### Divide-and-Conquer Algorithms Part Two

#### Recap from Last Time

# Divide-and-Conquer Algorithms

- A **divide-and-conquer** algorithm is one that works as follows:
  - (Divide) Split the input apart into multiple smaller pieces, then recursively invoke the algorithm on those pieces.
  - **(Conquer)** Combine those solutions back together to form the overall answer.
- Can be analyzed using **recurrence relations**.

### **Two Important Recurrences**

$$T(0) = \Theta(1)$$
  

$$T(1) = \Theta(1)$$
  

$$T(n) = T([n / 2]) + T([n / 2]) + \Theta(n)$$

Solves to O(n log n)

$$T(0) = \Theta(1)$$
  

$$T(1) = \Theta(1)$$
  

$$T(n) \le T(\lfloor n / 2 \rfloor) + \Theta(1)$$

Solves to O(log *n*)

# Outline for Today

#### • More Recurrences

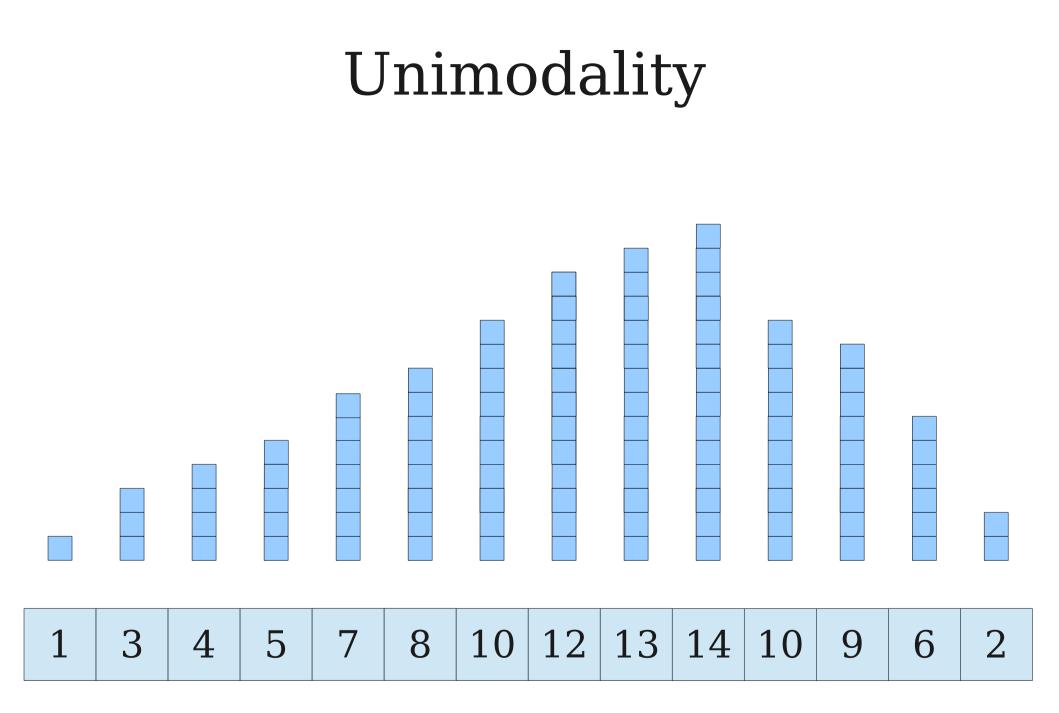
- Other divide-and-conquer relations.
- Algorithmic Lower Bounds
  - Showing that certain problems cannot be solved within certain limits.

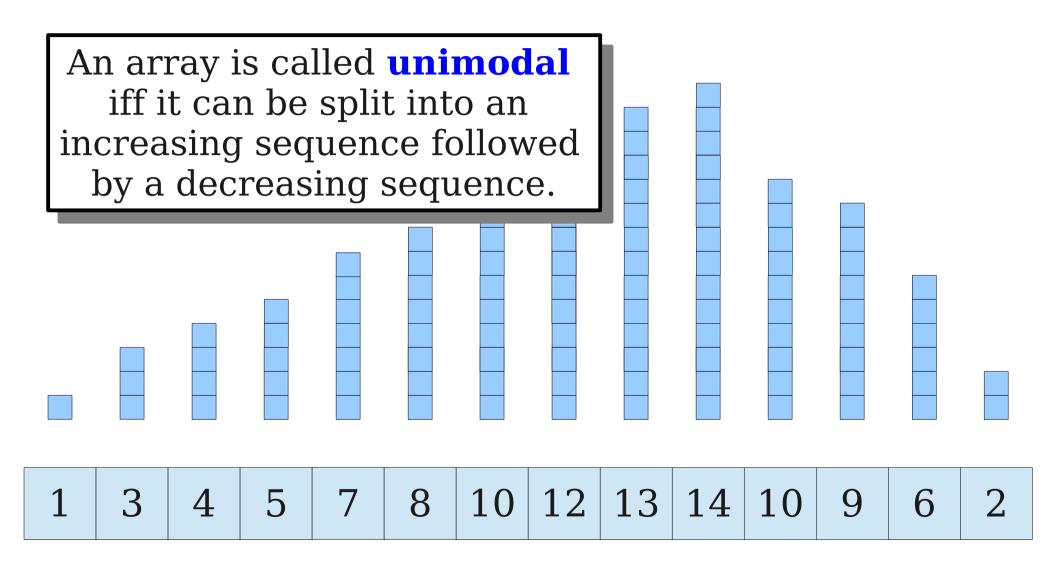
#### • Binary Heaps

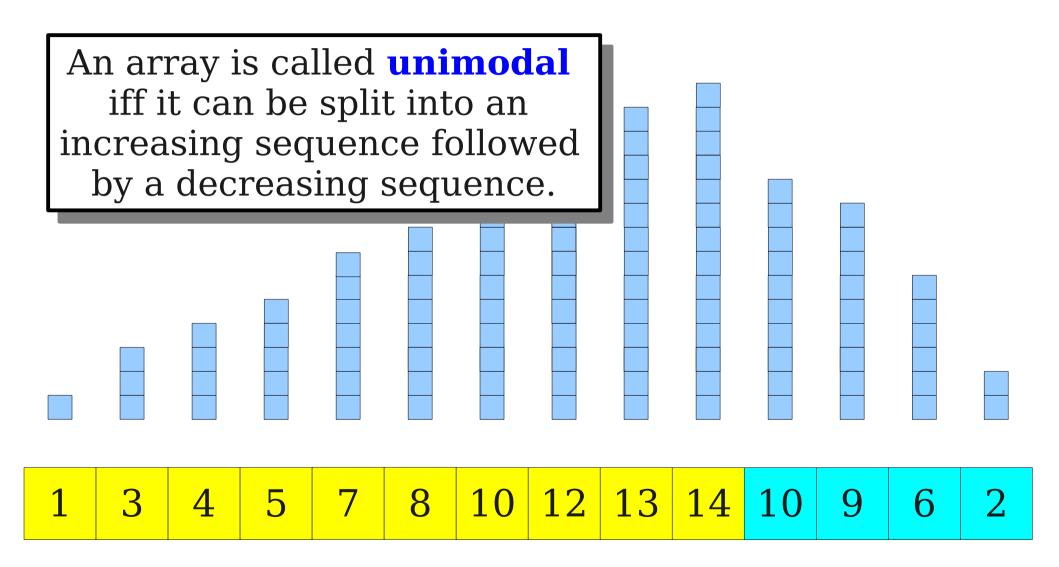
• A fast data structure for retrieving elements in sorted order.

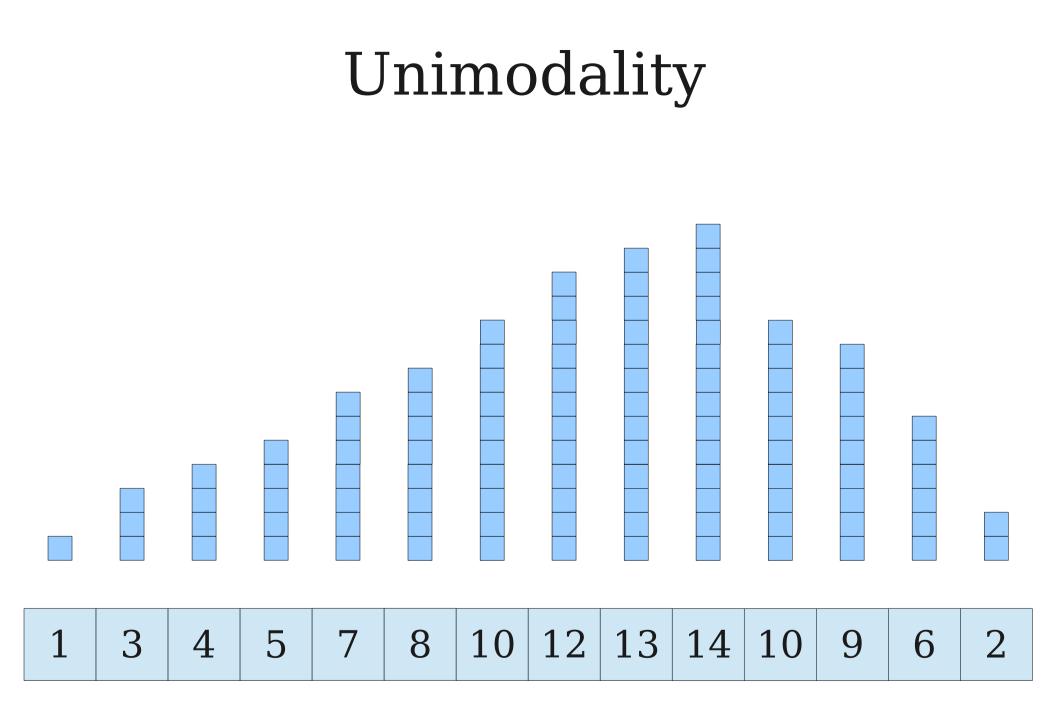
Another Algorithm: Maximizing Unimodal Arrays

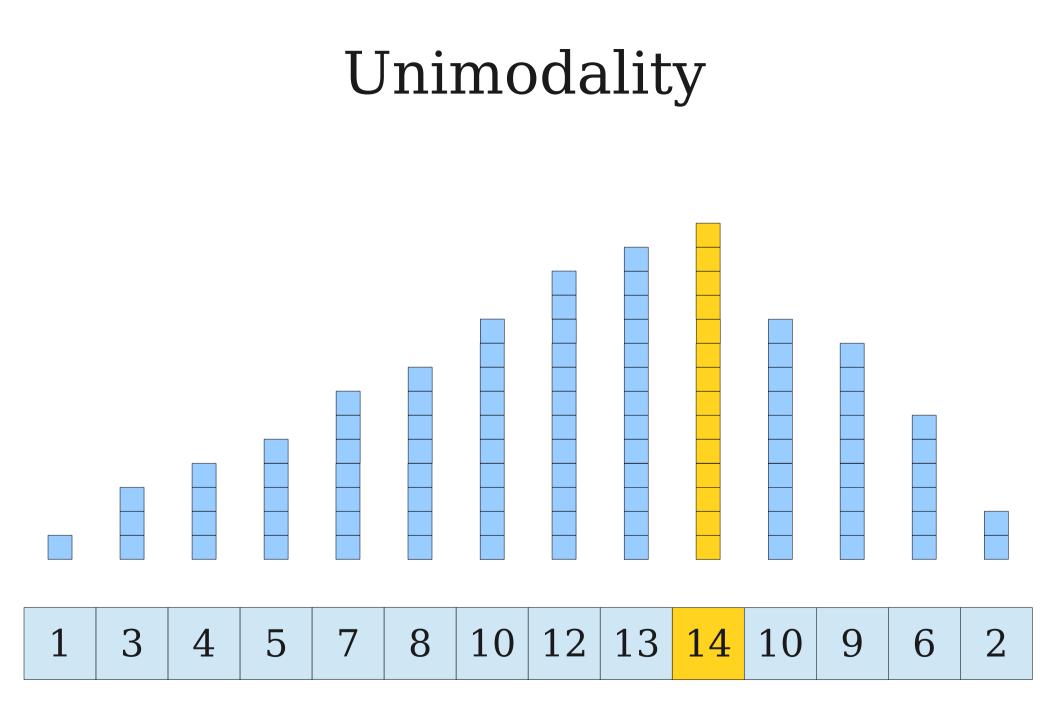
		1	3	4	5	7	8	10	12	13	14	10	9	6	2
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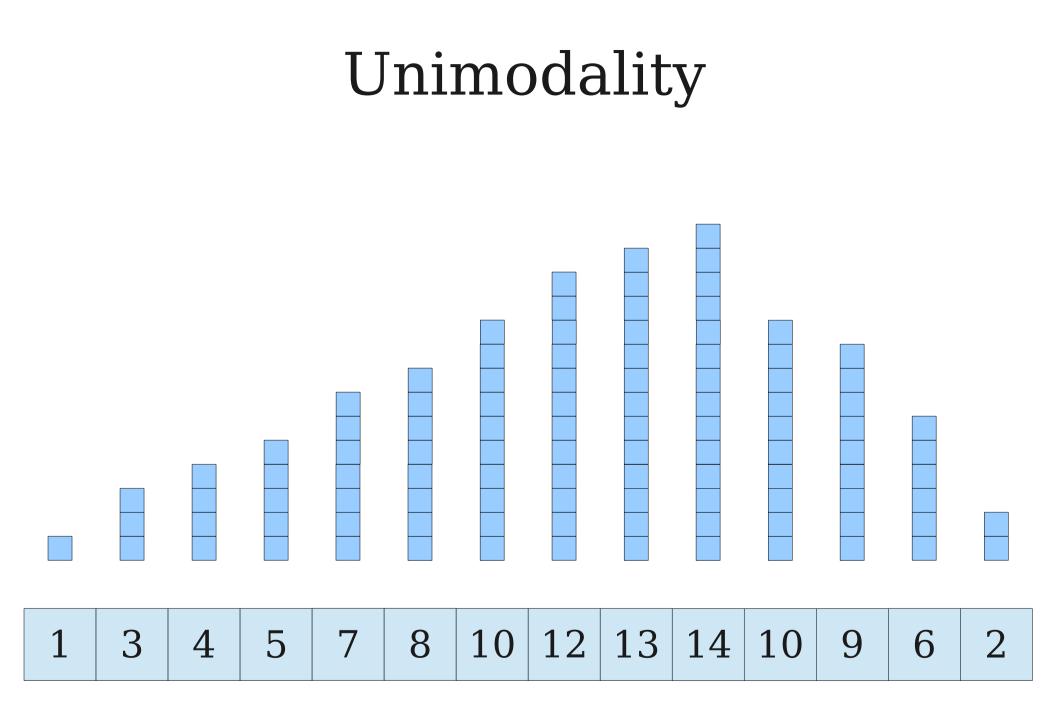


