# Lecture 9: RLHF and Guest Lecture on DPO

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CS234 Reinforcement Learning.

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- In class on Wednesday
- $\bullet$  You are allowed 1 side of 1 8.5"  $\times$  11" sheet of notes
- All material through today's lecture (Monday) is eligible for the exam
- See Ed post for additional details and past related midterm/quizzes
- Good luck!

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Select all that are true

- The Bradley Terry model expresses the probability that someone will select option b<sub>i</sub> over b<sub>j</sub>
- Using preference tuples and the Bradley Terry model, one can learn a model of the reward function
- The resulting reward function can be shifted by any constant and will not change the resulting preferences
- The resulting reward function can be multiplied by any constant and will not change the resulting preferences
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- Last time: Imitation Learning (Max Entropy IRL) and RLHF
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- RLHF for LLM
- Direct Preference Optimization

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- Often easier for people to make than hand writing a reward function
- Often easier than providing scalar reward (how much do you like this ad?)

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- Consider k-armed bandits<sup>1</sup>: K actions  $b_1, b_2, \ldots b_k$ . No state/context.
- Assume a human makes noisy pairwise comparisons, where the probability she prefers  $b_i \succ b_j$  is

$$P(b_i \succ b_j) = \frac{\exp\left(r(b_i)\right)}{\exp\left(r(b_i)\right) + \exp\left(r(b_j)\right)} = p_{ij}$$
(1)

- Assume have N tuples of form  $(b_i, b_j, \mu)$  where  $\mu(1) = 1$  if the human marked  $b_i \succ b_j$ ,  $\mu(1) = 0.5$  if the human marked  $b_i = b_j$ , else 0 if  $b_j \succ b_i$
- Maximize likelihood with cross entropy

$$loss = -\sum_{(b_i, b_j, \mu) \in \mathcal{D}} \mu(1) \log P(b_i \succ b_j) + \mu(2) \log P(b_j \succ b_j)$$
(2)

- Use learned reward model, and do PPO with this model
- See prior lecture for notes on doing this over trajectories

<sup>&</sup>lt;sup>1</sup>We will see more on bandits later in the course

- How is this used in ChatGPT?
- Next set of slides are from part of Tatsu Hashimoto's Lecture 11 in CS224N

# High-level instantiation: 'RLHF' pipeline



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- First step: instruction tuning!
- Second + third steps: maximize reward (but how??)

# How do we model human preferences?

- Problem 2: human judgments are noisy and miscalibrated!
- Solution: instead of asking for direct ratings, ask for pairwise comparisons, which can be more reliable [Phelps et al., 2015; Clark et al., 2018]



## Make sure your reward model works first!

Evaluate RM on predicting outcome of held-out human judgments



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#### RLHF: Putting it all together [Christiano et al., 2017; Stiennon et al., 2020]

- Finally, we have everything we need:
  - A pretrained (possibly instruction-finetuned) LM  $p^{PT}(s)$
  - A reward model  $RM_{\phi}(s)$  that produces scalar rewards for LM outputs, trained on a dataset of human comparisons
  - A method for optimizing LM parameters towards an arbitrary reward function.
- Now to do RLHF:
  - Initialize a copy of the model  $p_{\theta}^{RL}(s)$  , with parameters  $\theta$  we would like to optimize
  - Optimize the following reward with RL:

$$R(s) = RM_{\phi}(s) - \beta \log \left( \frac{p_{\theta}^{PD}(s)}{p^{PT}(s)} \right)$$

 $\begin{array}{c} F(s) \\ \hline T(s) \end{array} \end{array} \begin{array}{c} Pay a price when \\ p_{\theta}^{RL}(s) > p^{PT}(s) \end{array}$ 

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This is a penalty which prevents us from diverging too far from the pretrained model. In expectation, it is known as the **Kullback-Leibler (KL)** divergence between  $p_{\theta^{L}}^{RL}(s)$  and  $p^{PT}(s)$ .

### RLHF provides gains over pretraining + finetuning



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# InstructGPT: scaling up RLHF to tens of thousands of tasks



#### Step 2

Collect comparison data, and train a reward model.





A labeler ranks the outputs from best to worst



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#### Step 3

the dataset

The policy

generates

an output.

calculates a

reward for

the output.

the policy

using PPO.

Optimize a policy against the reward model using reinforcement learning.



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## Controlled comparisons of "RLHF" style algorithms

Method	Simulated win-rate (%)	Human win-rate (%)
GPT-4	$79.0 \pm 1.4$	$69.8 \pm 1.6$
ChatGPT	$61.4 \pm 1.7$	$52.9 \pm 1.7$
PPO	$46.8 \pm 1.8$	$55.1 \pm 1.7$
Best-of-n	$45.0 \pm 1.7$	$50.7 \pm 1.8$
Expert Iteration	$41.9 \pm 1.7$	$45.7 \pm 1.7$
SFT 52k (Alpaca 7B)	$39.2 \pm 1.7$	$40.7\pm1.7$
SFT 10k	$36.7 \pm 1.7$	$44.3\pm1.7$
Binary FeedME	$36.6 \pm 1.7$	$37.9 \pm 1.7$
Quark	$35.6 \pm 1.7$	-
Binary Reward Conditioning	$32.4 \pm 1.6$	-
Davinci001	$24.4 \pm 1.5$	$32.5 \pm 1.6$
LLaMA 7B	$11.3\pm1.1$	$6.5\pm0.9$

- Many works study RLHF behaviors using GPT-4 feedback (Simulated) as a surrogate for Human feedback.
- PPO (method in InstructGPT) does work
- Simple baselines (Best-of-n, Training on 'good' outputs) works well too

[Dubois et al 2023]

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- Learning and making decisions from human preferences is a rich area intersecting social choice, computational economics and AI
- New course at Stanford on this topic: Koyejo's CS329H: Machine Learning from Human Preferences

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Image: A matrix and a matrix