Slide Template

Neal Parikh and Stephen Boyd

Stanford University

May 12, 2014

Outline

First section

Second section

First section

Bulleted list



- XXX
- XXX
- XXX

► XXX

- XXX
- XXX
- XXX



First section

Pictures with tikz



Pictures with tikz

- convex envelope of (nonconvex) f is the largest convex underestimator g
- ▶ *i.e.*, the best convex lower bound to a function



- example: ℓ_1 is the envelope of card (on unit ℓ_∞ ball)
- example: $\|\cdot\|_*$ is the envelope of rank (on unit spectral norm ball)
- ▶ various characterizations: *e.g.*, f^{**} or convex hull of epigraph

First section

Outline

First section

Second section

Group lasso

(e.g., Yuan & Lin; Meier, van de Geer, Bühlmann; Jacob, Obozinski, Vert)

problem:

minimize
$$f(x) + \lambda \sum_{i=1}^{N} ||x_i||_2$$

i.e., like lasso, but require groups of variables to be zero or not

▶ also called $l_{1,2}$ mixed norm regularization

Structured group lasso

(Jacob, Obozinski, Vert; Bach et al.; Zhao, Rocha, Yu; ...)

problem:

$$\begin{array}{ll} \mbox{minimize} & f(x) + \sum_{i=1}^N \lambda_i \|x_{g_i}\|_2 \\ \mbox{where} & g_i \subseteq [n] \mbox{ and } \mathcal{G} = \{g_1, \dots, g_N\} \end{array}$$

like group lasso, but the groups can overlap arbitrarily

- > particular choices of groups can impose 'structured' sparsity
- e.g., topic models, selecting interaction terms for (graphical) models, tree structure of gene networks, fMRI data
- generalizes to the composite absolute penalties family:

$$r(x) = \|(\|x_{g_1}\|_{p_1}, \dots, \|x_{g_N}\|_{p_N})\|_{p_0}$$

Structured group lasso

(Jacob, Obozinski, Vert; Bach et al.; Zhao, Rocha, Yu; ...)

hierarchical selection:



 $\blacktriangleright \mathcal{G} = \{\{4\}, \{5\}, \{6\}, \{2, 4\}, \{3, 5, 6\}, \{1, 2, 3, 4, 5, 6\}\}$

nonzero variables form a rooted and connected subtree

- if node is selected, so are its ancestors
- if node is not selected, neither are its descendants

Sample ADMM implementation: lasso

```
prox_f = Q(v, rho) (rho/(1 + rho))*(v - b) + b;
prox_g = Q(v, rho) (max(0, v - 1/rho) - max(0, -v - 1/rho));
AA = A*A';
L = chol(eve(m) + AA);
for iter = 1:MAX_ITER
    xx = prox_g(xz - xt, rho);
    yx = prox_f(yz - yt, rho);
    yz = L \setminus (L' \setminus (A*(xx + xt) + AA*(yx + yt)));
    xz = xx + xt + A'*(yx + yt - yz);
    xt = xt + xx - xz;
    yt = yt + yx - yz;
end
```

Figure



Algorithm

if L is not known (usually the case), can use the following line search:

given x^k , λ^{k-1} , and parameter $\beta \in (0, 1)$. Let $\lambda := \lambda^{k-1}$. repeat 1. Let $z := \mathbf{prox}_{\lambda g}(x^k - \lambda \nabla f(x^k))$.

- 2. break if $f(z) \leq \hat{f}_{\lambda}(z, x^k)$.
- 3. Update $\lambda := \beta \lambda$.

return $\lambda^k := \lambda$, $x^{k+1} := z$.

typical value of β is 1/2, and

$$\hat{f}_{\lambda}(x,y) = f(y) + \nabla f(y)^{T}(x-y) + (1/2\lambda) \|x-y\|_{2}^{2}$$