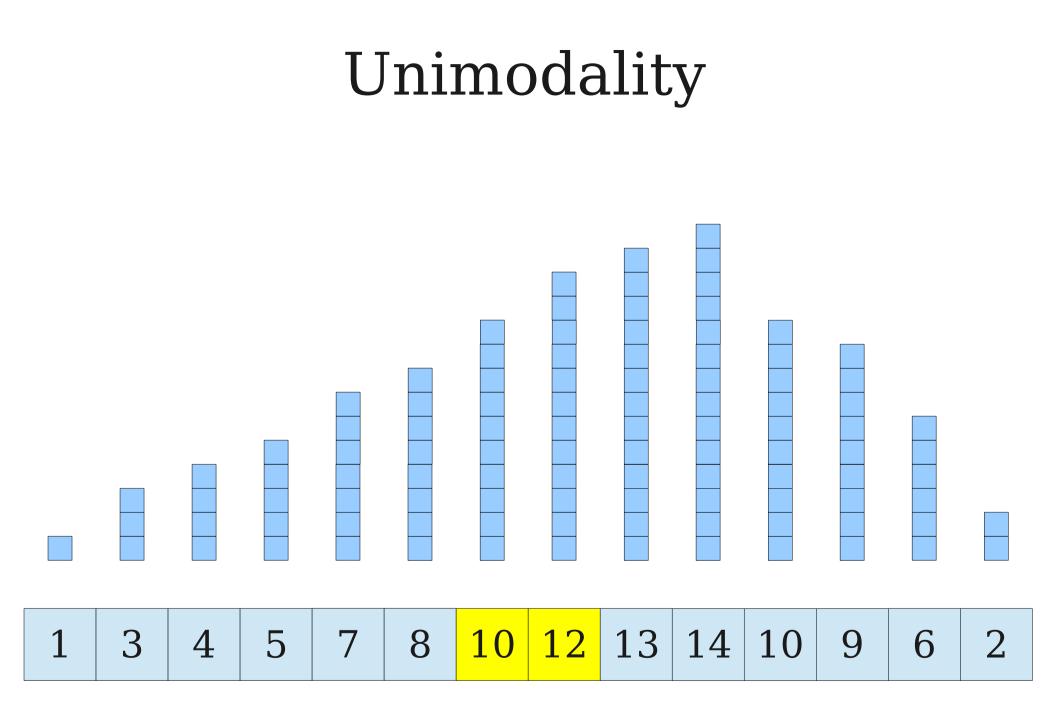


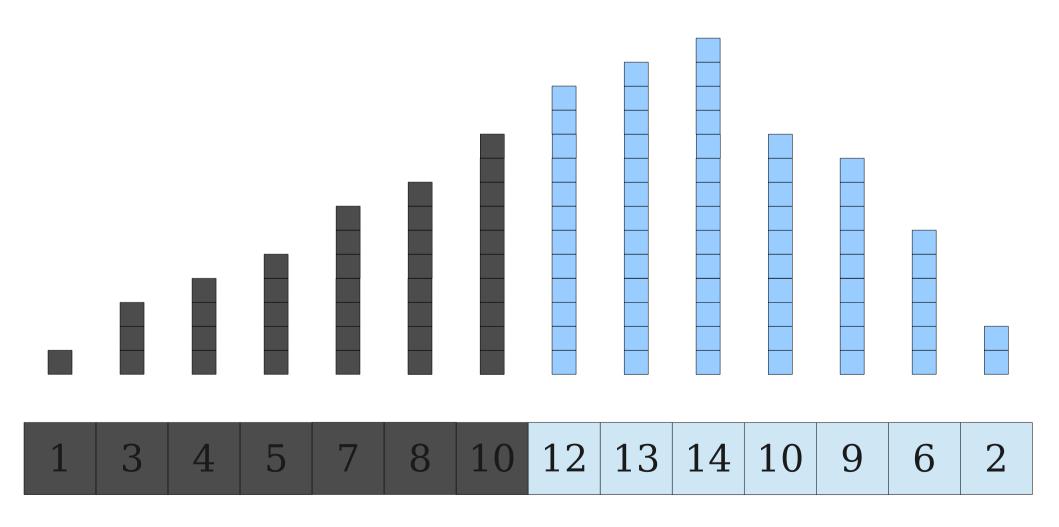


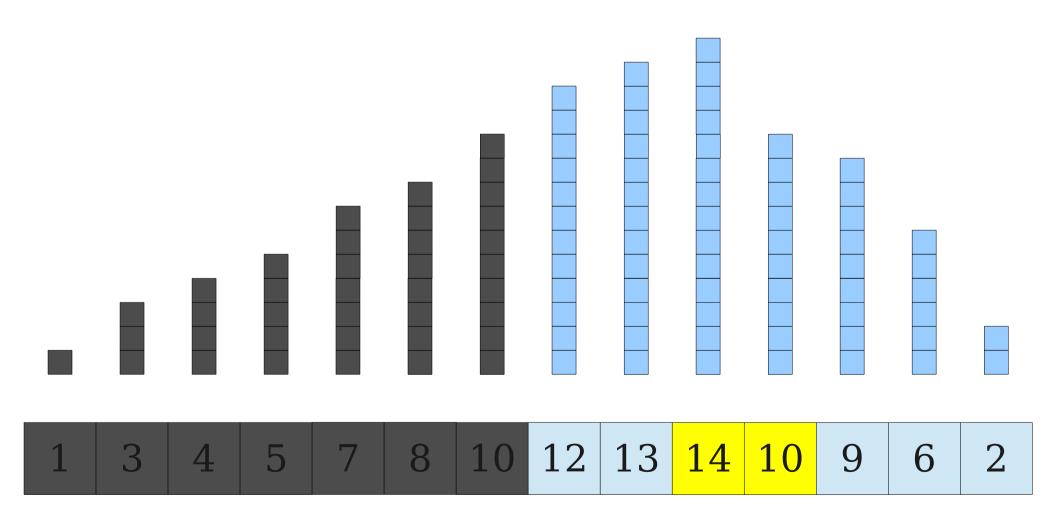


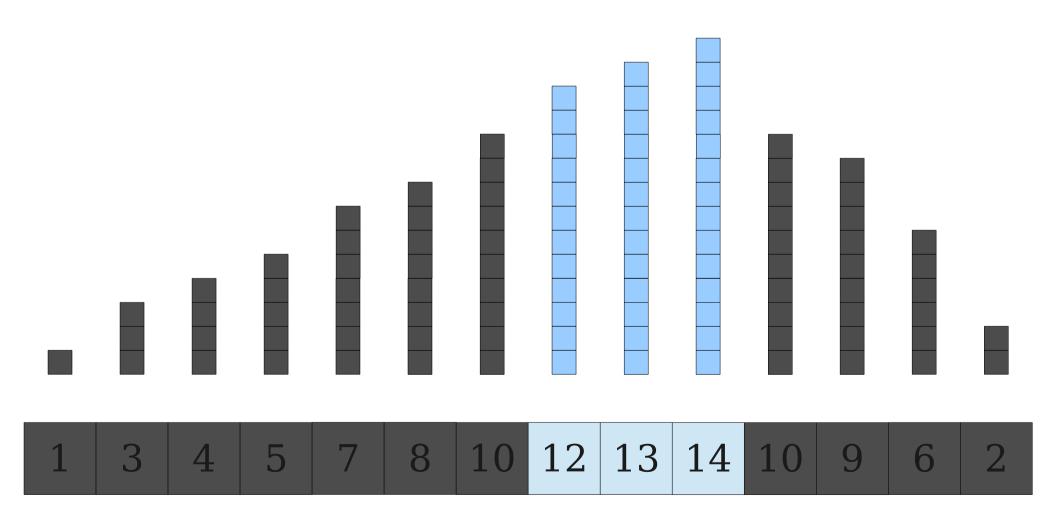


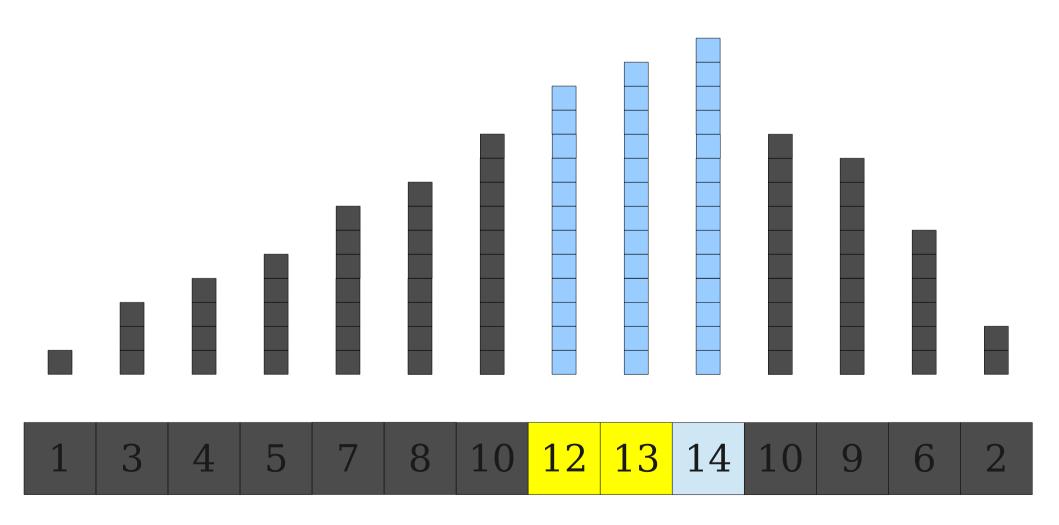


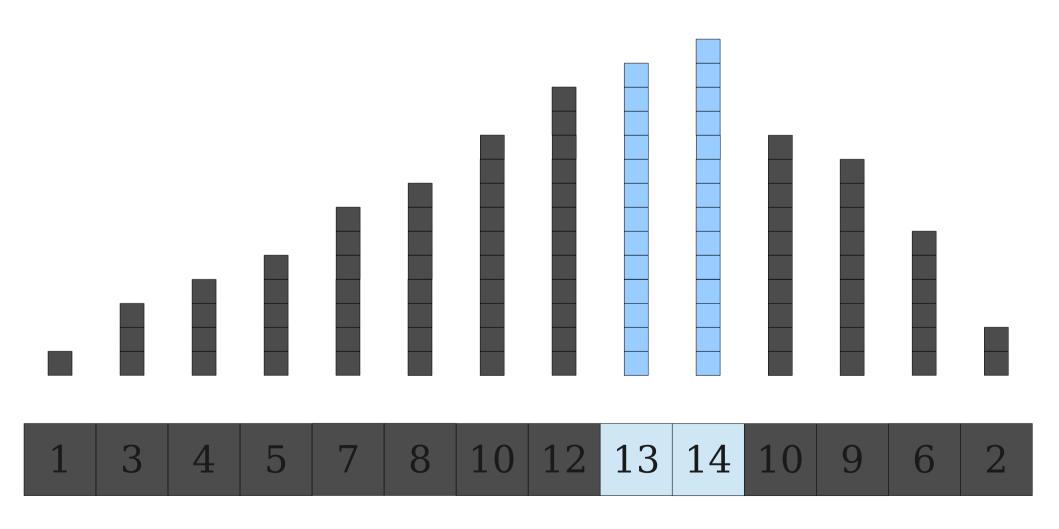


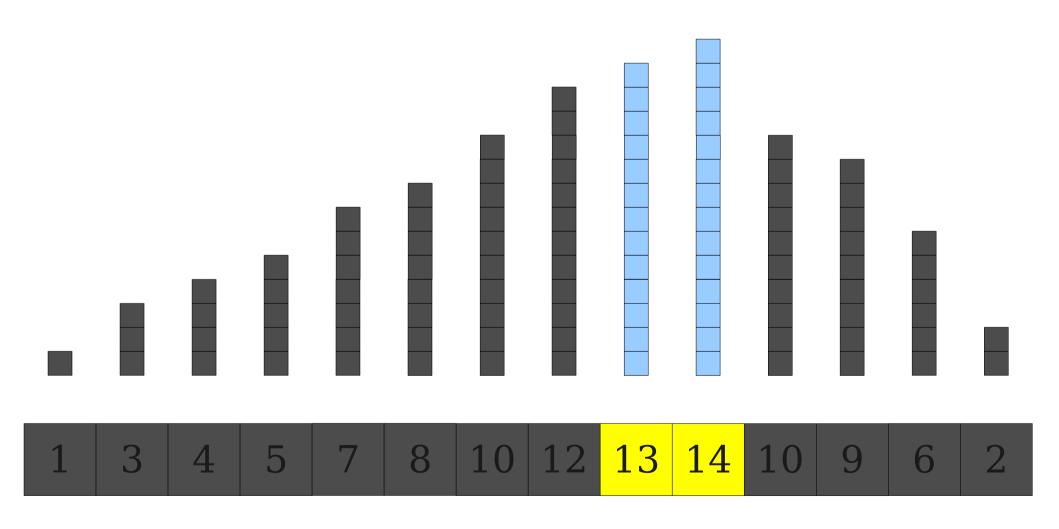


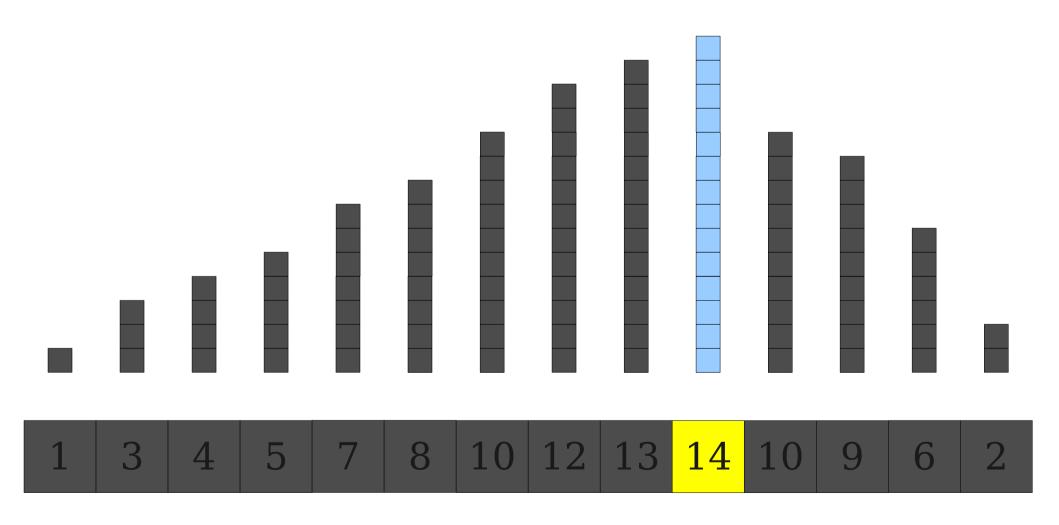












```
procedure unimodalMax(list A, int low, int high):
    if low = high - 1:
        return A[low]
    let mid = [(high + low) / 2]
    if A[mid] < A[mid + 1]
        return unimodalMax(A, mid + 1, high)
    else:
        return unimodalMax(A, low, mid + 1)</pre>
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$$T(1) = \Theta(1)$$

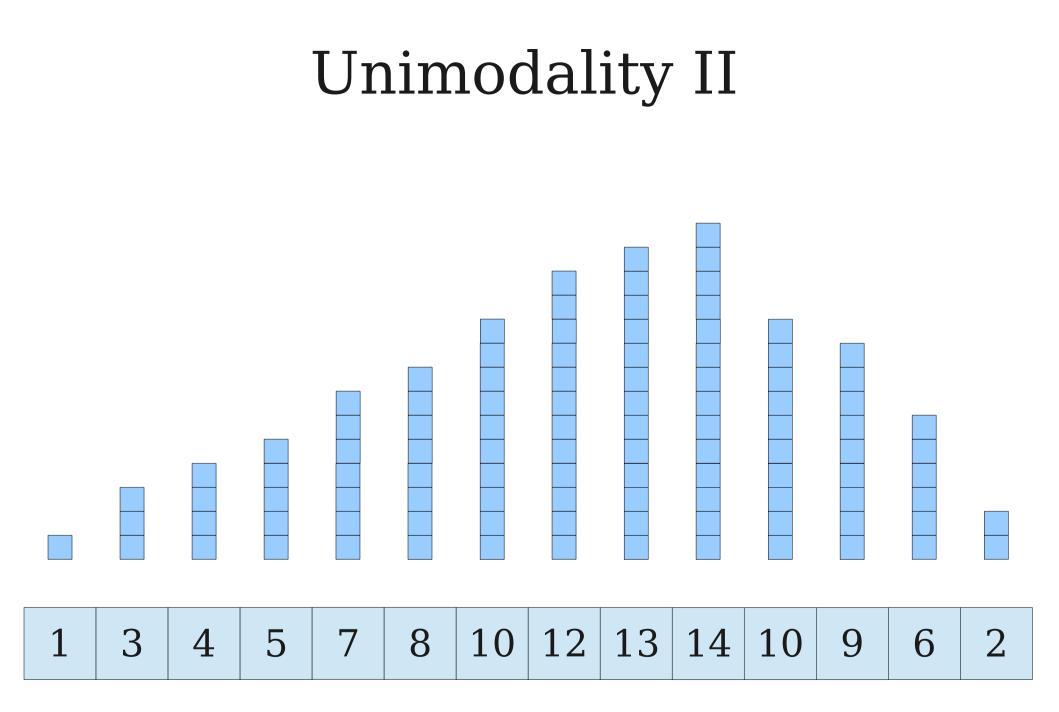
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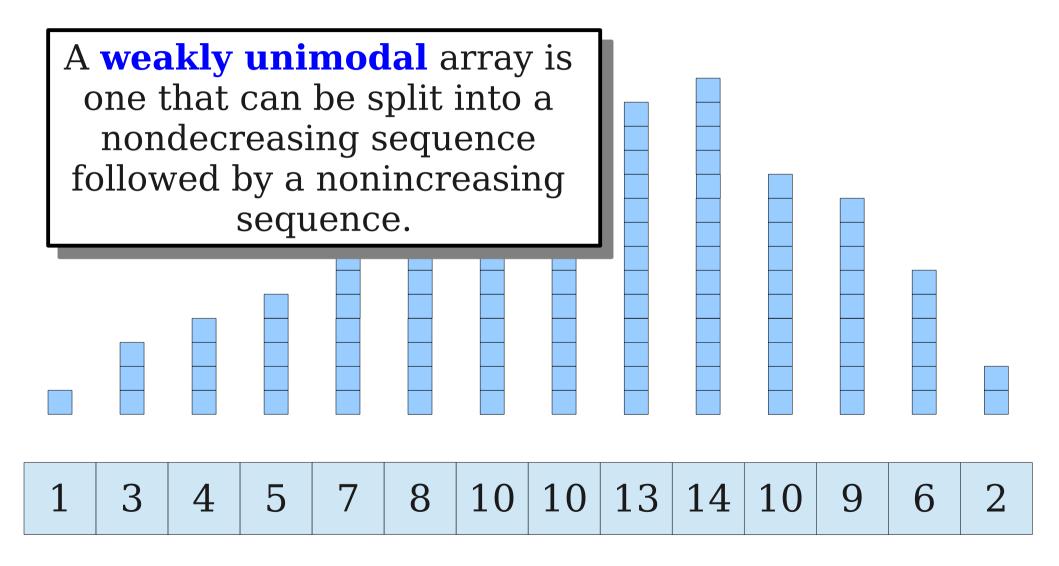
$$\begin{array}{l} T(1) = \Theta(1) \\ T(n) \leq T(\lceil n \ / \ 2 \rceil) + \Theta(1) \end{array}$$

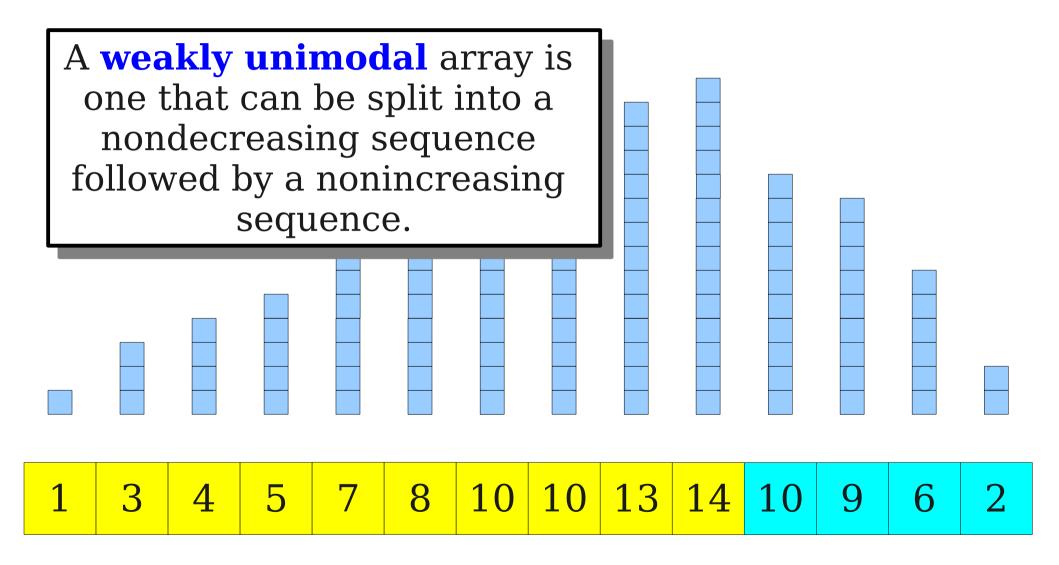
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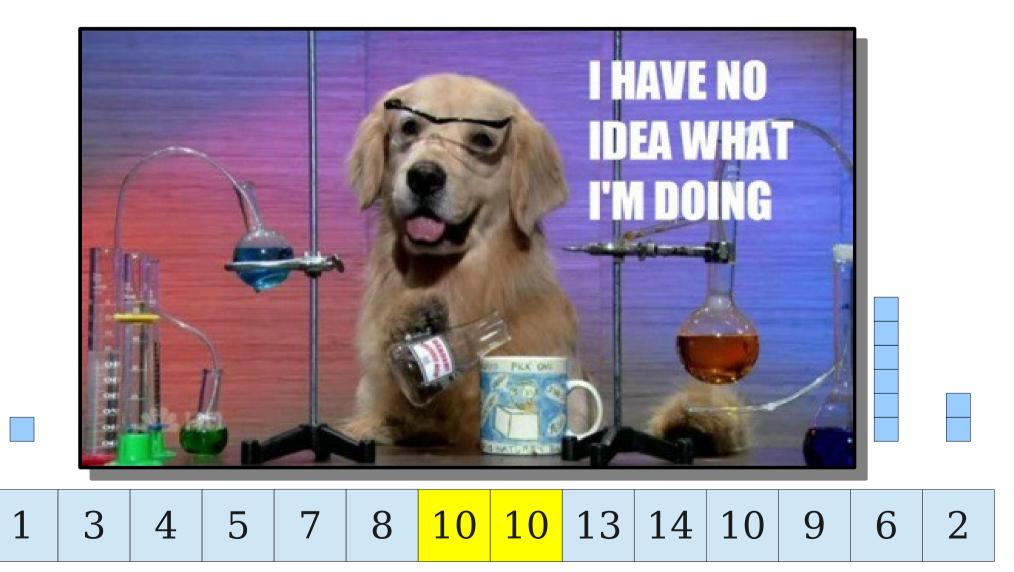
$$T(1) = \Theta(1)$$
  
 
$$T(n) \le T([n / 2]) + \Theta(1)$$

**O(log** *n*)









```
procedure weakUnimodalMax(list A, int low, int high):
    if low = high - 1:
        return A[low]
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procedure weakUnimodalMax(list A, int low, int high):
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$$\begin{array}{l} T(1) = \Theta(1) \\ T(n) \leq T(\lceil n \ / \ 2 \rceil) + T(\lfloor n \ / \ 2 \rfloor) + \Theta(1) \end{array}$$

```
procedure weakUnimodalMax(list A, int low, int high):
    if low = high - 1:
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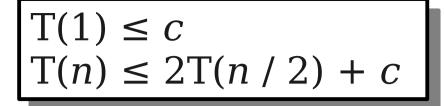
$$T(1) \le c$$
  
$$T(n) \le T(\lceil n / 2 \rceil) + T(\lfloor n / 2 \rfloor) + c$$

```
procedure weakUnimodalMax(list A, int low, int high):
    if low = high - 1:
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```

$$T(1) \le c$$
  
 
$$T(n) \le T(n / 2) + T(n / 2) + c$$

```
procedure weakUnimodalMax(list A, int low, int high):
    if low = high - 1:
        return A[low]
```

$$T(1) \le c$$
  
$$T(n) \le 2T(n / 2) + c$$



 $T(n) \leq 2T\left(\frac{n}{2}\right) + c$ 

$$\begin{split} n) &\leq 2 \operatorname{T} \left( \frac{n}{2} \right) + c \\ &\leq 2 \left( 2 \operatorname{T} \left( \frac{n}{4} \right) + c \right) + c \end{split}$$

**T** (

# $\begin{array}{l} \mathrm{T}(1) \leq c \\ \mathrm{T}(n) \leq 2\mathrm{T}(n \,/\, 2) \,+\, c \end{array}$

 $T(n) \leq 2T\left(\frac{n}{2}\right) + c$  $\leq 2\left(2T\left(\frac{n}{4}\right)+c\right)+c$  $\leq 4 \operatorname{T}\left(\frac{n}{4}\right) + 2 c + c$ 

$$T(n) \leq 2T\left(\frac{n}{2}\right) + c$$
  
$$\leq 2\left(2T\left(\frac{n}{4}\right) + c\right) + c$$
  
$$\leq 4T\left(\frac{n}{4}\right) + 2c + c$$
  
$$= 4T\left(\frac{n}{4}\right) + 3c$$

$$\leq 2T\left(\frac{n}{2}\right)+c$$

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$$\leq 4T\left(\frac{n}{4}\right)+2c+c$$

$$= 4T\left(\frac{n}{4}\right)+3c$$

$$\leq 4\left(2T\left(\frac{n}{8}\right)+c\right)+3c$$

T(n)

$$\leq 2T\left(\frac{n}{2}\right)+c$$

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T(n)

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## $\begin{array}{l} \mathrm{T}(1) \leq c \\ \mathrm{T}(n) \leq 2\mathrm{T}(n \,/\, 2) \,+\, c \end{array}$

$$\leq 2T\left(\frac{n}{2}\right)+c$$

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$$\leq 4\left(2T\left(\frac{n}{8}\right)+c\right)+3c$$

$$= 8T\left(\frac{n}{8}\right)+4c+3c$$

$$= 8T\left(\frac{n}{8}\right)+7c$$
...
$$\leq 2^{k}T\left(\frac{n}{2^{k}}\right)+(2^{k}-1)c$$

T(n)

$$T(n) \leq 2^k T\left(\frac{n}{2^k}\right) + (2^k - 1)c$$

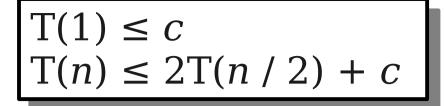
$$\begin{aligned} \mathbf{T}(n) &\leq 2^{k} \mathbf{T}\left(\frac{n}{2^{k}}\right) + (2^{k} - 1)c \\ &\leq 2^{\log_{2} n} \mathbf{T}(1) + (2^{\log_{2} n} - 1)c \end{aligned}$$

$$\begin{split} \mathrm{T}(n) &\leq 2^{k} \mathrm{T}\left(\frac{n}{2^{k}}\right) + (2^{k} - 1)c \\ &\leq 2^{\log_{2} n} \mathrm{T}(1) + (2^{\log_{2} n} - 1)c \\ &= n \mathrm{T}(1) + c (n - 1) \end{split}$$

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$$T(n) \leq 2^{k} T\left(\frac{n}{2^{k}}\right) + (2^{k} - 1)c$$
  
$$\leq 2^{\log_{2} n} T(1) + (2^{\log_{2} n} - 1)c$$
  
$$= n T(1) + c(n - 1)$$
  
$$\leq c n + c(n - 1)$$
  
$$= 2 c n - c$$

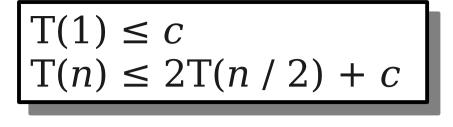
$$\begin{split} \mathrm{T}(n) &\leq 2^{k} \mathrm{T}\left(\frac{n}{2^{k}}\right) + (2^{k} - 1)c \\ &\leq 2^{\log_{2} n} \mathrm{T}(1) + (2^{\log_{2} n} - 1)c \\ &= n \mathrm{T}(1) + c(n - 1) \\ &\leq c n + c(n - 1) \\ &= 2 c n - c \\ &= O(n) \end{split}$$

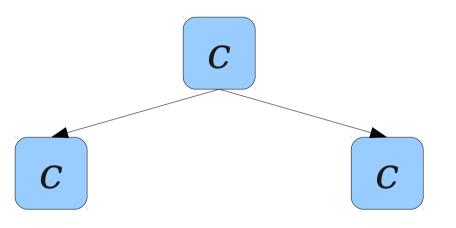


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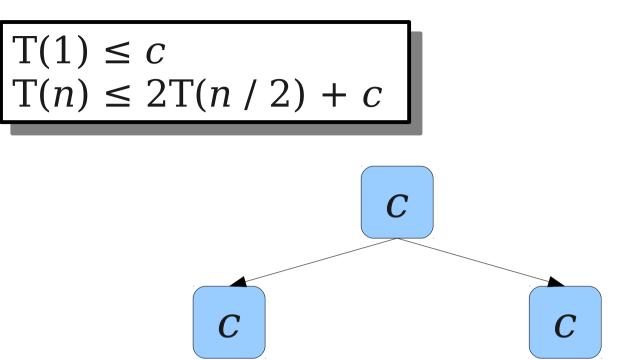
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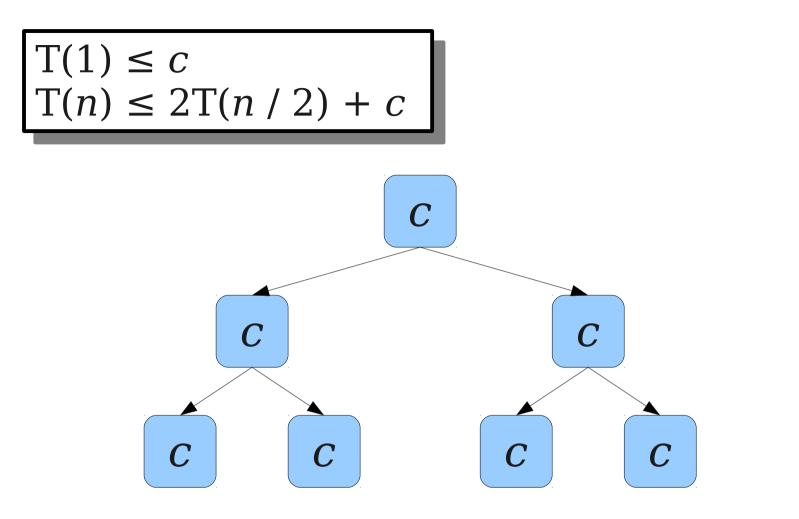






