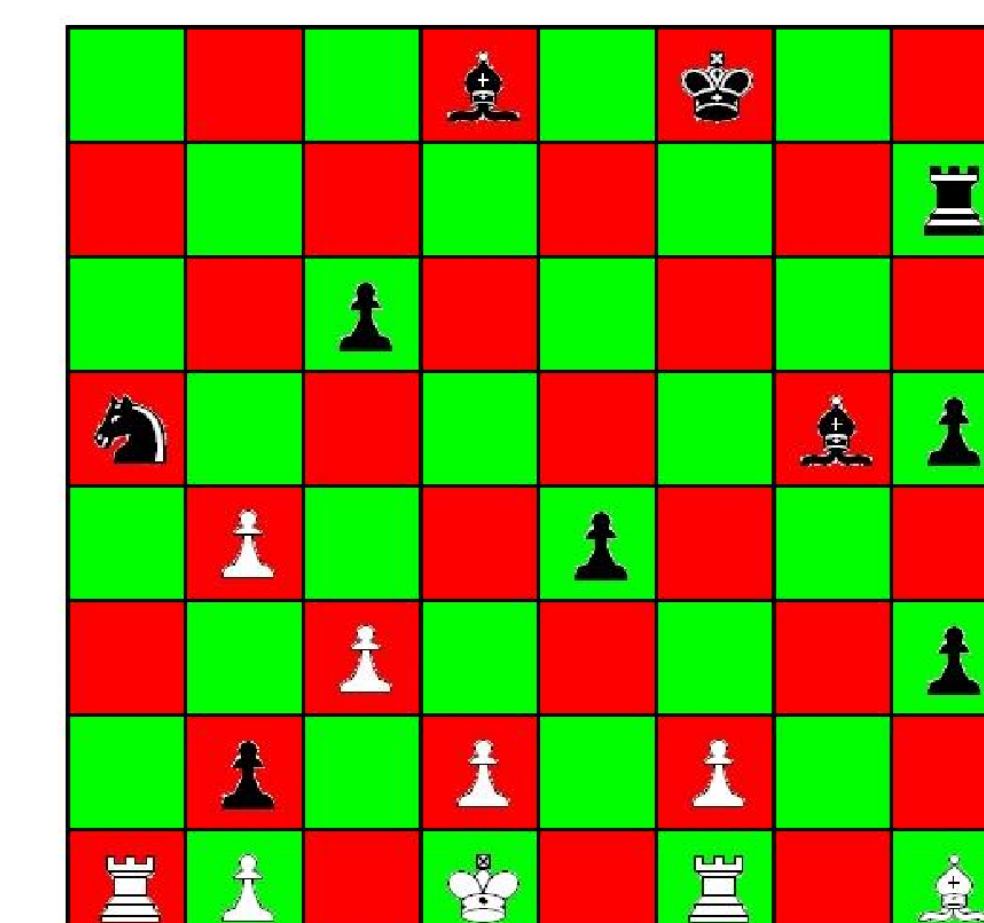
Color detection



Minimum distance



Side info



Possible improvements

- Use corner detection to correlate with lines.
- Improve algorithm to find initial square.
- Use size variations between chess pieces to improve piece recognition.
- Try another shape signature that is more robust to scale and rotation or use 3D object recognition.
- Process images from different views to recognize occluded pieces.