

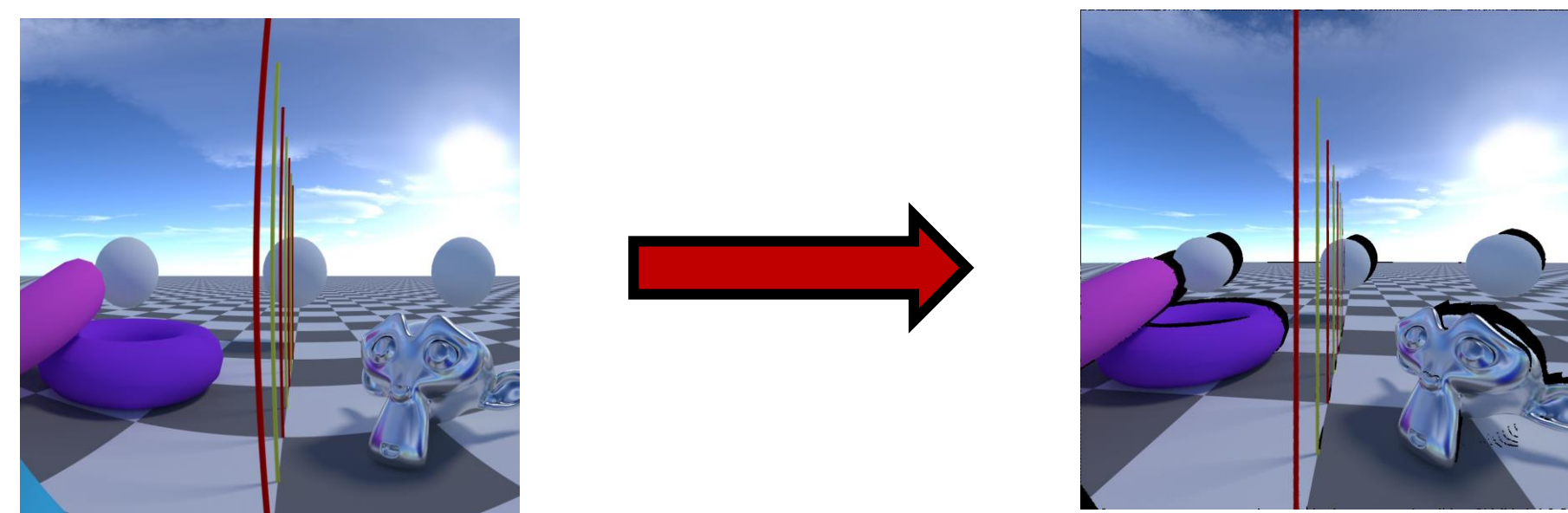
# Depth-Aided Exemplar-Based Disocclusions Filling for View Synthesis

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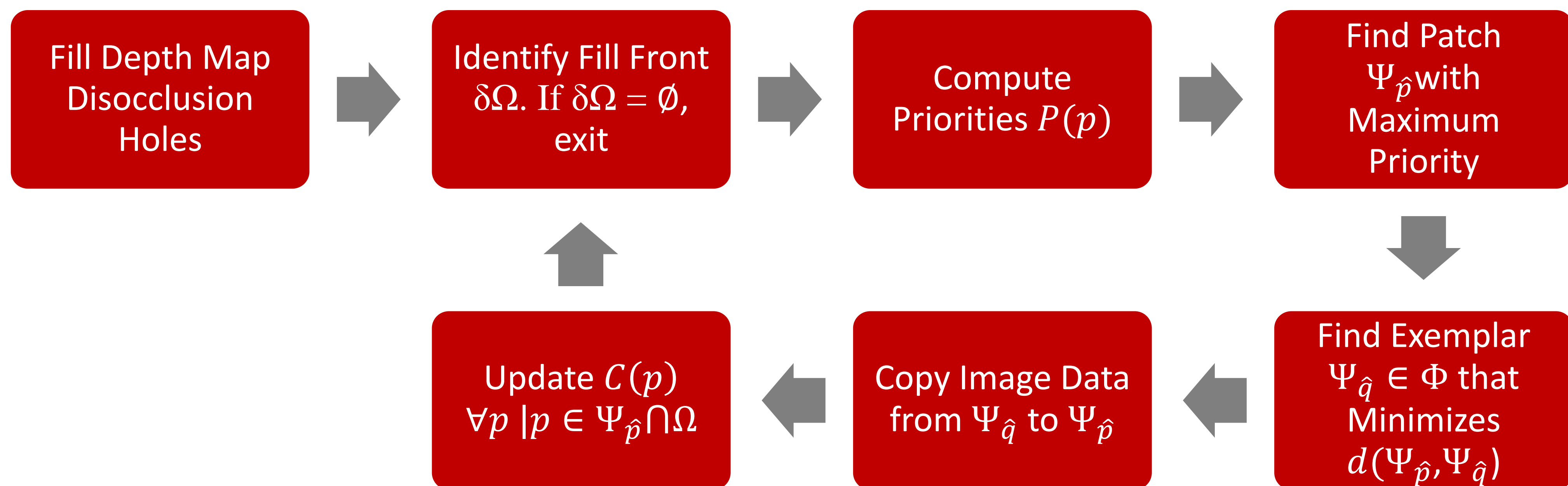
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## Motivation

Virtual reality is a new and rapidly expanding area seeking to immerse the user in completely new surroundings. Total immersion is currently hindered in pre-recorded environments by the user's inability to move inside the scene. Additional views can be synthesized through Depth-image-based-rendering (DIBR), but DIBR causes disocclusion holes – spatial regions that were not visible in the reference view. These holes can be filled with traditional inpainting, but the additional depth data can be leveraged to produce higher quality, more accurate results.