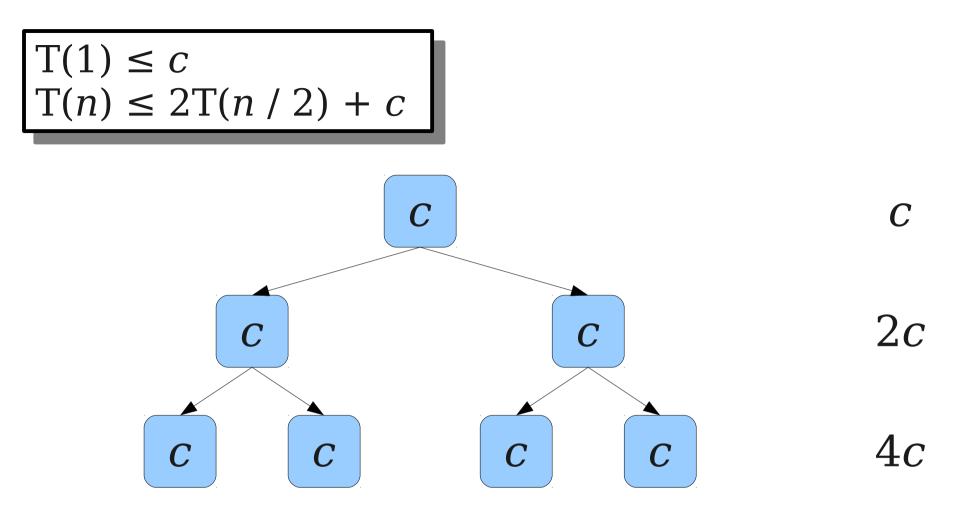
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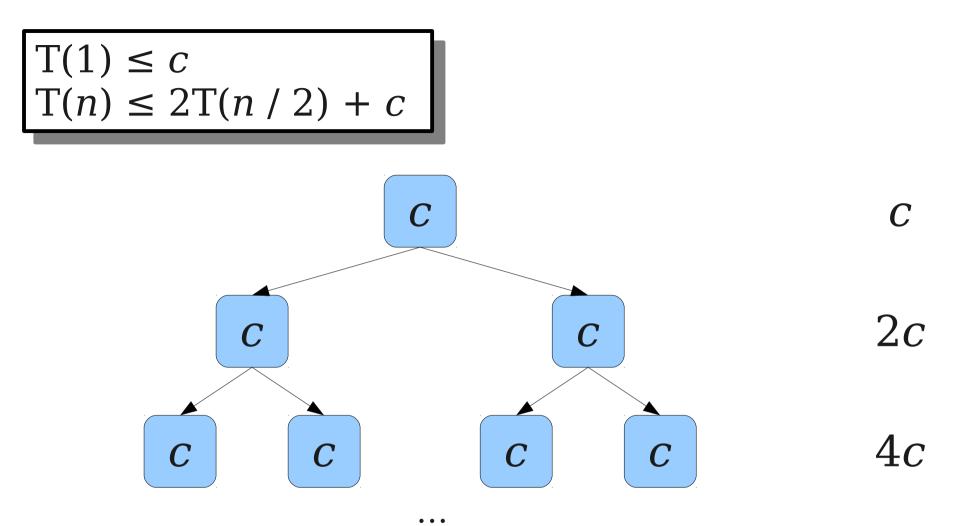
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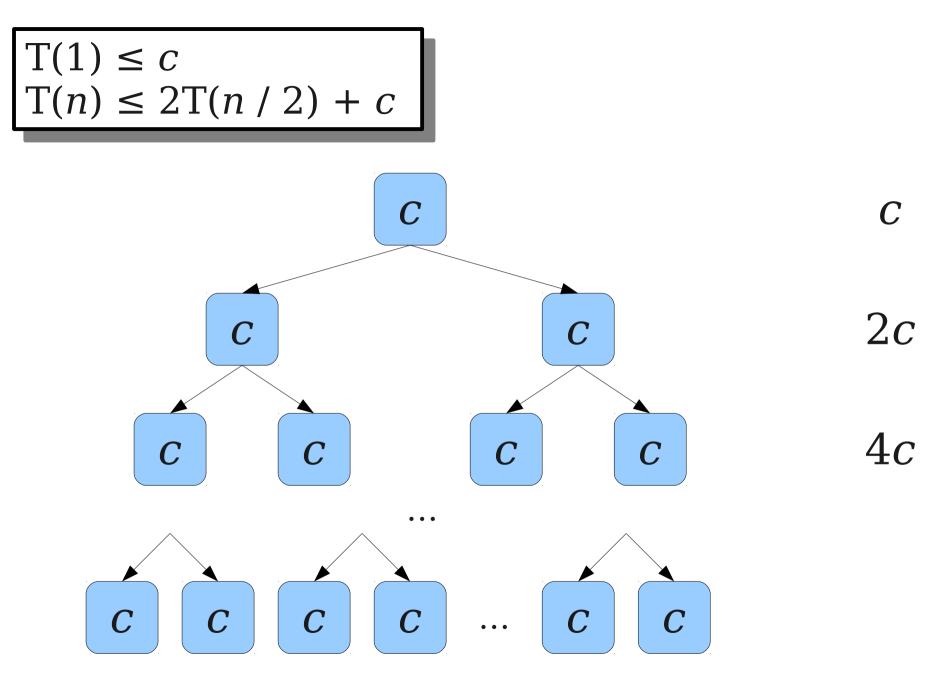


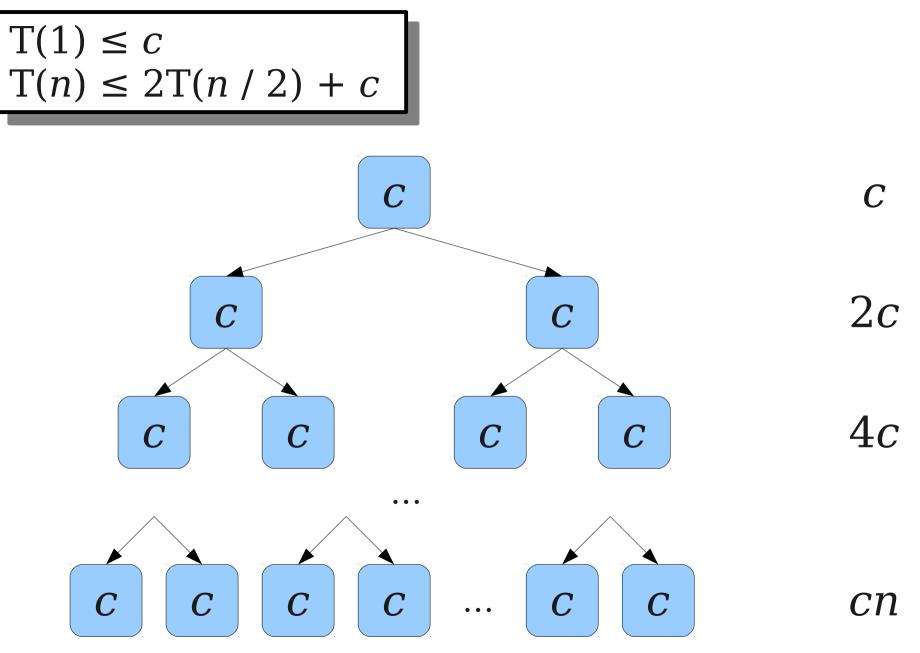


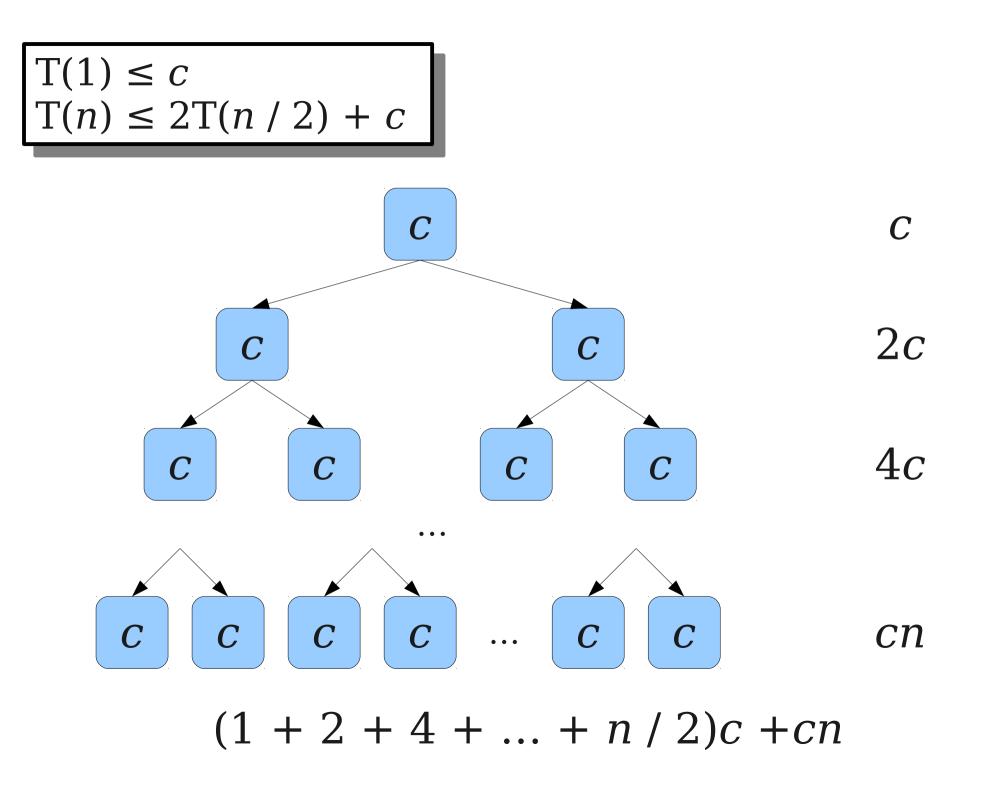
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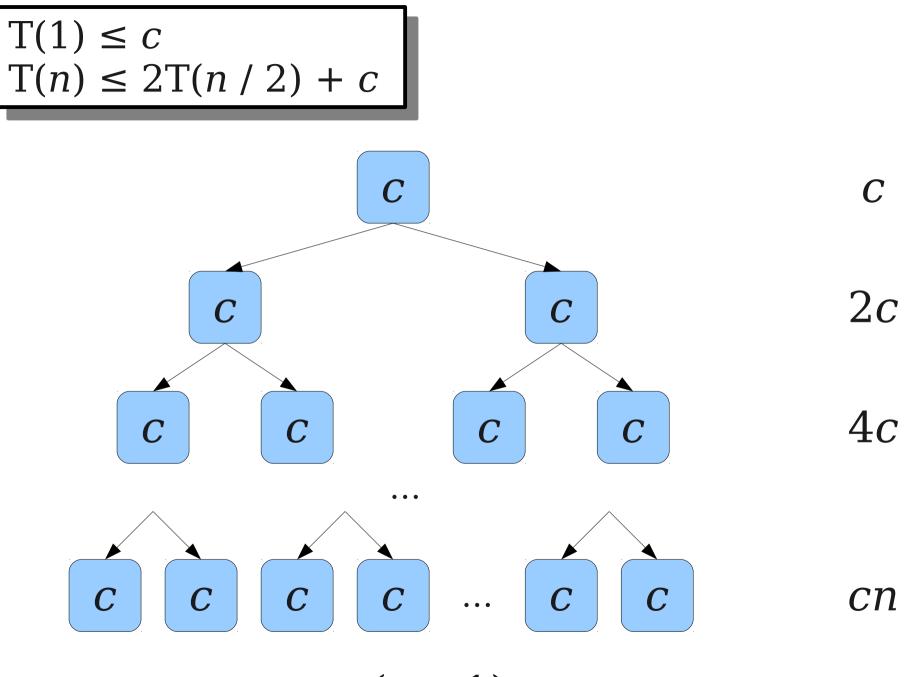




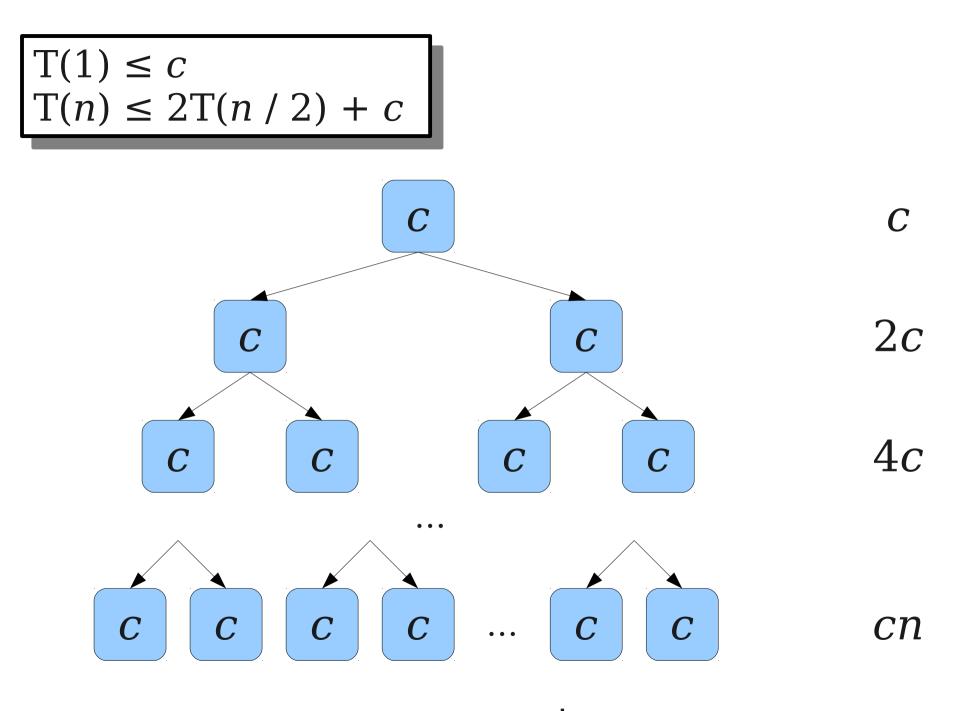




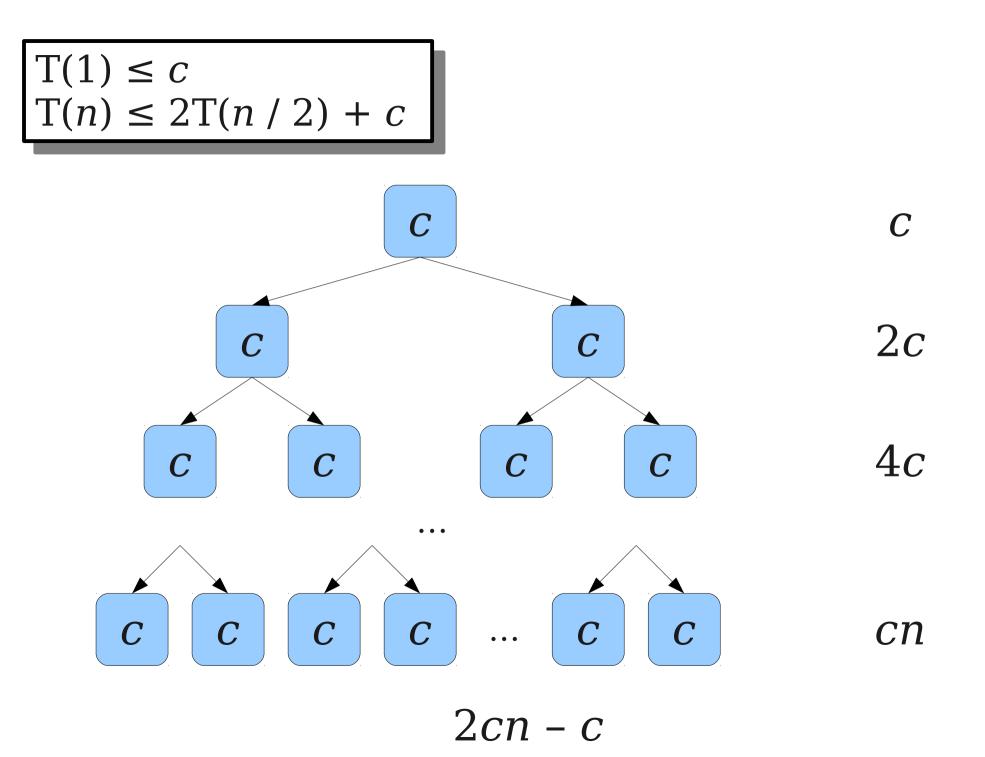




(n - 1)c + cn



cn - c + cn



#### Another Recurrence Relation

• The recurrence relation

 $\begin{array}{l} T(1) = \Theta(1) \\ T(n) \leq T(\lceil n \ / \ 2 \rceil) + T(\lfloor n \ / \ 2 \rfloor) + \Theta(1) \end{array}$ 

#### solves to T(n) = O(n)

• Intuitively, the recursion tree is "bottomheavy:" the bottom of the tree accounts for almost all of the work.

# Unimodal Arrays

- Our recurrence shows that the work done is O(n), but this might not be a tight bound.
- Does our algorithm ever do  $\Omega(n)$  work?
- Yes: What happens if all array values are equal to one another?
- Can we do better?

- Claim: Every correct algorithm for finding the maximum value in a unimodal array must do  $\Omega(n)$  work in the worst-case.
- Note that this claim is over *all possible algorithms*, so the argument had better be watertight!

- We will prove that any algorithm for finding the maximum value of a unimodal array must, on at least one input, inspect all *n* locations.
- *Proof idea*: Suppose that the algorithm didn't do this.

?	?	?	?	?	?	?	?	?	?	?	?	?	?

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# Algorithmic Lower Bounds

- The argument we just saw is called an **adversarial argument** and is often used to establish algorithmic lower bounds.
- Idea: Show that if an algorithm doesn't do enough work, then it cannot distinguish two different inputs that require different outputs.
- Therefore, the algorithm cannot always be correct.

#### o Notation

- Let  $f, g : \mathbb{N} \to \mathbb{N}$ .
- We say that f(n) = o(g(n)) (*f* is *little-o* of *g*) iff  $\lim_{n \to \infty} \frac{f(n)}{g(n)} = 0$
- In other words, *f* grows strictly slower than *g*.
- Often used to describe impossibility results.
- For example: There is no *o*(*n*)-time algorithm for finding the maximum element of a weakly unimodal array.

# What Does This Mean?

- In the worst-case, our algorithm must do  $\Omega(n)$  work.
- That's the same as a linear scan over the input array!
- Is our algorithm even worth it?
- Yes: In most cases, the runtime is  $\Theta(\log n)$  or close to it.

**Binary Heaps** 

### Data Structures Matter

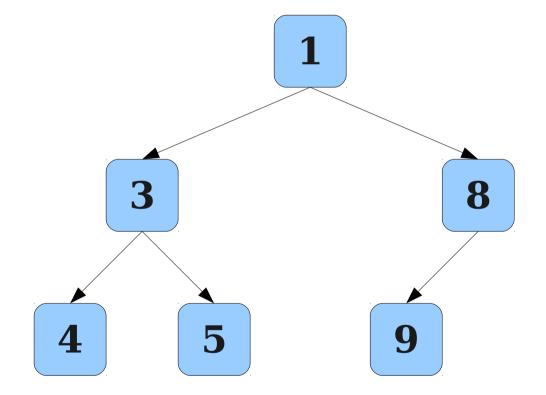
- We have seen two instances where a better choice of data structure improved the runtime of an algorithm:
  - Using adjacency lists instead of adjacency matrices in graph algorithms.
  - Using a double-ended queue in 0/1 Dijkstra's algorithm.
- Today, we'll explore a data structure that is useful for improving algorithmic efficiency.
- We'll come back to this structure in a few weeks when talking about Prim's algorithm and Kruskal's algorithm.

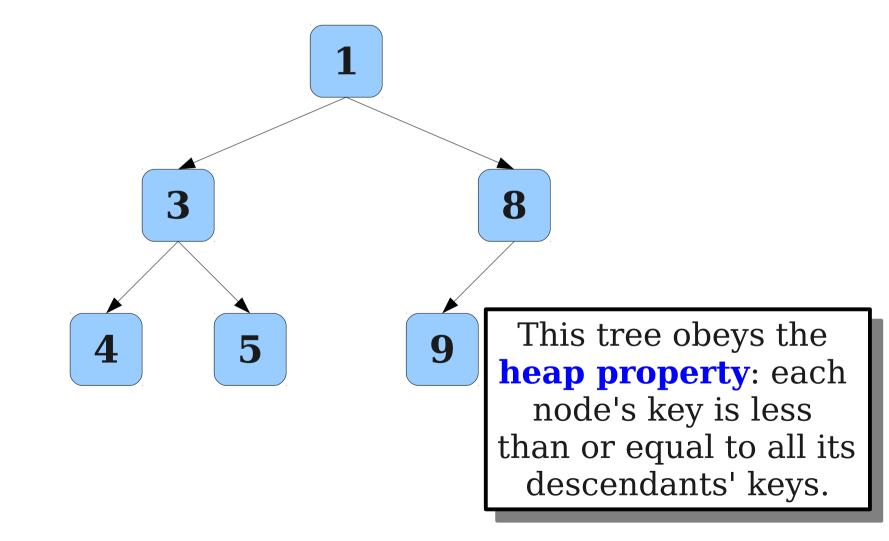
# Priority Queues

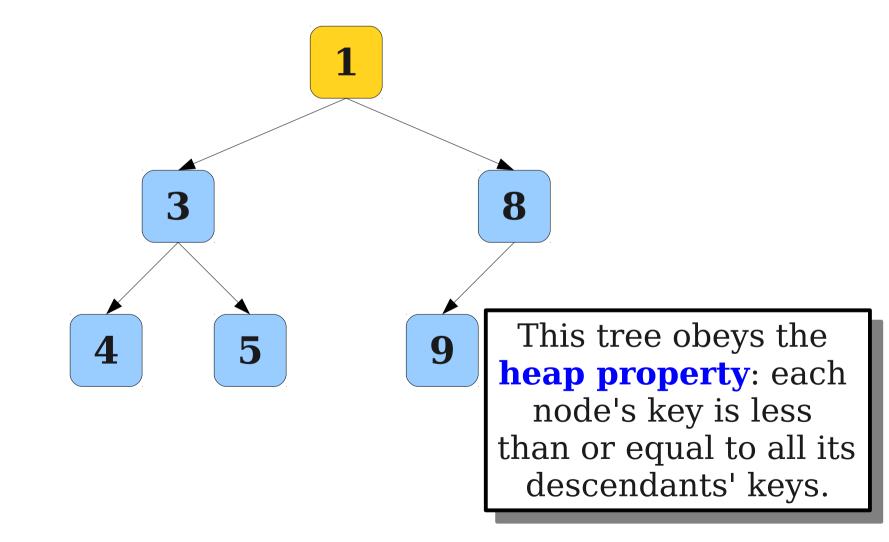
- A **priority queue** is a data structure for storing elements associated with *priorities* (often called **keys**).
- Optimized to find the element that currently has the smallest key.
- Supports the following operations:
  - enqueue(k, v) which adds element v to the queue with key k.
  - **is-empty**, which returns whether the queue is empty.
  - **dequeue-min**, which removes the element with the least priority from the queue.
- Many implementations are possible with varying tradeoffs.

