

Multiple Choice (8 x 1 pt)

1. For a symmetric ($A = A^T$) $n \times n$ matrix A ,
 - (a) $A^T A$ is invertible
 - (b) The eigenvalues are all real-valued
 - (c) For any b , there exists an x such that $Ax = b$
 - (d) There exist non-singular matrices L and U such that $A = LU$
2. If we're given a matrix A , the following can be said:
 - (a) If A is positive definite, then it has Cholesky Factors (ie $A = LL^T$)
 - (b) If A is over-determined, we use QR decomposition with Householder to solve $Ax = b$
 - (c) The pseudo-inverse of A , $A^+ = V\Sigma^+U^T$ can be used to solve least-squares problems
 - (d) Solving the minimization problem $\min_x \|b - Ax\|_2$ is equivalent to solving $Ax = b$
3. The following can be said about a Householder Matrix $H = I - 2\frac{vv^T}{v^T v}$
 - (a) The condition number for H is ∞
 - (b) It is a projection matrix onto the hyperplane orthogonal to v
 - (c) It preserves the 2-norm of a vector (ie $\|x\|_2 = \|Hx\|_2$ for all x)
 - (d) The eigenvalues of H are 1 with multiplicity n
4. Consider the multi-variate optimization problem $\min_{\vec{x}} f(\vec{x})$.
 - (a) When the Hessian is **negative definite**, we are at a local maximizer
 - (b) Solving this minimization problem is exactly equivalent to finding some \vec{x} such that $\nabla f(\vec{x}) = 0$
 - (c) If f is continuous and twice differentiable, then the Hessian is guaranteed not to be singular
 - (d) Steepest Descent performs poorly when the Hessian is poorly conditioned
5. Which of the following statement is true about the solution to the system of linear equations $Ax = b$, where A is an $m \times n$ matrix with $m > n$.
 - (a) It has no solutions
 - (b) It has infinite solutions
 - (c) It has unique solutions
 - (d) Can not say in general
6. Let x_0 be a least squares solution to $Ax = b$. Which of the following statement is true in general about the residual $r = Ax_0 - b$
 - (a) r is the projection of b onto the null space of A^T
 - (b) r is the projection of b onto the column space of A
 - (c) r is perpendicular to b
 - (d) r lies in the null space of A

7. Consider a symmetric matrix A with an eigenvalue λ and the corresponding unit length eigenvector q . The following is true about $B = A - \lambda qq^T$
- (a) The set of eigenvalues of B can not contain λ
 - (b) q lies in the null space of B
 - (c) The characteristic polynomials of A and B have the same roots
 - (d) If $q_2 \neq q$ is an eigenvector of A with the same eigenvalue λ , then q_2 cannot be an eigenvector of B
8. Given that $f(x)$ is continuous and has a root in the interval $[a, b]$, which of the following methods are guaranteed to converge to the root
- (a) Newton method
 - (b) Secant method
 - (c) Bisection method
 - (d) All of the above

Solving $Ax = b$ (4 pts)

1. Often in applications we are asked to solve the system of equations $Ax_i = b_i$ (where A **does not change**) for many b_i . Please discuss three options available for solving this problem **quickly and repeatedly**, and what properties A must have for each to work. (3 pts)

2. Why do we try to solve the least squares problem $\min_x \|b - Ax\|$ even when we know that A is full-ranked? (1 pt)

Singular Value Decomposition (4 pts)

1. State (without proof) the SVD of the following matrices (2 pts)

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} -3 \\ 5 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 & 1 \\ 0 & 10 & 0 \end{pmatrix} \quad (-5)$$

2. State the properties satisfied by U , Σ and V (1 pt)

3. In **Principle Component Analysis**, how is the SVD modified? How is this justified?

