Dynamic Programming Part Three

Announcements

- Problem Set Five due right now, or due Wednesday with a late period.
- Problem Set Six out, due next Monday.
 - Explore dynamic programming across different application domains!
 - Get a feel for how to structure DP solutions!
 - You may use a late day on Problem Set Six, but be aware this will overlap with the final project.
- Handout: "Guide to Dynamic Programming" also available.

Final Project Logistics

- Final project will go out next Monday and be due on Saturday, August 17 at 12:15PM (note the different time).
- Format: Three algorithms questions, each of which combine two or more different techniques from the quarter.
 - No collaboration permitted with other students.
 - No outside sources may be consulted.
 - Course staff will only answer clarifying questions about the problems.

Please evaluate this course on Axess.

Your feedback really makes a difference.

Outline for Today

- Shortest Paths Revisited
 - What if the edge weights are negative?
- The Bellman-Ford Algorithm
 - A simple and elegant algorithm for finding shortest paths.
- The Floyd-Warshall Algorithm
 - Finding shortest paths between all pairs of points.

Negative Edge Weights

The Recurrence

- Idea: Find paths of lengths at most 0, 1, 2, ..., n.
- Let w(u, v) denote the weight of edge (u, v).

1

- Let *s* be our start node. Let OPT(v, i) be the length of the shortest s v path whose length is at most *i*, or ∞ if no path exists.
- **Claim:** OPT(*v*, *i*) satisfies the following recurrence:

$$OPT(v,i) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0 \text{ and } v \neq s \end{cases}$$
$$min \begin{cases} OPT(v,i-1), & \text{otherwise} \\ min \{OPT(u,i-1)+w(u,v)\} \end{cases} & \text{otherwise} \end{cases}$$

The Bellman-Ford Algorithm

- The **Bellman-Ford algorithm** evaluates this recurrence bottom-up:
 - Create a table DP of size $n \times n$.
 - Set $DP[v][0] = \infty$ for all $v \neq s$.
 - Set DP[s][0] = 0
 - For i = 1 to n 1, for all $v \in V$:

```
- Set DP[v][i] = min \{ DP[v][i - 1], min \{ DP[u][i - 1] + w(u, v) \} (where (u, v) \in E) \}
```

• Return row *n* of DP.

	V 1	V 2	V 3	v_4
3	0	-3	-1	-2
2	0	-3	2	-2
1	0	-3	2	8
0	0	8	8	8



$$OPT(v,i) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v = s \\ \infty & \text{if } i = 0 \text{ and } v \neq s \\ min \begin{cases} OPT(v,i-1), & \\ min \{OPT(u,i-1)+w(u,v)\} \end{cases} & \text{otherwise} \end{cases}$$

Analyzing Time Complexity

- What is the time complexity of this algorithm?
 - Create a table DP of size $n \times n$.
 - Set $DP[v][0] = \infty$ for all $v \neq s$.
 - Set DP[s][0] = 0
 - For i = 1 to n 1, for all $v \in V$:

```
- Set DP[v][i] = min \{ DP[v][i - 1], min \{ DP[u][i - 1] + w(u, v) \} (where (u, v) \in E) \}
```

- Return row *n* of DP.
- Answer: **O(mn)**, i you reverse *G* prior to running the algorithm.

Analyzing Space Complexity

- What is the *space* complexity of this algorithm?
 - Create a table DP of size $n \times n$.
 - Set $DP[v][0] = \infty$ for all $v \neq s$.
 - Set DP[s][0] = 0
 - For i = 1 to n 1, for all $v \in V$:

```
- Set DP[v][i] = min \{ DP[v][i - 1], min \{ DP[u][i - 1] + w(u, v) \} (where (u, v) \in E) \}
```

- Return row *n* of DP.
- Answer: **O**(*n*²). (Can we reduce this?)

All-Pairs Shortest Paths

Shortest Paths

- Dijkstra's algorithm and the Bellman-Ford algorithm solve the single-source shortest paths problem in which we want shortest paths starting from a single node.
- The *all-pairs shortest paths problem* asks how to find the shortest paths between all possible pairs of nodes.
- Can we already solve this problem?
- How efficient is our solution?

Intermediary Nodes

- A path between *u* and *v* starts at *u*, passes through some set of intermediary nodes, and ends at *v*.
- If there are no negative cycles, there is some shortest path from *u* to *v* where no nodes will be revisited. (*Why?*)

Intermediary Nodes

- Number all nodes $v_1, v_2, ..., v_n$.
- What does a shortest path from *u* to *v* look like if no intermediary nodes are allowed?
- What does a shortest path from u to v look like if only node v_1 can be an intermediary node?
- What does a shortest path from u to v look like if only nodes v_1 and v_2 can be intermediary nodes?
- What does a shortest path from u to v look like if only nodes v_1 , v_2 , and v_3 can be intermediary nodes?

The Recurrence

- Let OPT(*i*, *j*, *k*) be the length of the shortest path from *i* to *j* where the only permitted internal nodes are v₁, v₂, ..., v_k.
- **Claim:** OPT(*i*, *j*, *k*) satisfies this recurrence:

$$OPT(i, j, k) = \begin{cases} 0 & \text{if } i = j \text{ and } k = 0 \\ w(v_i, v_j) & \text{if } (v_i, v_j) \in E \text{ and } k = 0 \\ \infty & \text{otherwise if } k = 0 \\ min \begin{cases} OPT(i, j, k-1), \\ OPT(i, k, k-1) + \\ OPT(k, j, k-1) \end{cases} & \text{if } k \neq 0 \end{cases}$$

The Floyd-Warshall Algorithm

- Let DP be an $n \times n \times (n + 1)$ table.
- For *i* from 1 to *n*, *j* from 1 to *n*:
 - Set DP[i][j][0] = 0 if i = j.
 - Set $DP[i][j][0] = w(v_i, v_j)$ if $i \neq j$ and $(u, v) \in E$.
 - Set $DP[i][j][0] = \infty$ if $i \neq j$ and $(u, v) \notin E$.
- For k from 1 to n, i from 1 to n, j from 1 to n:
 - Set DP[i][j][k] = min{
 DP[i][j][k 1],
 DP[i][k][k 1] + DP[k][j][k 1]
 }
- Return row *k* of DP.

Time and Space Complexity

- What is the time complexity of this algorithm?
 - **O**(*n*³)
- What is the space complexity of this algorithm?
 - **O**(*n*³)
- Interestingly, no dependence on the number of edges!

Further Algorithms

- Johnson's Algorithm combines Dijkstra's algorithm and Bellman-Ford together to solve the all-pairs shortest paths problem in arbitrary graphs with no negative cycles.
- Runtime is $O(mn + n^2 \log n)$ when implemented with appropriate data structures.
- How does that compare to Floyd-Warshall?
- Come talk to me after lecture for details!

Next Time

- Intractable Problems
- NP-Hardness
- Pseudopolynomial Algorithms