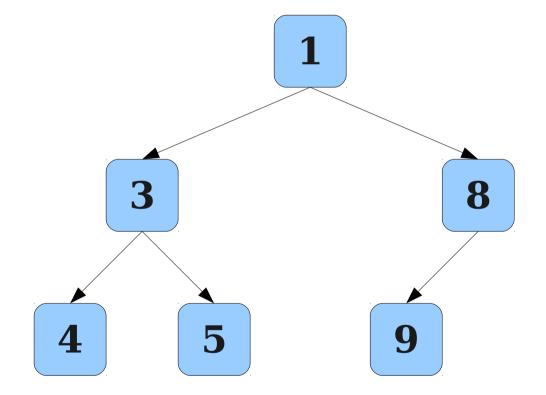
# A Naive Implementation

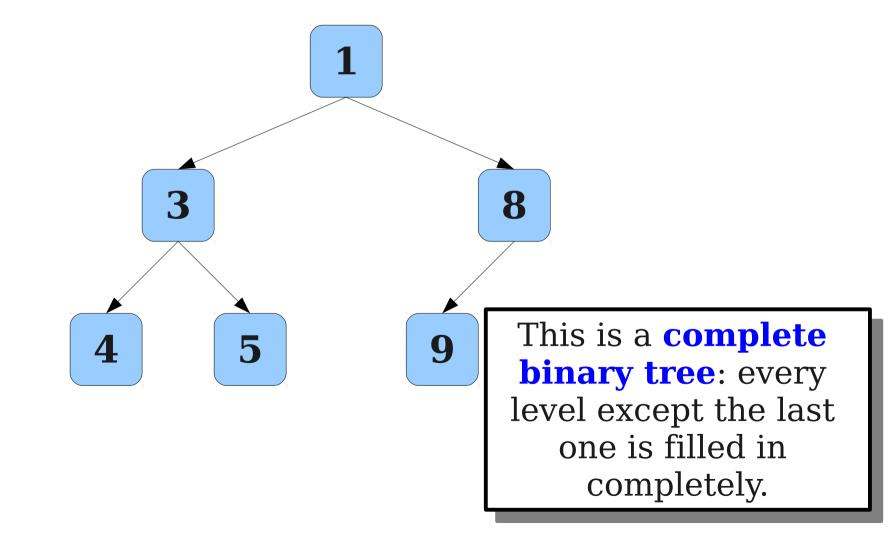
- One simple way to implement a priority queue is with an unsorted array key/value pairs.
- To enqueue v with key k, append (k, v) to the array in time O(1).
- To check whether the priority queue is empty, check whether the underlying array is empty in time O(1).
- To dequeue-min, scan across the array to find an element with minimum key, then remove it in time O(n).
- Doing *n* enqueues and *n* dequeues takes time  $O(n^2)$ .