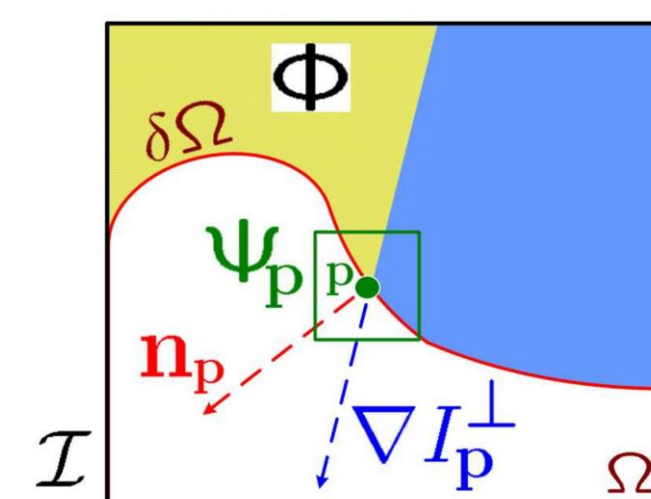


## The Algorithm



## Related Work

Daribo



$$P(p) = C(p) \cdot D(p) \cdot L(p)$$

$$C(p) = \frac{1}{|\Psi_p|} \sum_{q \in \Psi_p \cap \Phi} C(q)$$

$$D(p) = \langle \nabla^\perp I_p, n_p \rangle / \alpha$$

$$L(p) = \frac{1}{(|Z_p| + \sum_{q \in \Psi_p \cap \Phi} (Z_p - \bar{Z}_q)^2)}$$

$$\Psi_{\hat{q}} = \operatorname{argmin}_{\Psi_q \in \Phi} \{d(\Psi_{\hat{p}}, \Psi_q) + \beta d(Z_{\hat{p}}, Z_q)\}$$

Ružić

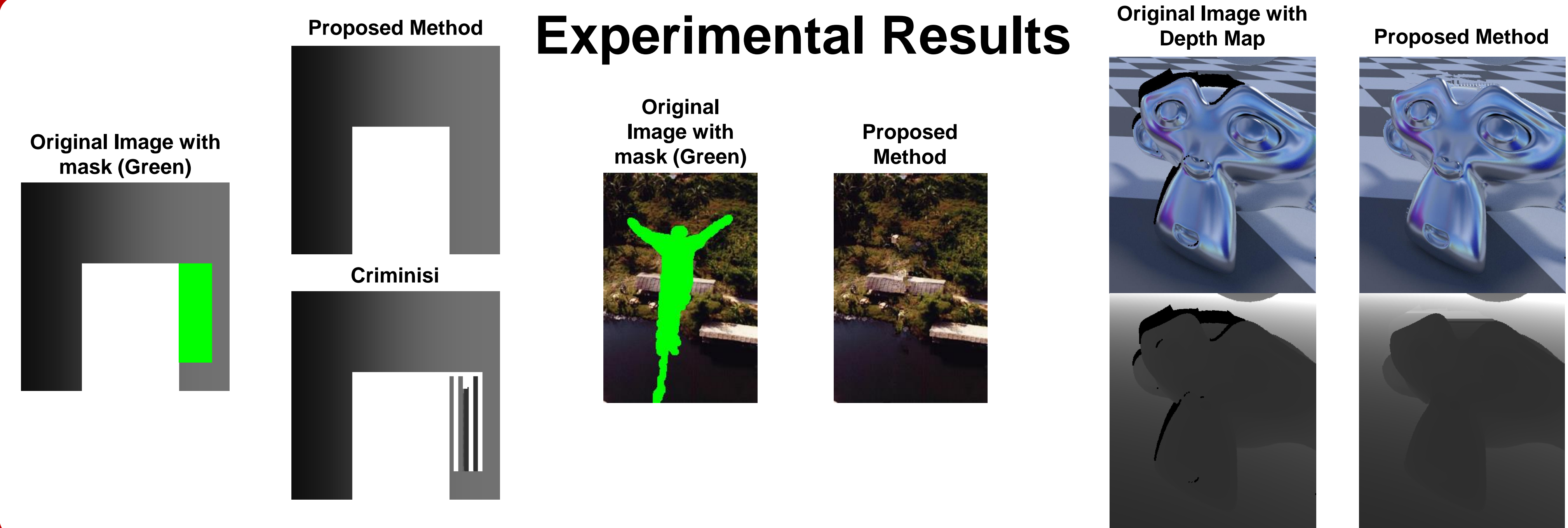


$$\Psi_{\hat{q}} = \sum_{i=1}^L \Psi_{\hat{q},i}$$

Jain

$$l(b_i) = \beta \sigma_N^2 b_i + \frac{1}{c(b_i)}$$

## Experimental Results



## References:

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- [2] K. Jain, L. C. Tran, R. Khoshebeh, and T. Q. Nguyen, "Efficient stereo-to-multiview synthesis," in *ICASSP 2011*, 2011, pp.889-892
- [3] Daribo and H. Saito, "A novel inpainting-based layered depth video for 3DTV," *IEEE Trans. On Broadcasting*, vol. 57, no. 2, pp. 533-541, 2011
- [4] T. Ruzic, L. Jovanov, H. Q. Luong, A. Pizurica, and W. Philips "Depth-guided patch-based disocclusion filling for view synthesis via markov random field modelling," in *ICSPCS 2014*, pp. 1-9, 15-17, 2014