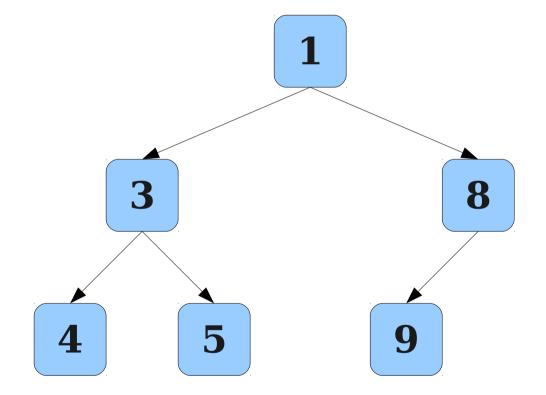


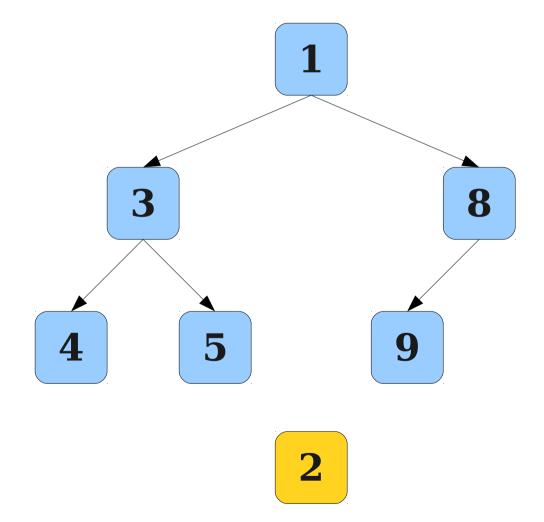


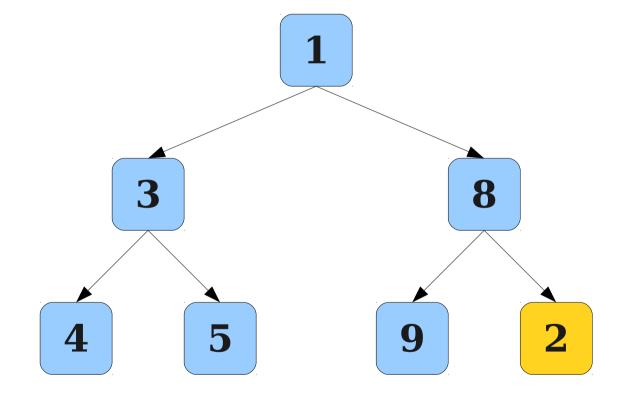


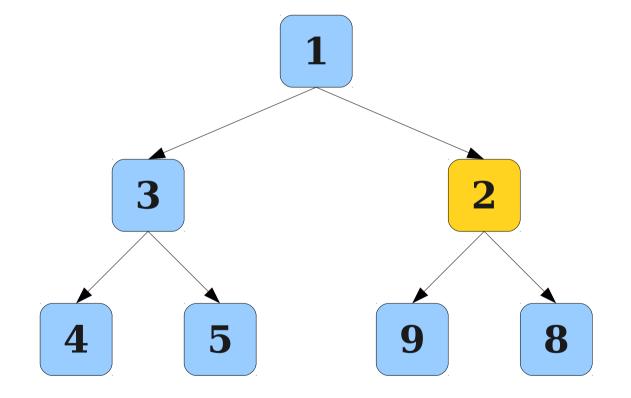


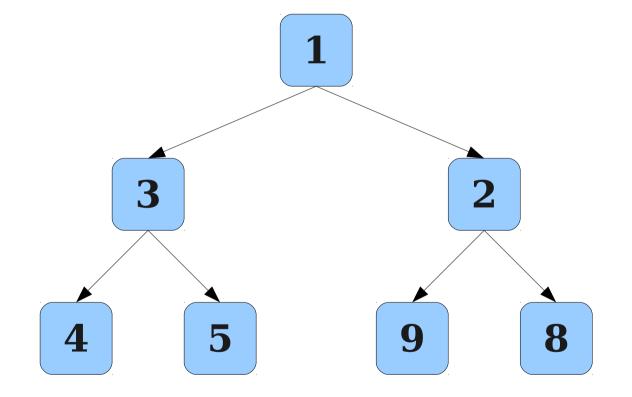


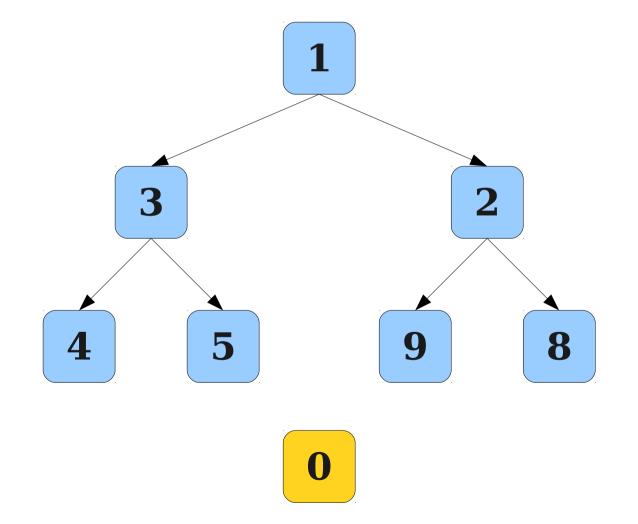


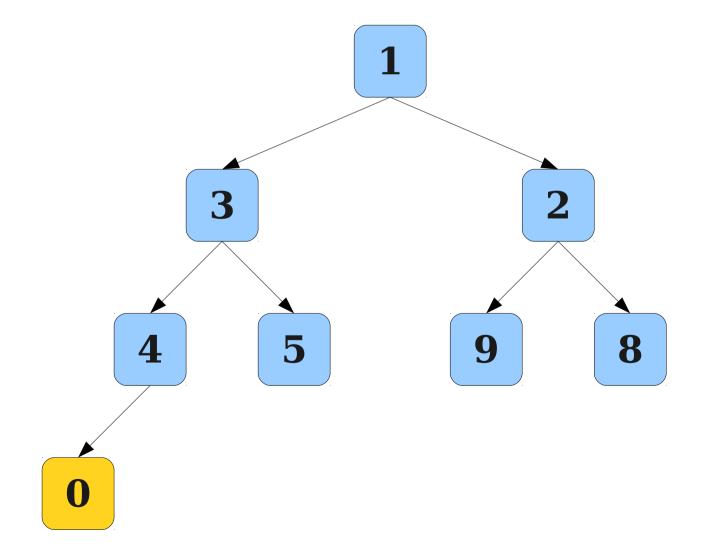


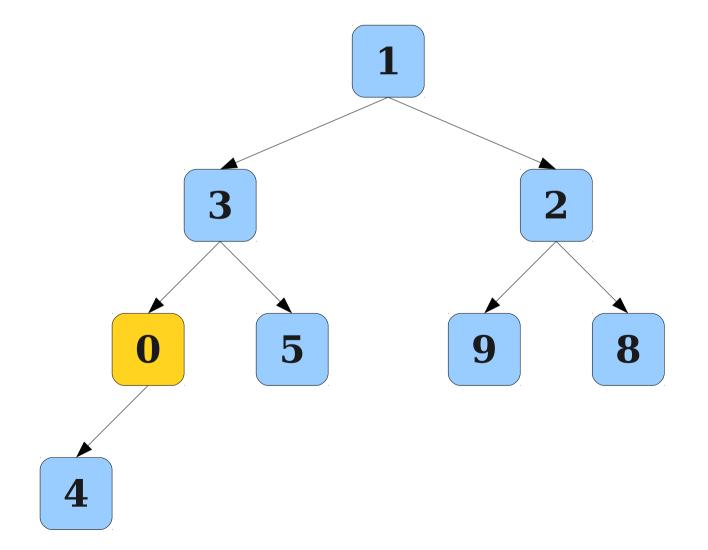


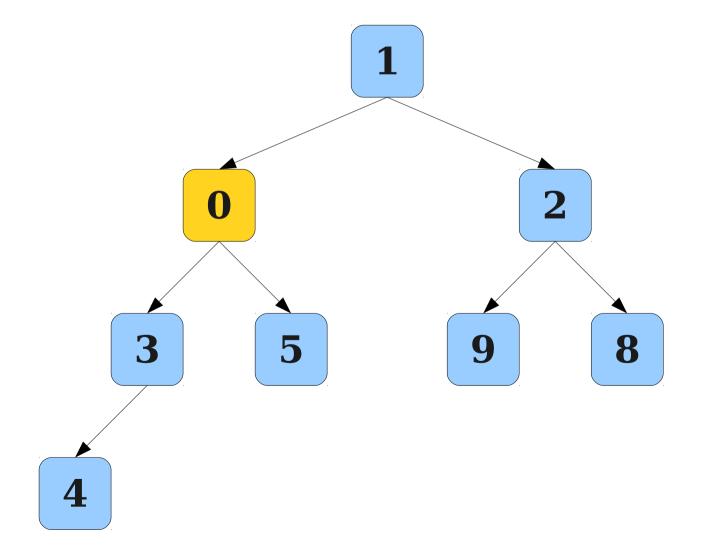


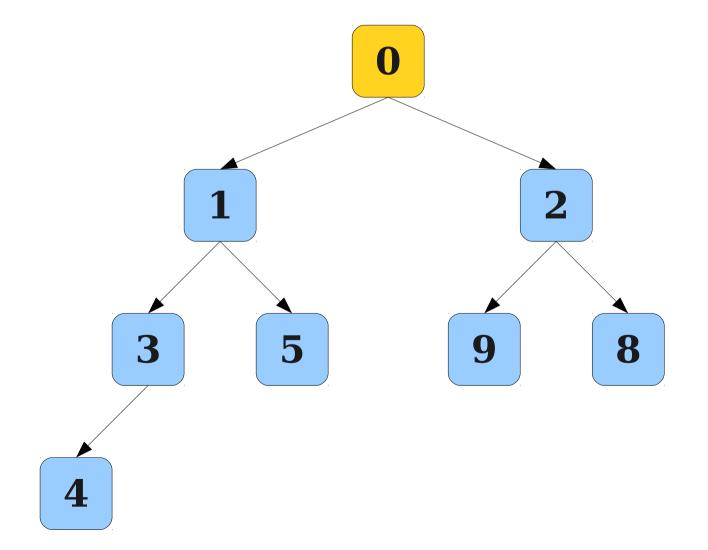


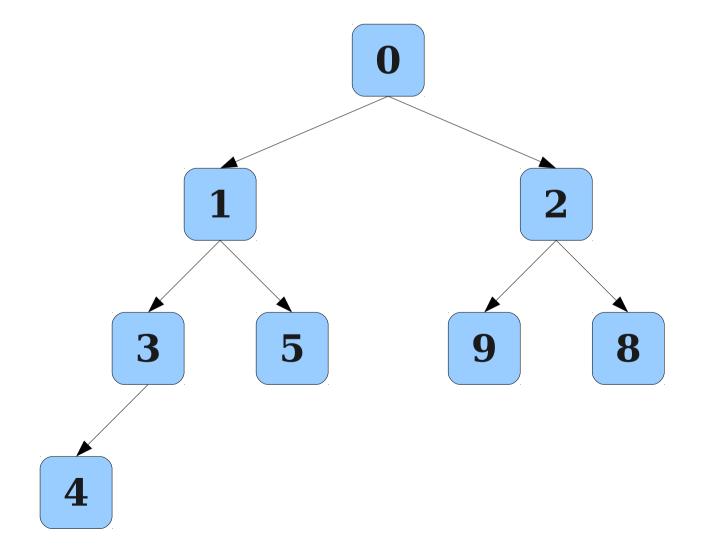


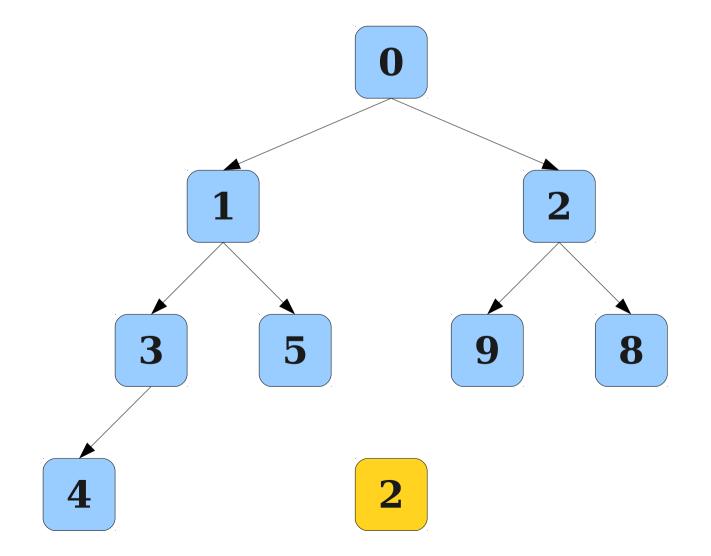


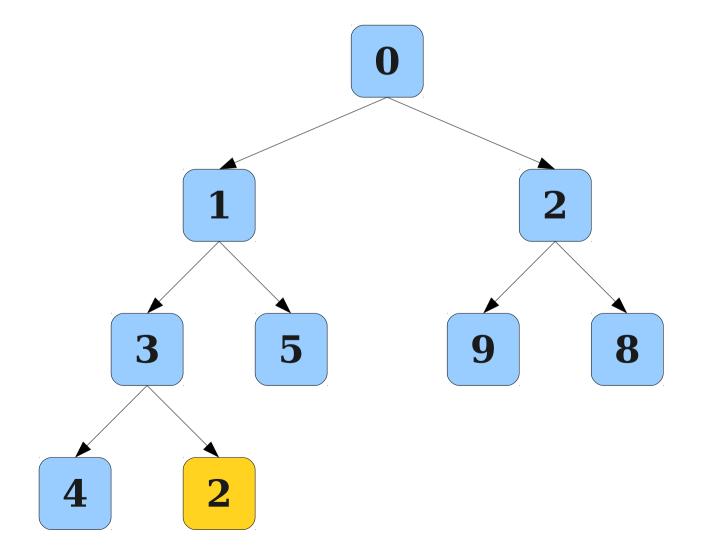


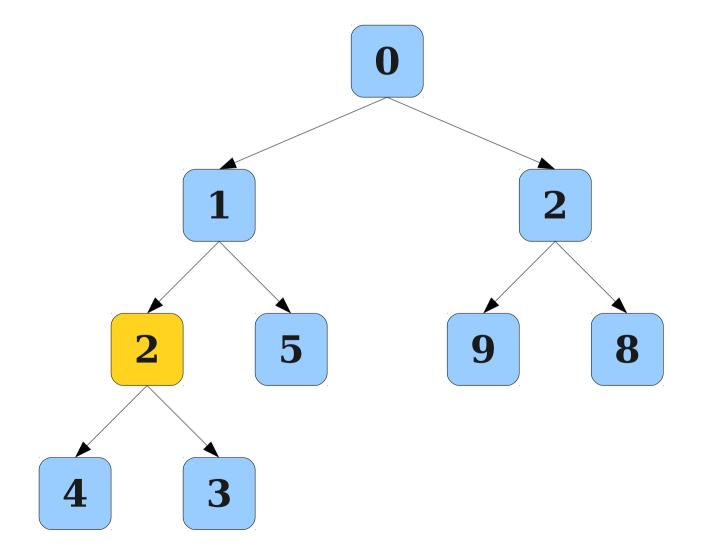


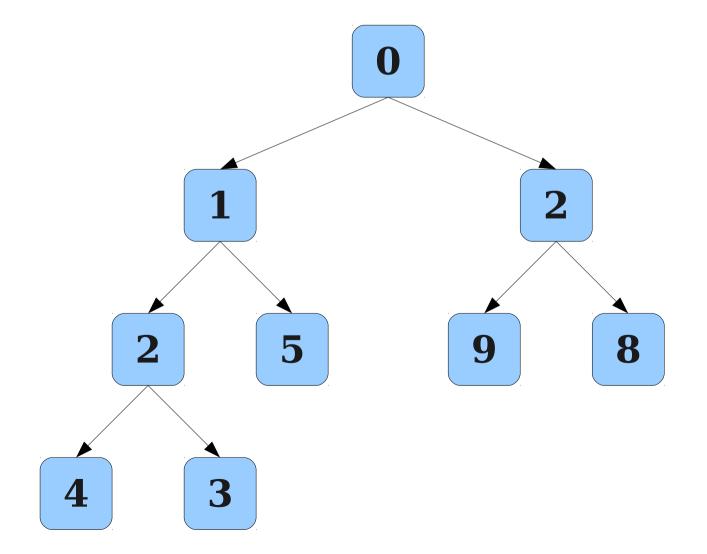


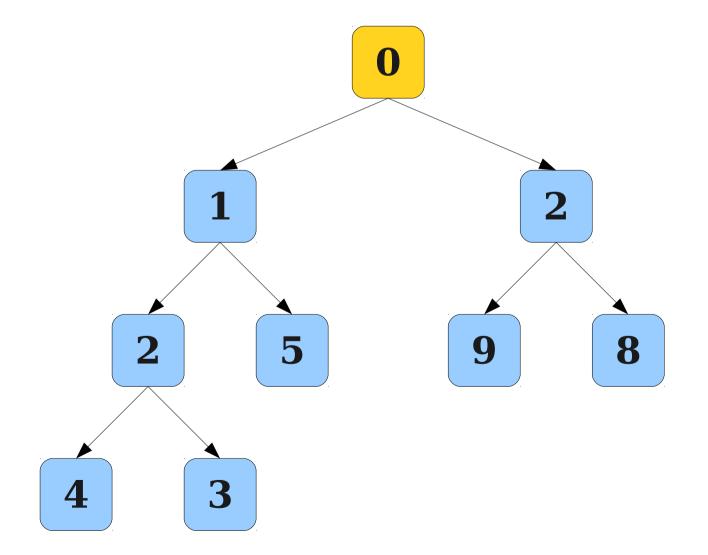




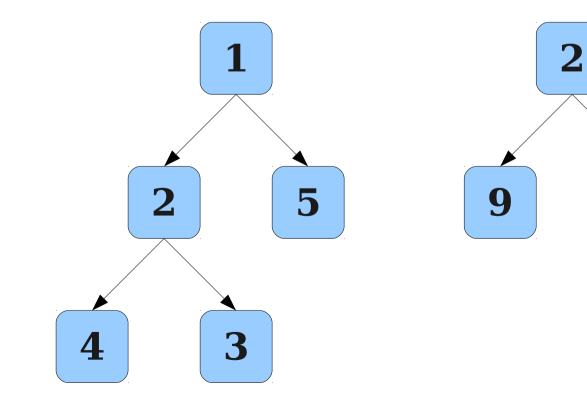


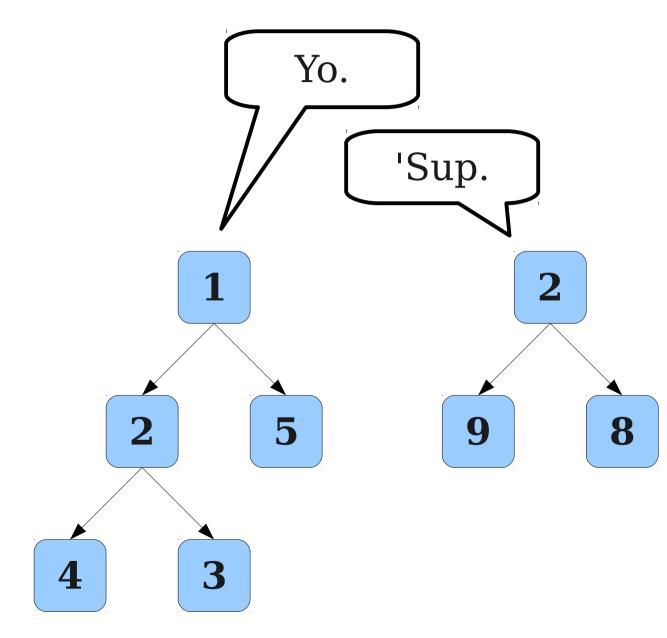




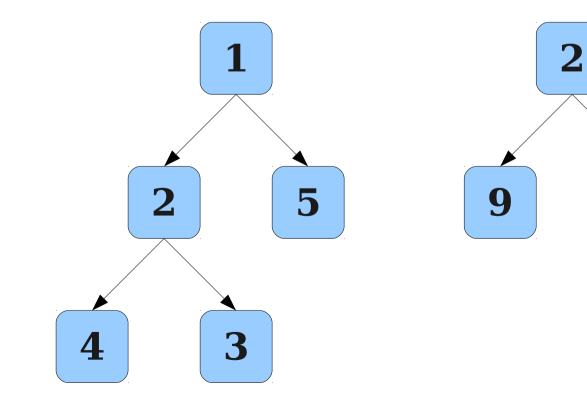


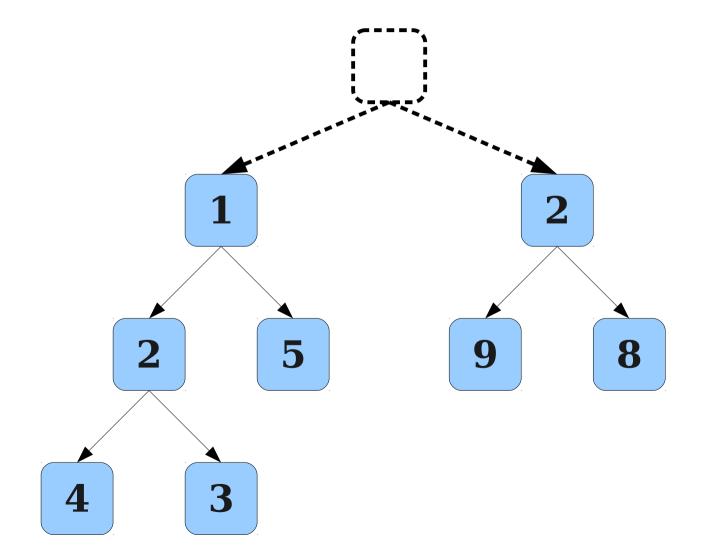
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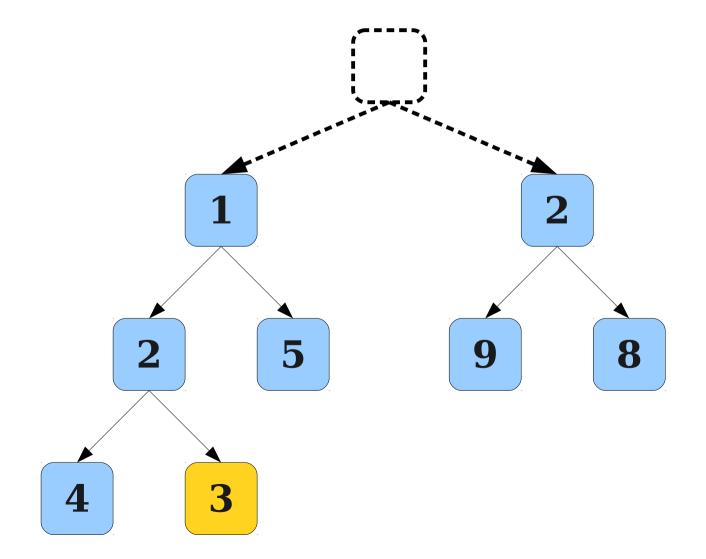


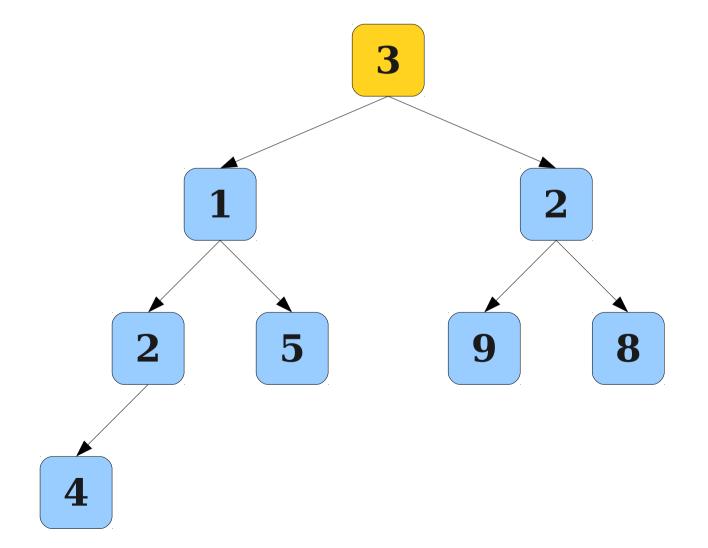


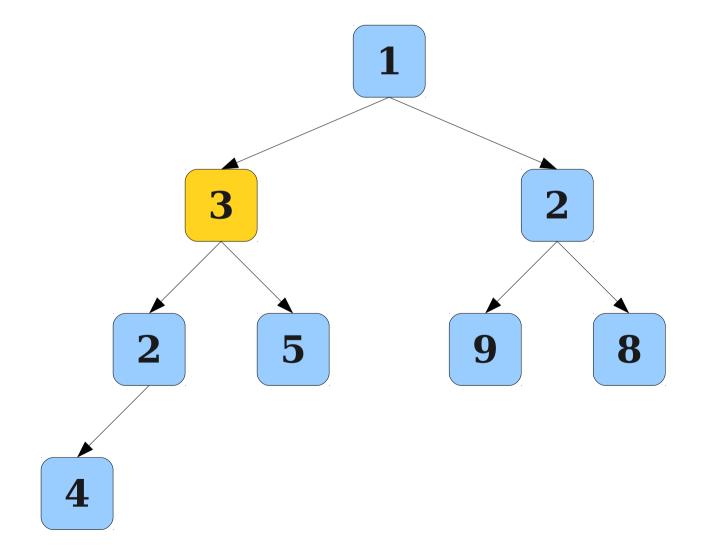
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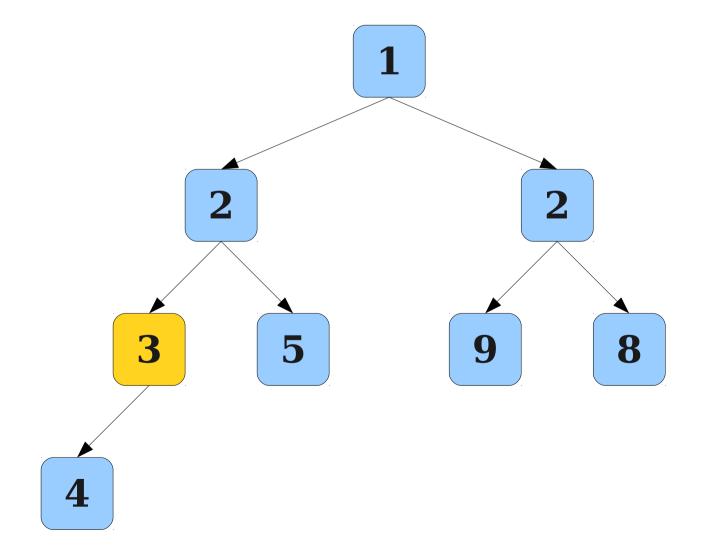


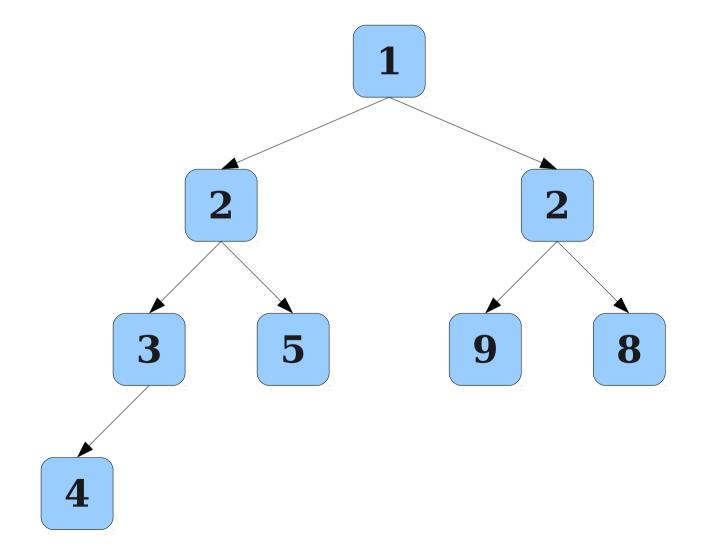








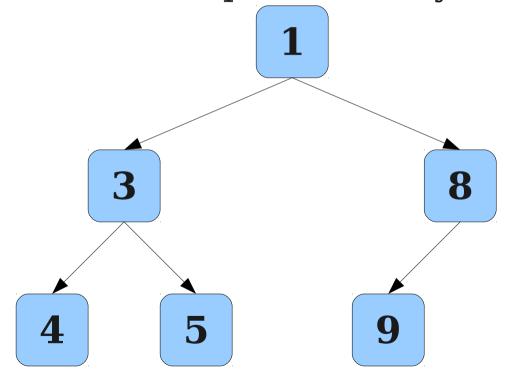




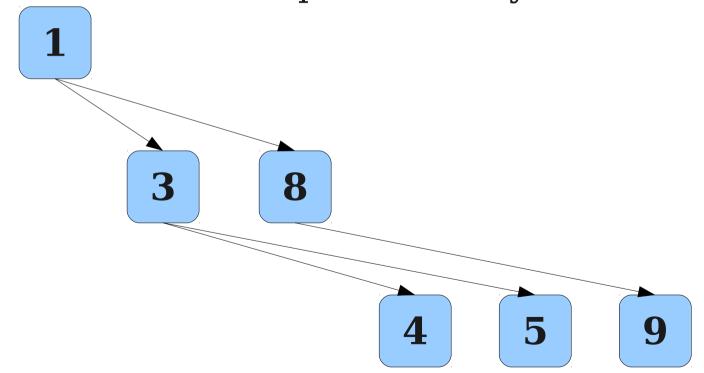
### Binary Heap Efficiency

- The enqueue and dequeue operations on a binary heap all run O(*h*), where *h* is the height of the tree.
- In a perfect binary tree of height h, there are  $1 + 2 + 4 + 8 + \ldots + 2^h = 2^{h+1} 1$  nodes.
- If there are *n* nodes, the maximum height would be found by setting  $n = 2^{h+1} 1$ .
- Solving, we get that  $h = \log_2 (n + 1) 1$
- Thus  $h = \Theta(\log n)$ , so enqueue and dequeue take time  $O(\log n)$ .

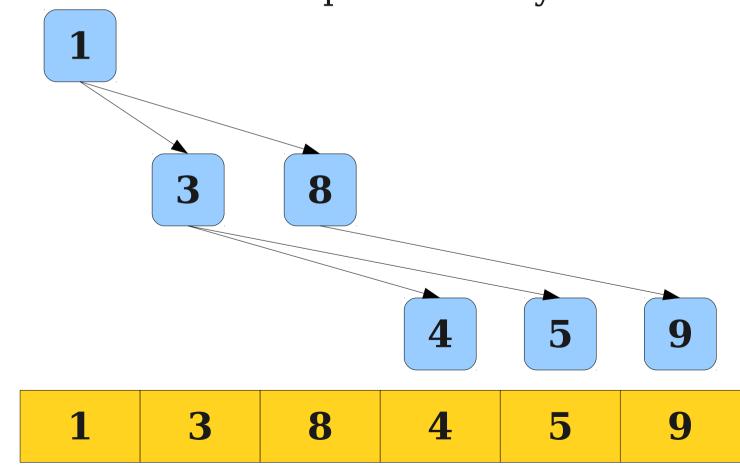
- It is extremely rare to actually implement a binary heap as a tree structure.
- Can encode the heap as an array:



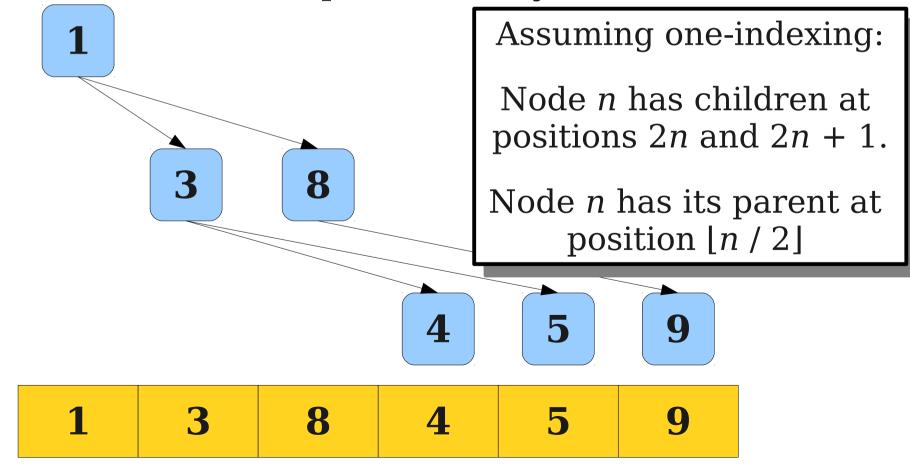
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- Can encode the heap as an array:



Application: **Heapsort** 

3	1	4	0	5	9	2

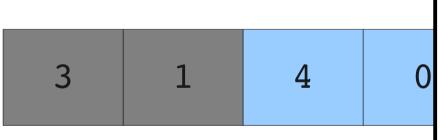
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3 1 4 0 5 9 2
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3 1 4 0 5 9 2
---------------

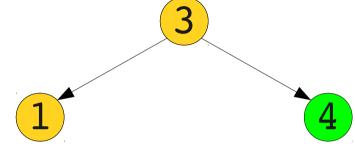
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3



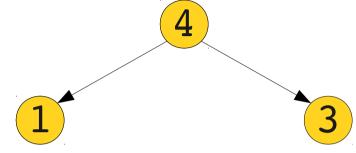
This is a **max-heap** (where *larger* values are on top), as opposed to a **min-heap** (where *smaller* values are on top). We'll see why in a minute.

3 1 4 0 5 9 2
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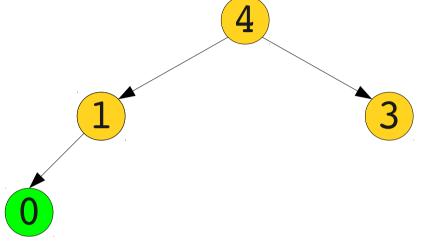


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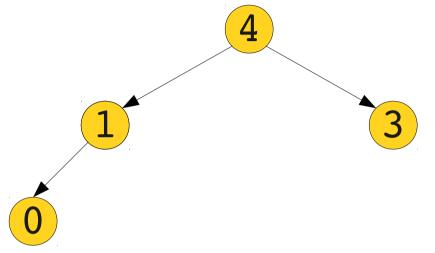
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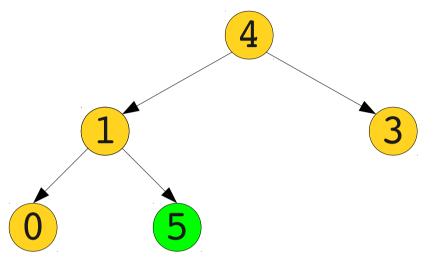
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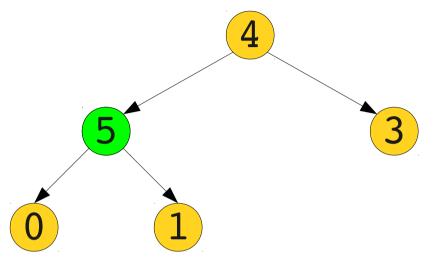
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3	1	4	0	5	9	2

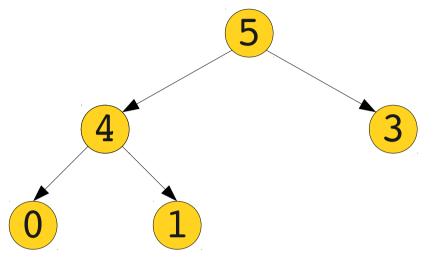


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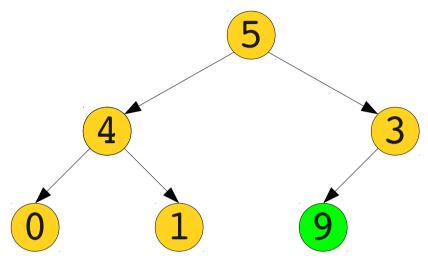


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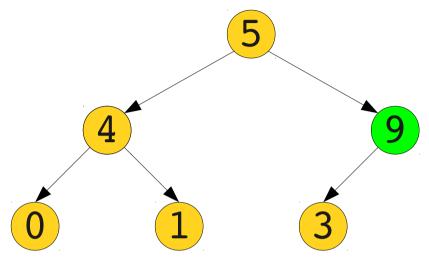
3 1 4 0 5 9 2
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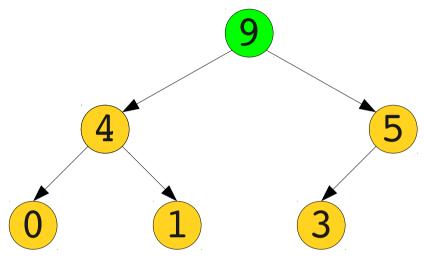
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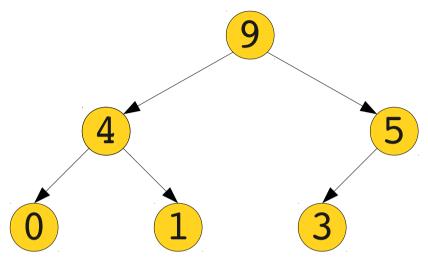
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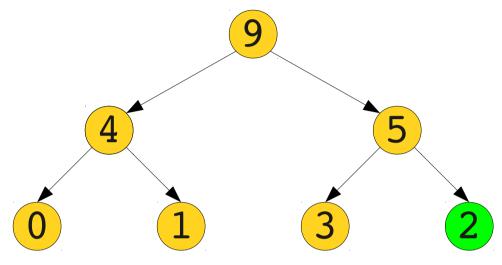
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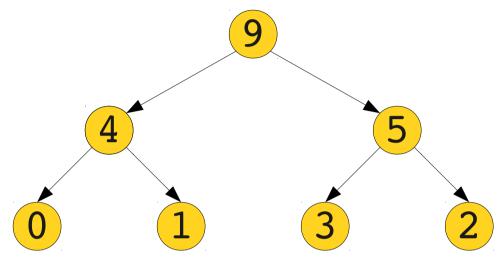
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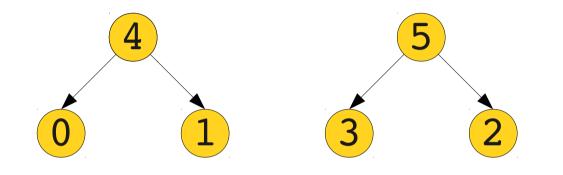
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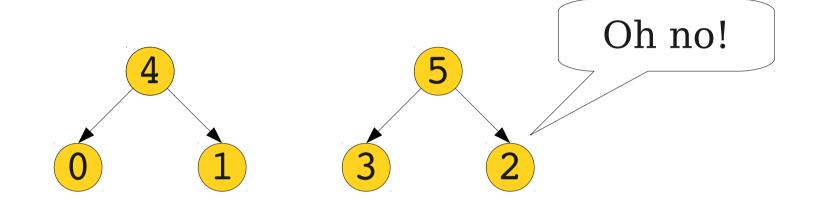
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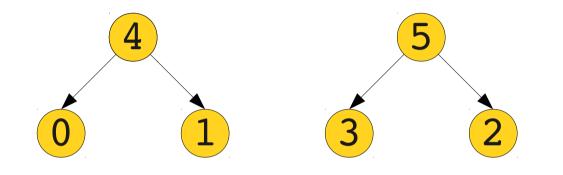
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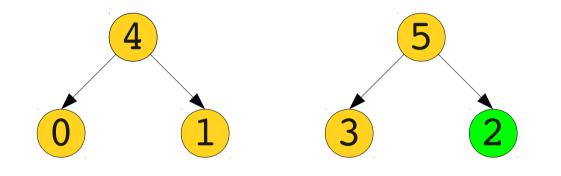
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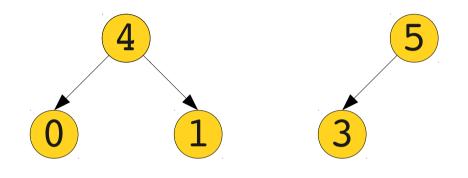
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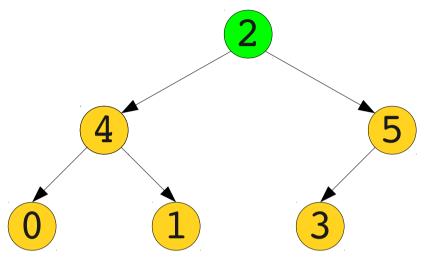
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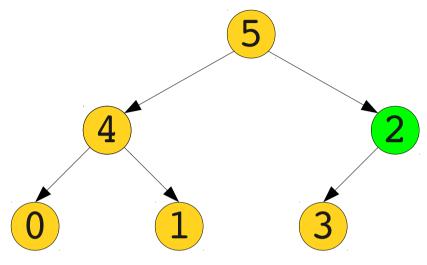
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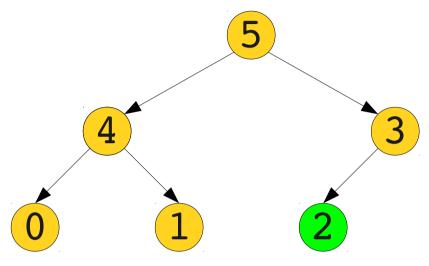
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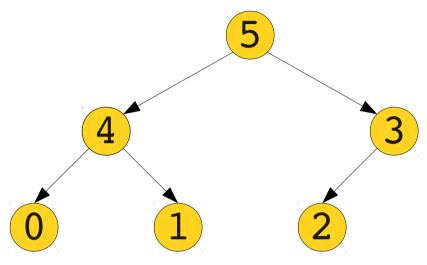
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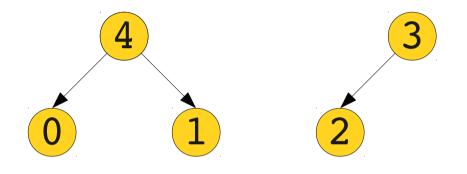
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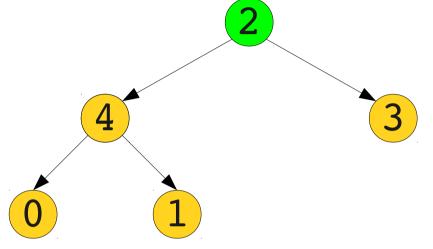
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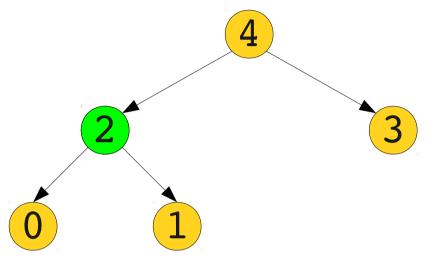
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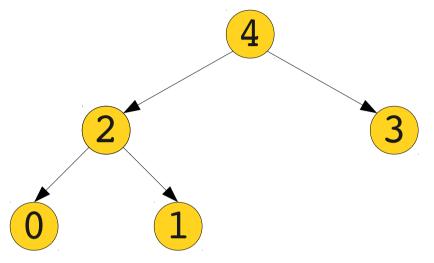
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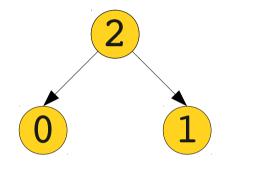
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3	1	4	0	5	5	9



3	1	4	0	5	5	9



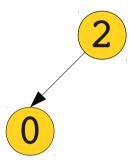


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3	1	4	0	4	5	9

3 1 4 0 4 5 9
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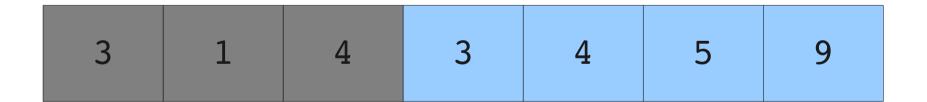
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3 1 4 3 4 5 9
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4 3 4 5 9	4	1	3
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3 1 2 3 4 5 9
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3 1 2 3 4 5 9
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3 1 2 3 4 5 9
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3 1 2 3 4 5 9
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3 1 2 3 4 5 9
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2 3 4 5 9	0 1 2	0	0 1 2	3 4	5	9
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#### A Better Idea

3	1	4	0	5	9	2

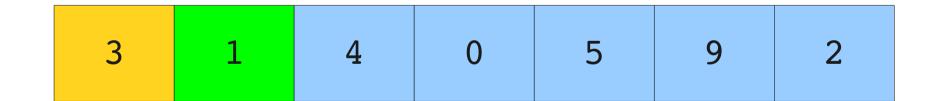
### A Better Idea

3 1 4 0 5 9 2
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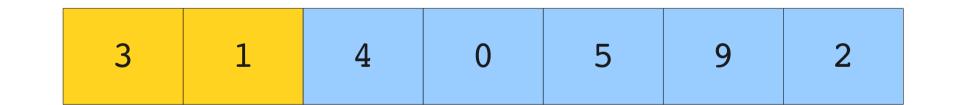


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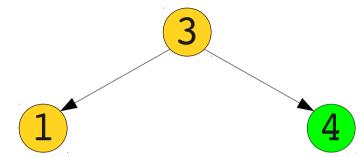




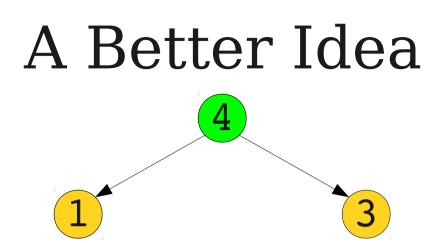






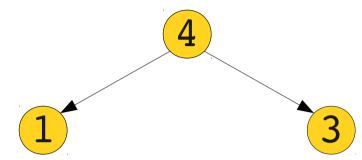


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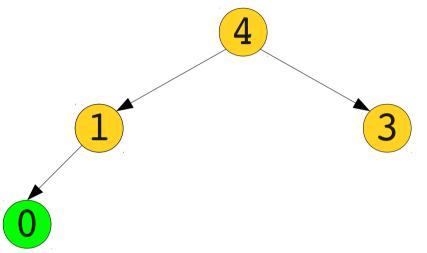
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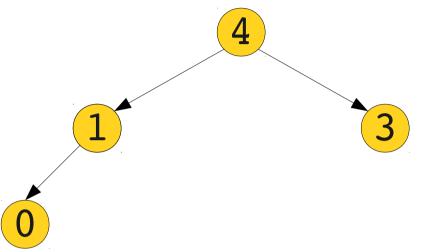
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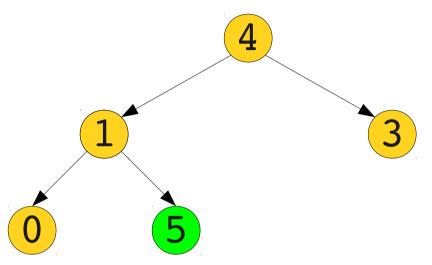


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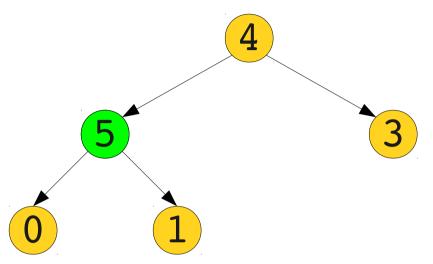




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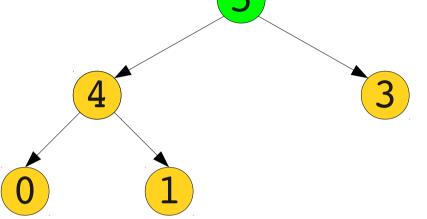


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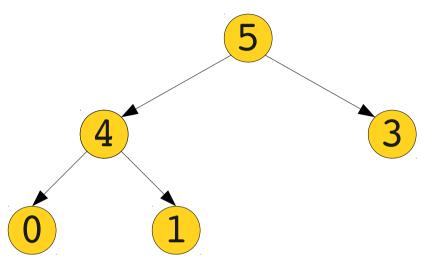


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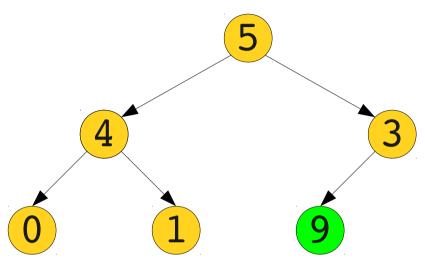


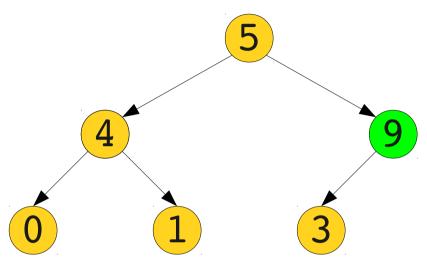


<b>5</b> 4 3 0 1 9 2
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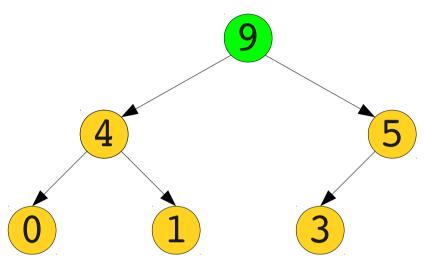


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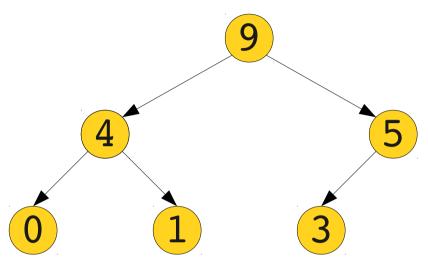




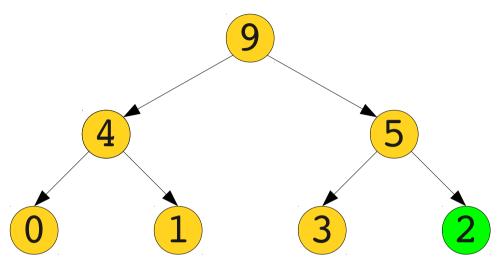
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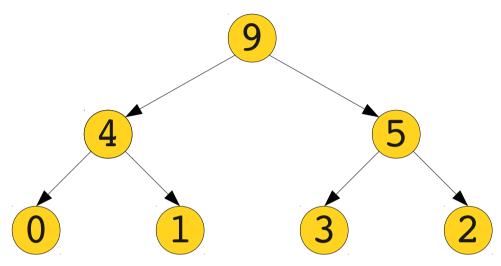
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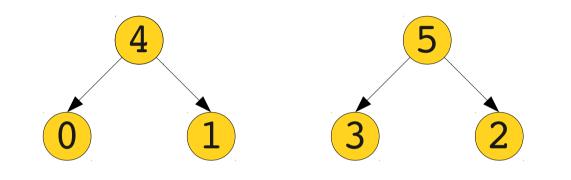
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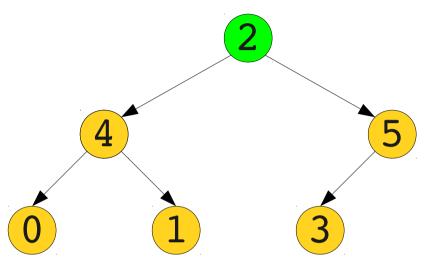
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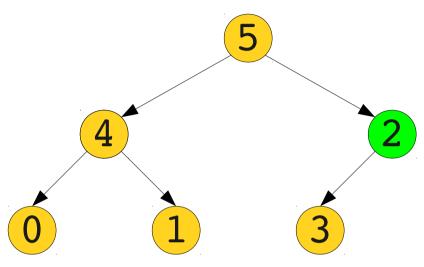


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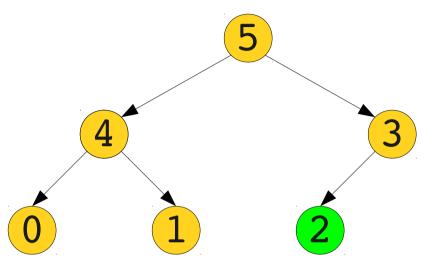


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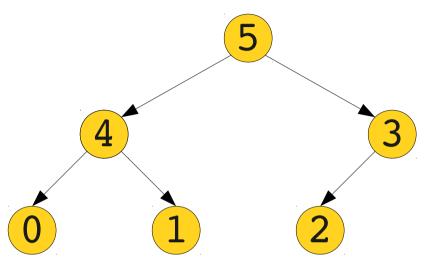




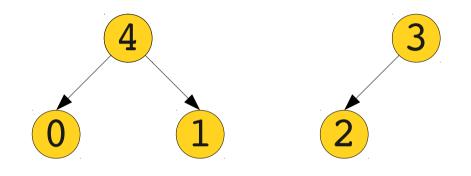
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5	4	3	0	1	2	9

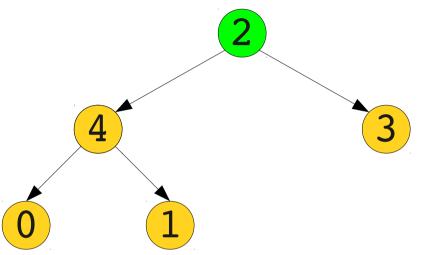


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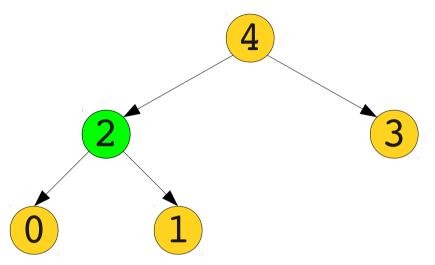


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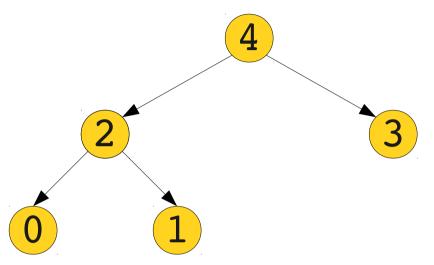




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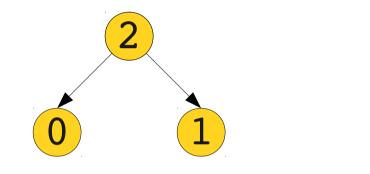


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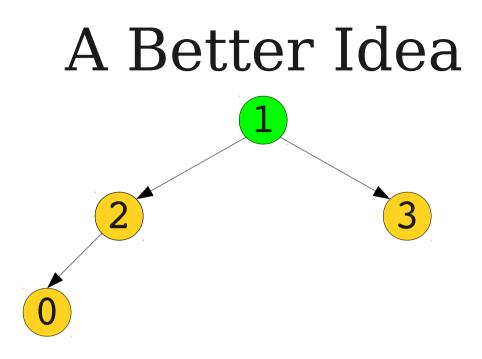


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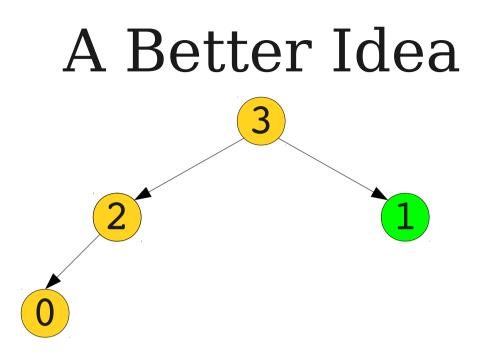
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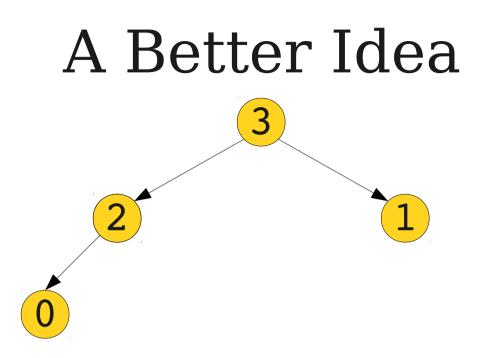
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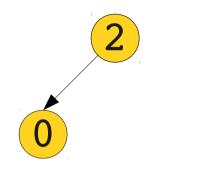
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3 2 1 0 4 5 9
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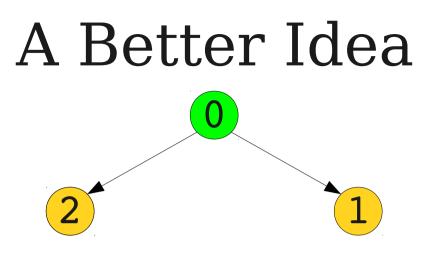


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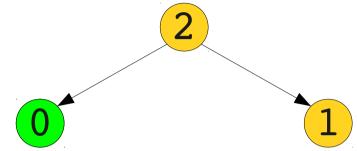


3	2	1	0	4	5	9



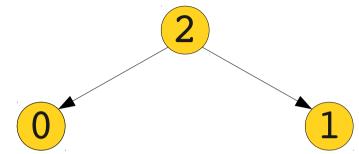
0 2 1 3 4 5 9
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2 0 1 3 4 5 9
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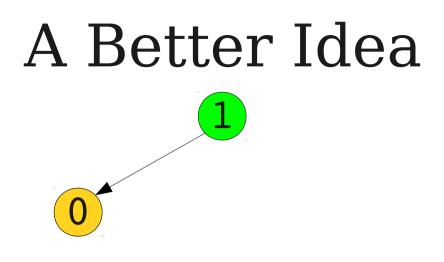


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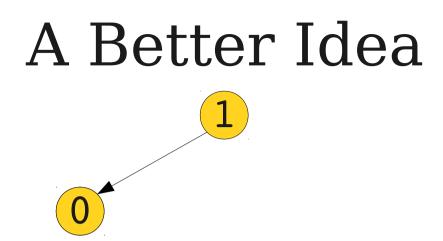




2 0 1 3 4 5 9
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1 0 2 3 4 5 9
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1 0 2 3 4 5 9
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0 1 2 3 4 5 9
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0 1 2 3 4 5 9
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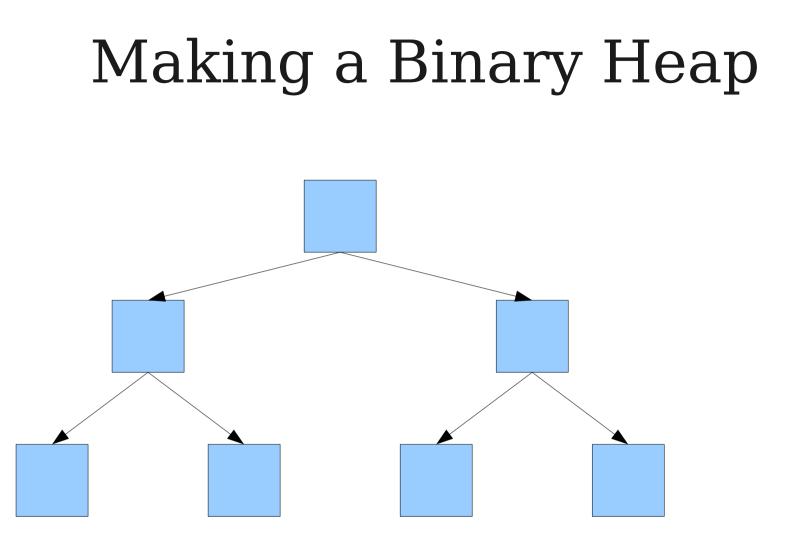
#### Heapsort

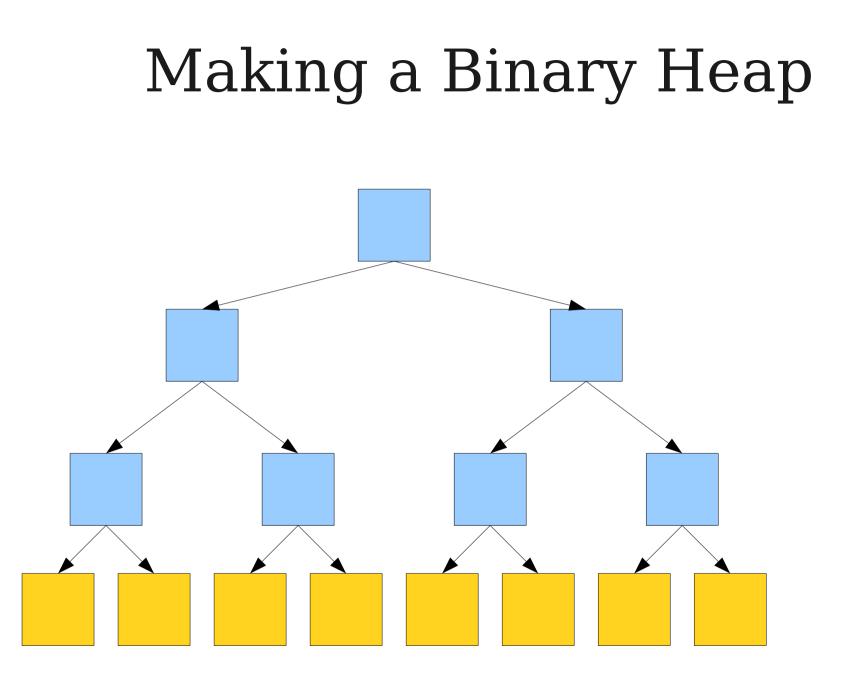
- The **heapsort** algorithm is as follows:
  - Build a max-heap from the array elements, using the array itself to represent the heap.
  - Repeatedly dequeue from the heap until all elements are placed in sorted order.
- This algorithm runs in time O(n log n), since it does n enqueues and n dequeues.
- Only requires O(1) auxiliary storage space, compared with O(*n*) space required in mergesort.

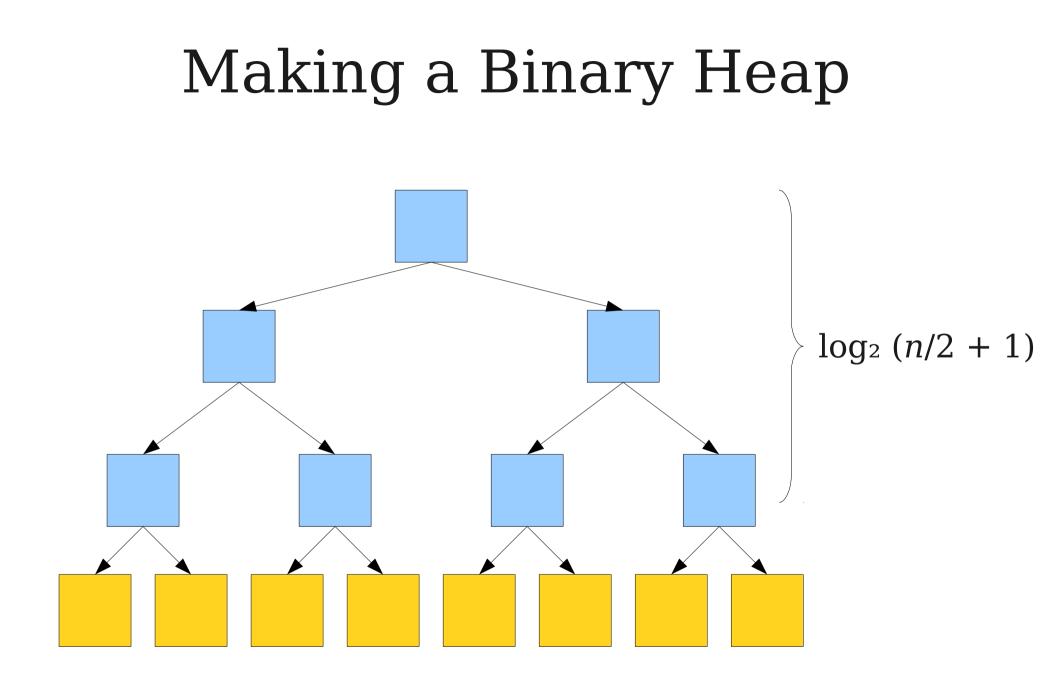
#### An Optimization: **Heapify**

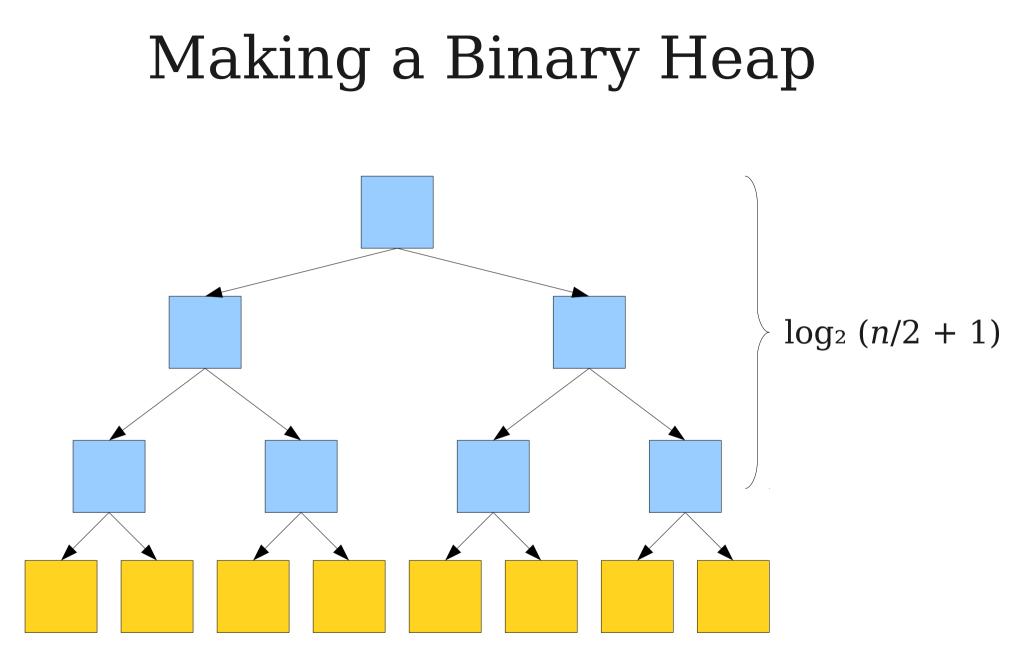
#### Making a Binary Heap

- Suppose that you have *n* elements and want to build a binary heap from them.
- One way to do this is to enqueue all of them, one after another, into the binary heap.
- We can upper-bound the runtime as n calls to an O(log n) operation, giving a total runtime of O(n log n).
- Is that a tight bound?



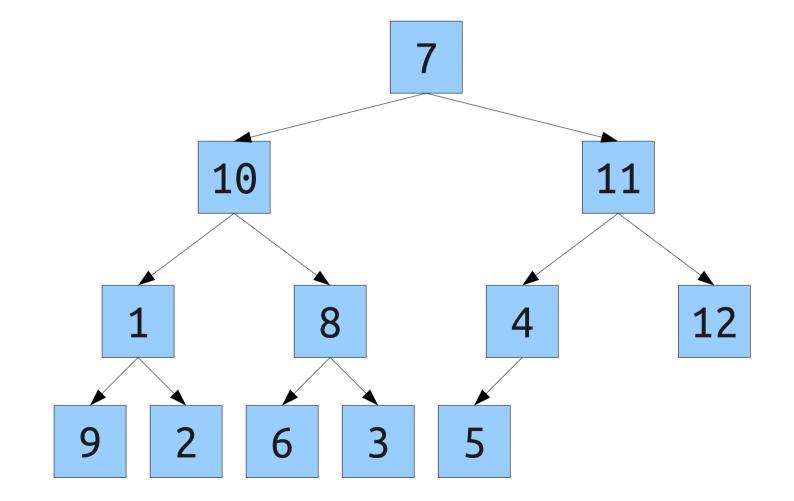


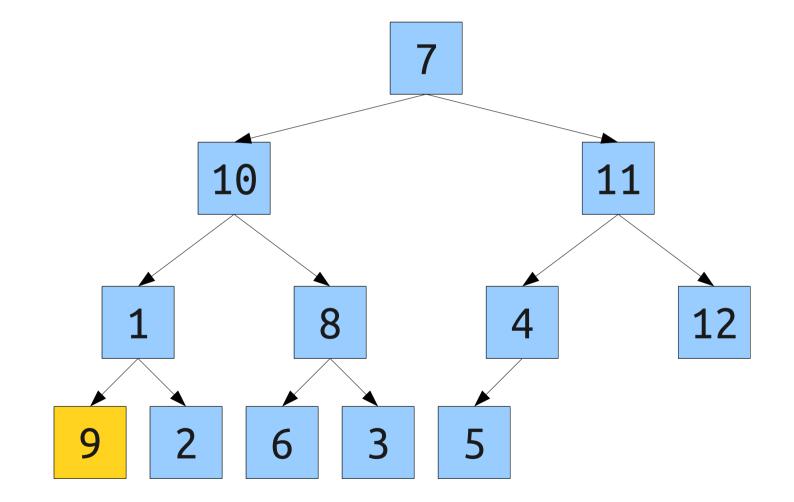


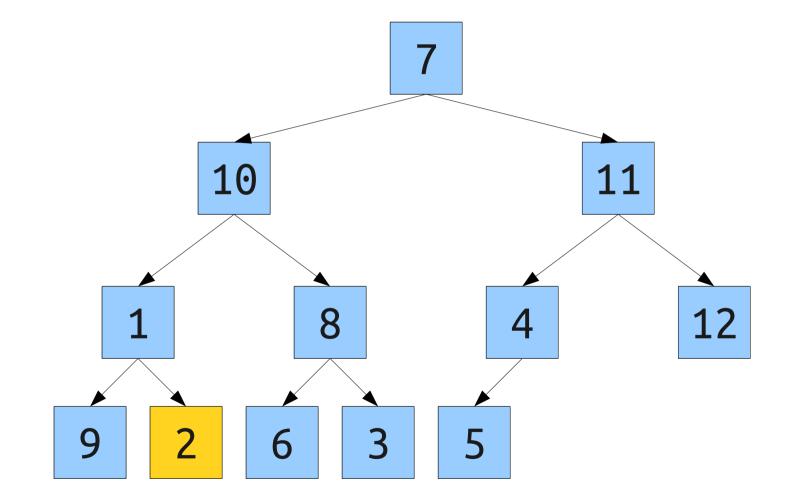


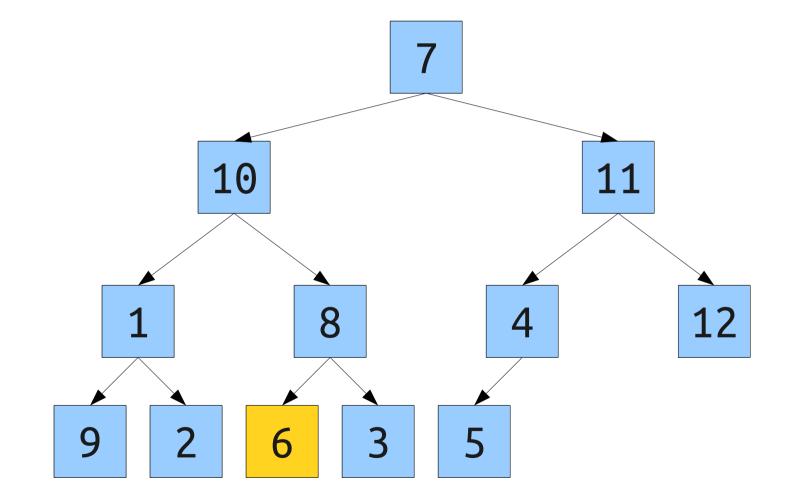
Total Runtime:  $\Theta(n \log n)$ 

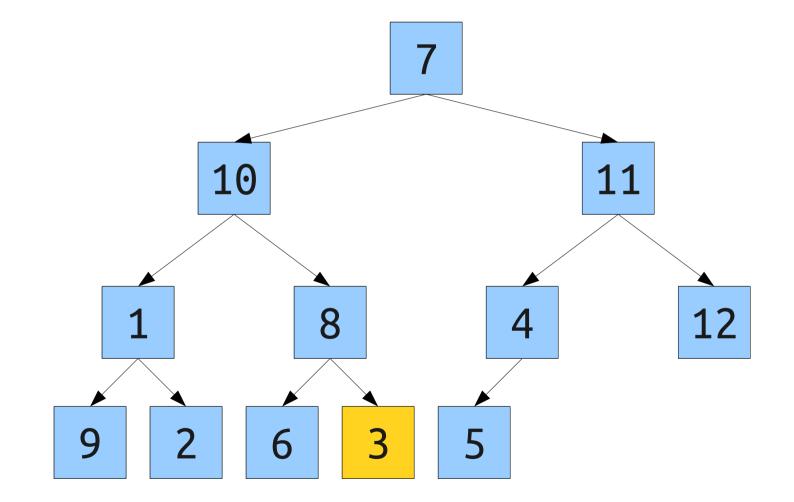
- Here is a slightly different algorithm for building a binary heap out of a set of data:
  - Put the nodes, in any order, into a complete binary tree of the right size. (Shape property holds, but heap property might not.)
  - For each node, starting at the bottom layer and going upward, run a bubble-down step on that node.

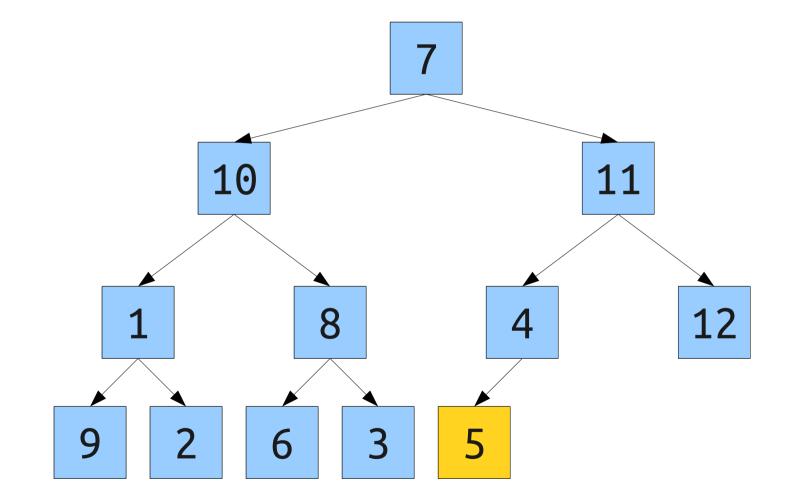


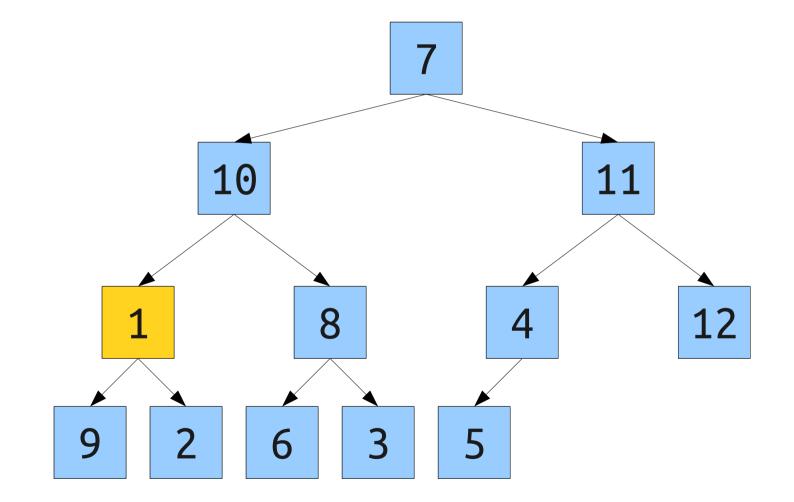


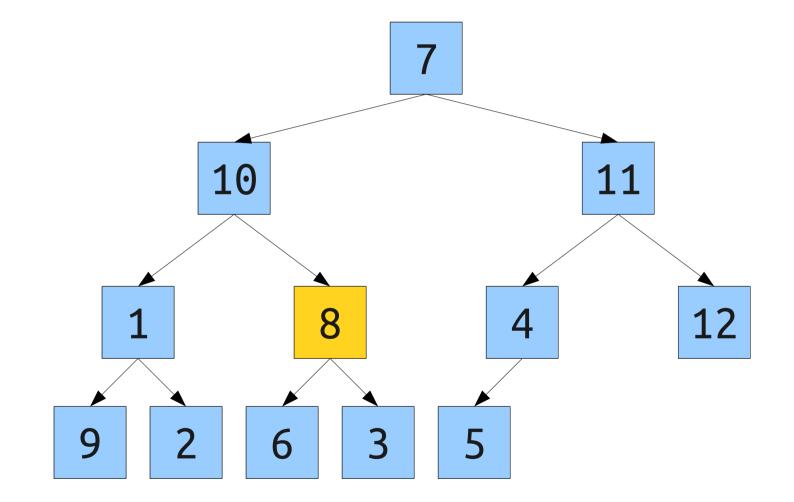


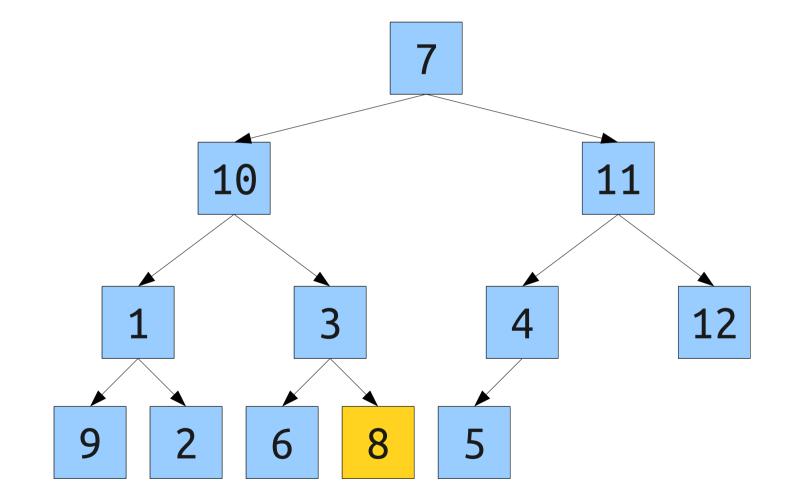


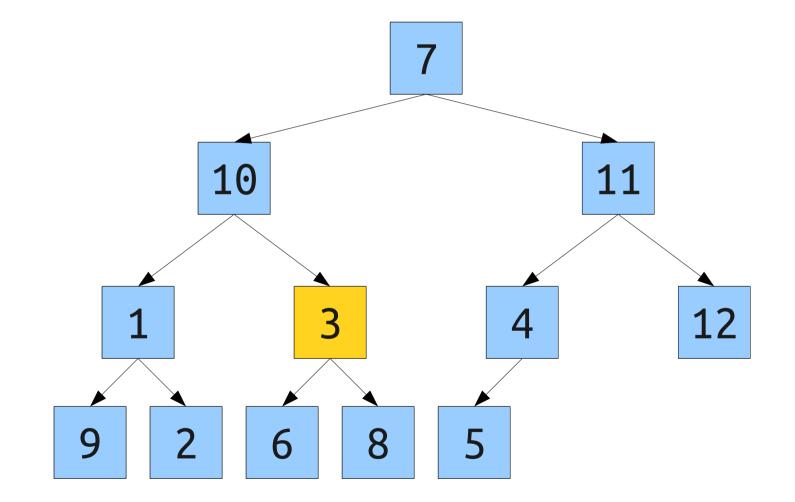


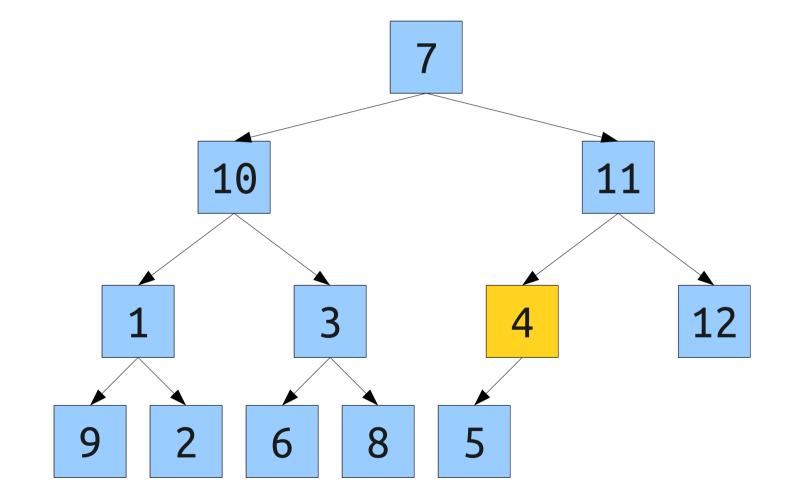


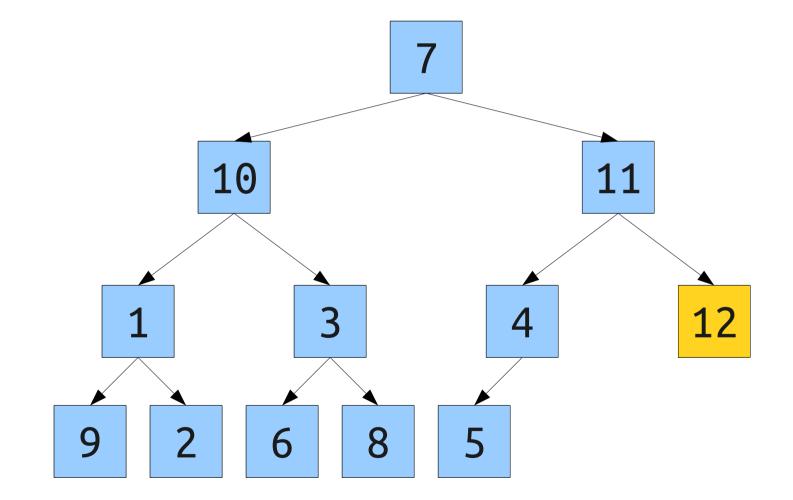


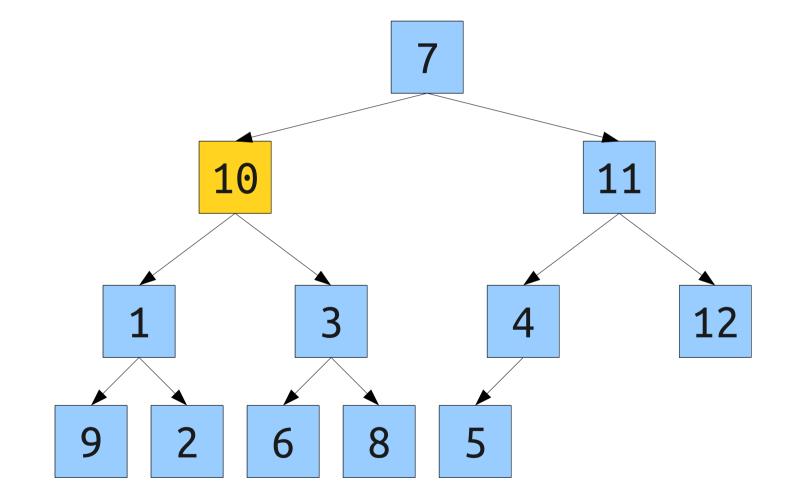


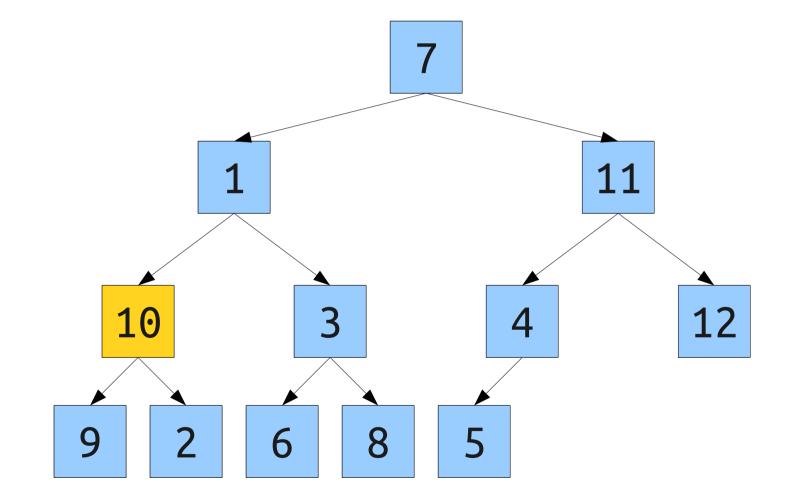


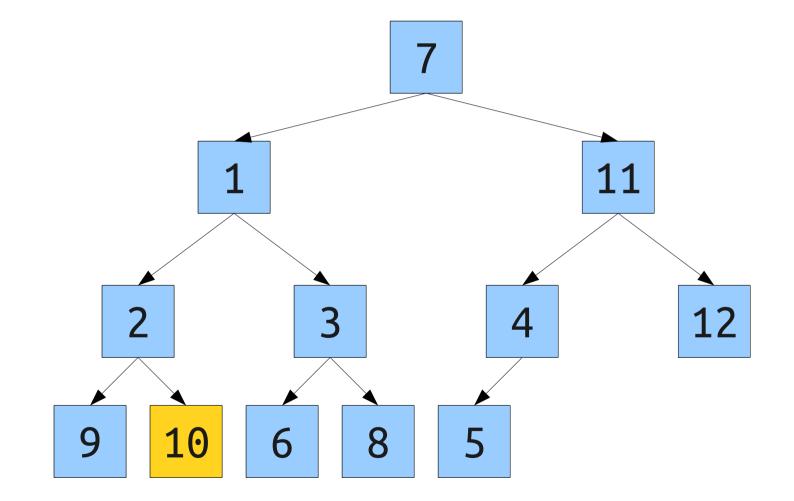


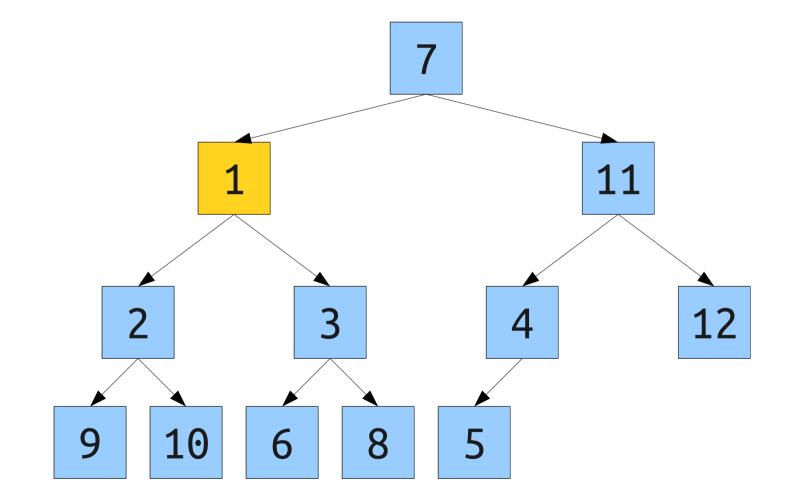


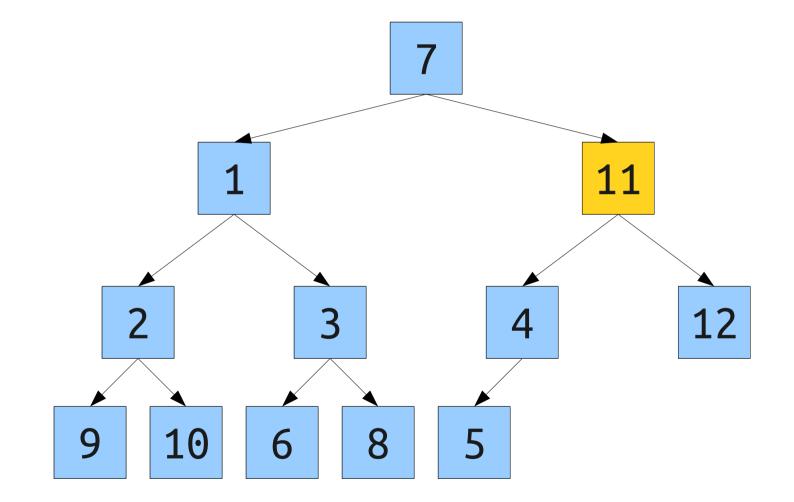


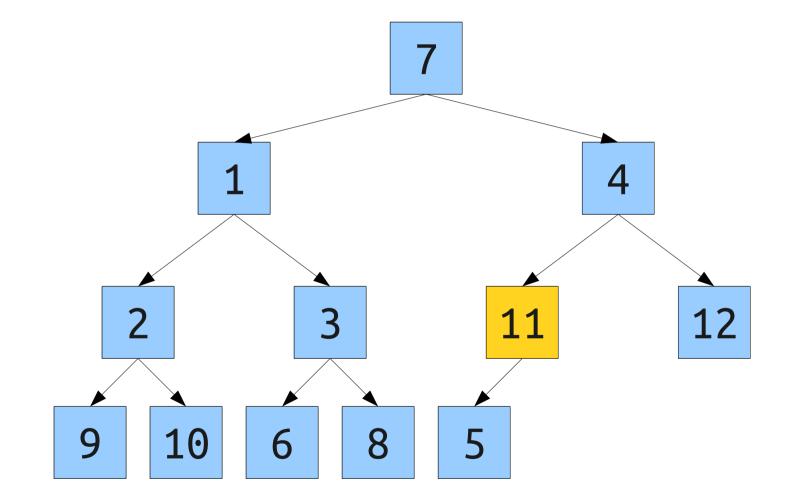


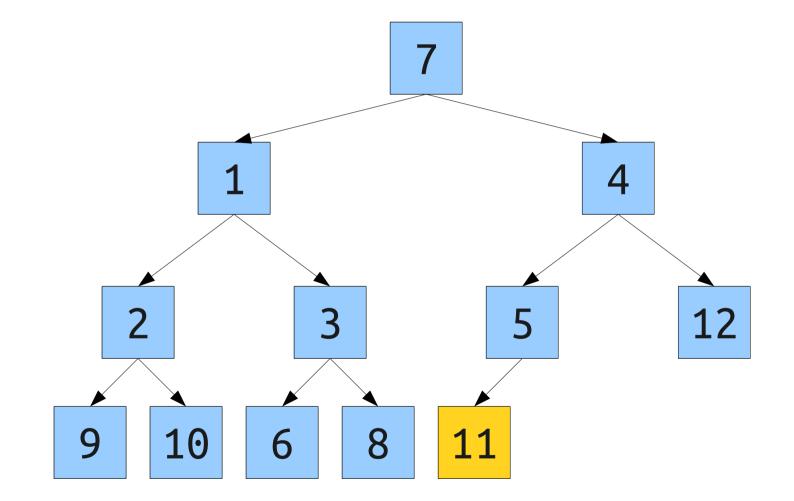


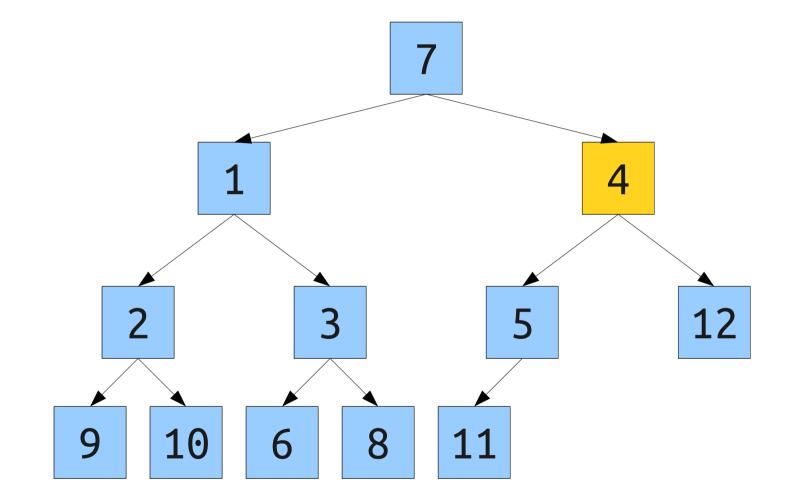


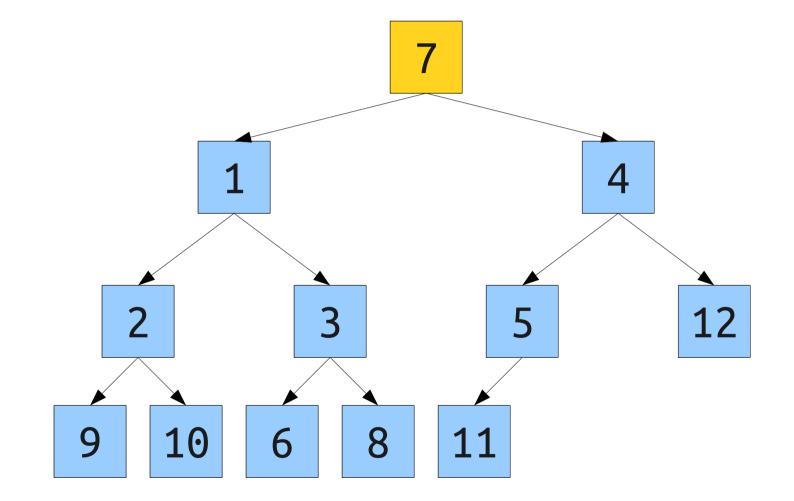


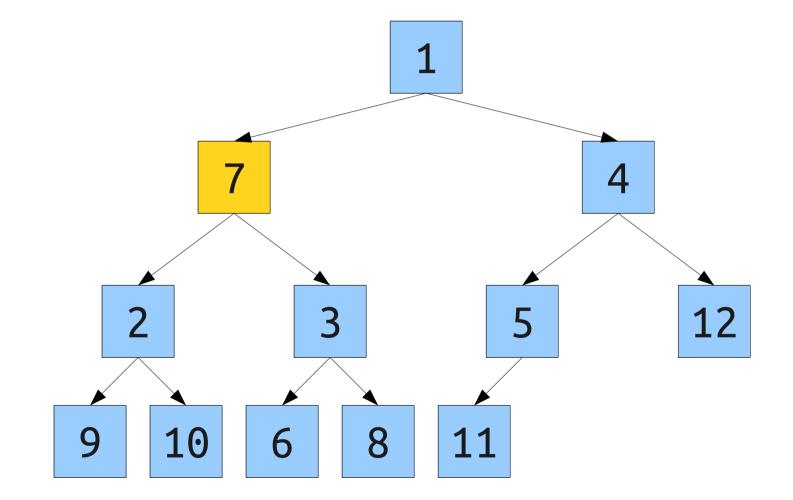


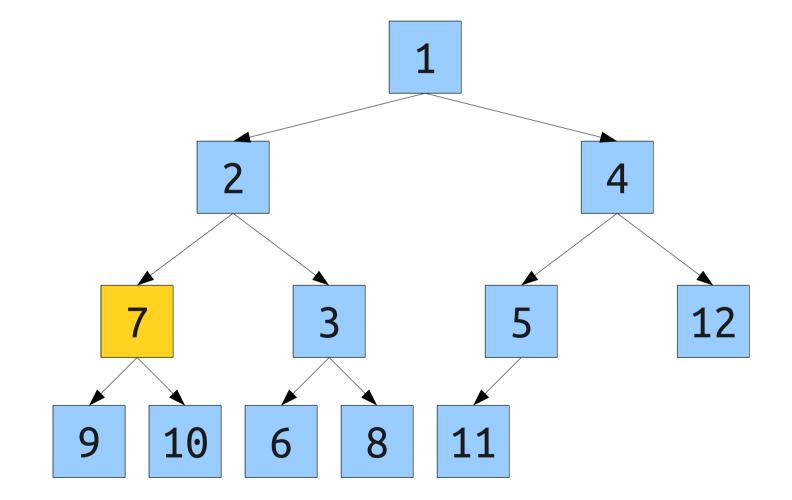


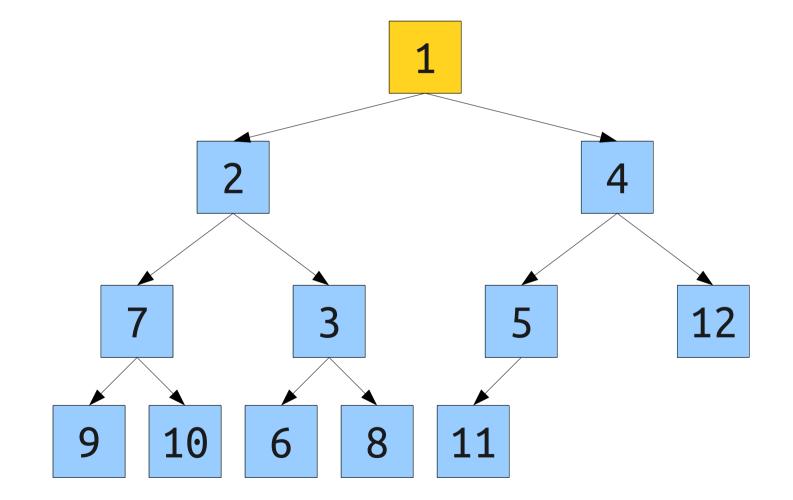


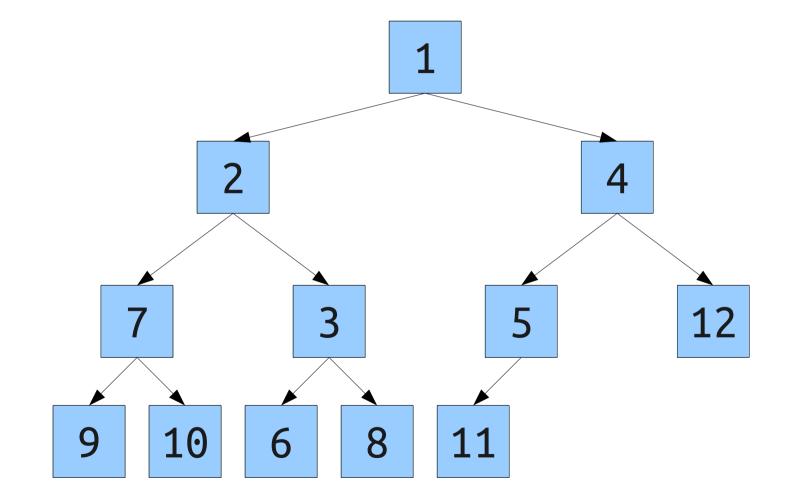


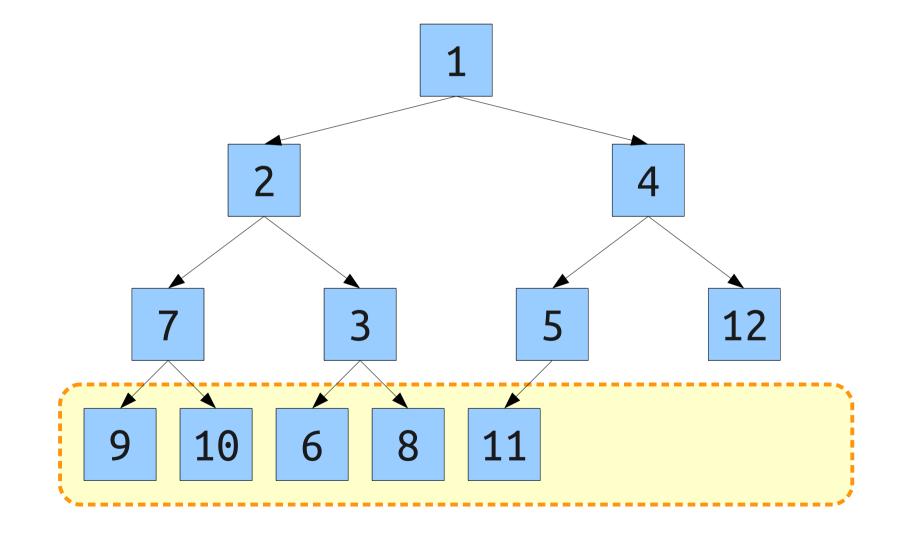


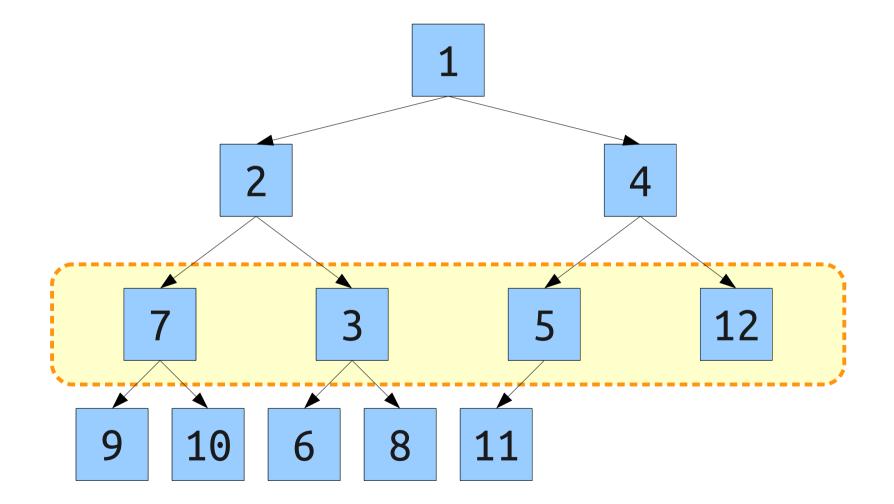


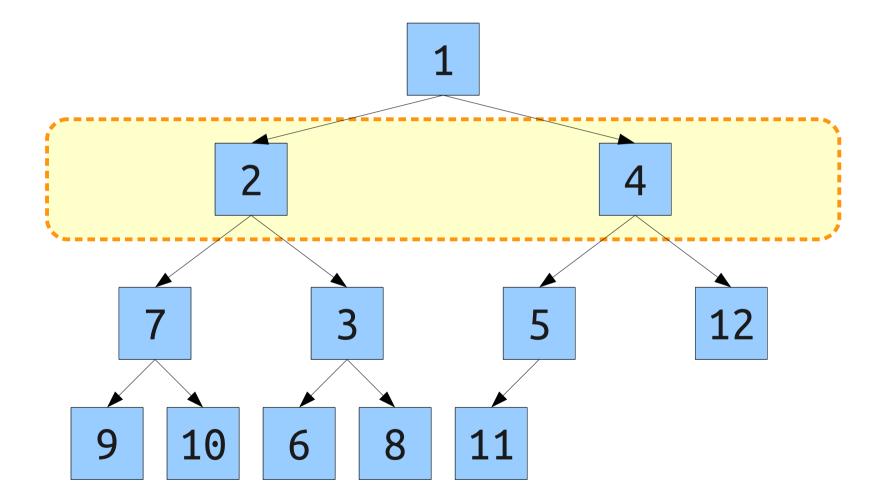


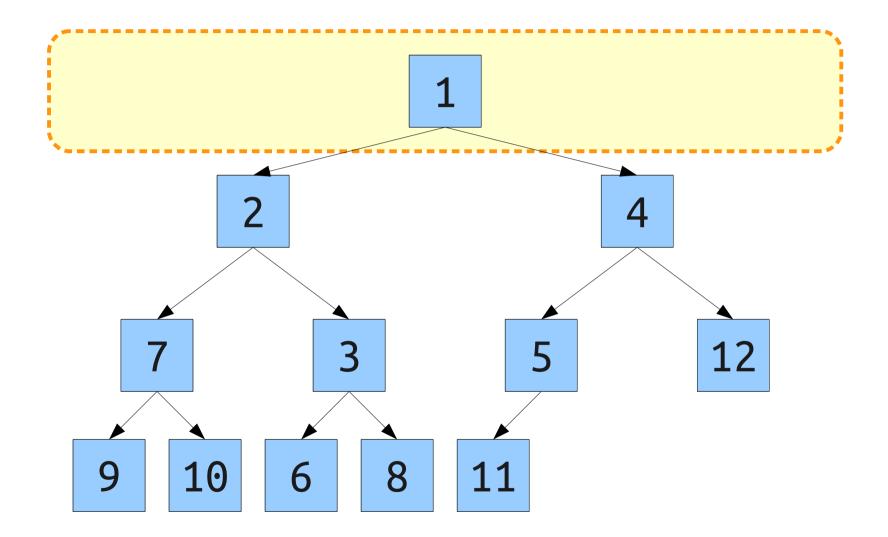












#### Analyzing the Runtime

- At most half of the elements start one layer above that and can move down at most once.
- At most a quarter of the elements start one layer above that and can move down at most twice.
- At most an eighth of the elements start two layers above that and can move down at most thrice.
- More generally: At most  $n / 2^k$  of the elements can move down k steps.
- Can upper-bound the runtime with the sum  $T(n) \leq \sum_{i=0}^{\lceil \log_2 n \rceil} \frac{ni}{2^i} = n \sum_{i=0}^{\lceil \log_2 n \rceil} \frac{i}{2^i}$

#### Simplifying the Summation

• We want to simplify the sum

$$\sum_{i=0}^{\log_2 n} \frac{i}{2^i}$$

• Let's introduce a new variable *x*, then evaluate the sum when  $x = \frac{1}{2}$ :

$$\sum_{i=0}^{\log_2 n} i x^i$$

• If x < 1, each term is less than the previous, so

$$\sum_{i=0}^{\log_2 n} i x^i < \sum_{i=0}^{\infty} i x^i$$

# Solving the Summation $\sum_{i=0}^{\infty} i x^i$

# Solving the Summation $\sum_{i=0}^{\infty} i x^{i} = x \sum_{i=0}^{\infty} i x^{i-1}$

# Solving the Summation $\sum_{i=0}^{\infty} i x^{i} = x \sum_{i=0}^{\infty} i x^{i-1}$ $= x \sum_{i=0}^{\infty} \frac{d}{dx} x^{i}$

# Solving the Summation $\sum_{i=0}^{\infty} i x^{i} = x \sum_{i=0}^{\infty} i x^{i-1}$ $= x \sum_{i=0}^{\infty} \frac{d}{dx} x^{i}$ $= x \frac{d}{dx} \left( \sum_{i=0}^{\infty} x^{i} \right)$

### Solving the Summation $\sum_{i=1}^{\infty} i x^{i} = x \sum_{i=1}^{\infty} i x^{i-1}$ i=0 $= x \sum_{i=0}^{\infty} \frac{d}{dx} x^{i}$ $= x \frac{d}{dx} \left( \sum_{i=0}^{\infty} x^i \right)$ $= x \frac{d}{dx} \left( \frac{1}{1-x} \right)$

\ /

### Solving the Summation $\sum_{i=1}^{\infty} i x^{i} = x \sum_{i=1}^{\infty} i x^{i-1}$ i=0 $= x \sum_{i=0}^{\infty} \frac{d}{dx} x^{i}$ $= x \frac{d}{dx} \left( \sum_{i=0}^{\infty} x^{i} \right)$ $= x \frac{d}{dx} \left( \frac{1}{1-x} \right)$ $= x \frac{1}{(1-x)^2}$

# Solving the Summation $\sum_{i=1}^{\infty} i x^{i} = x \sum_{i=1}^{\infty} i x^{i-1}$ i=0 $= x \sum_{i=0}^{\infty} \frac{d}{dx} x^{i}$ $= x \frac{d}{dx} \left( \sum_{i=0}^{\infty} x^{i} \right)$ $= x \frac{d}{dx} \left( \frac{1}{1-x} \right)$ $= x \frac{1}{(1-x)^2}$ $= \frac{x}{(1-x)^2}$

#### The Finishing Touches

• We know know that

$$T(n) \le n \sum_{i=0}^{\lceil \log_2 n \rceil} i x^i < n \sum_{i=0}^{\infty} i x^i = \frac{nx}{(1-x)^2}$$

• Evaluating at  $x = \frac{1}{2}$ , we get

$$T(n) \leq \frac{n(1/2)}{(1 - (1/2))^2} = \frac{n(1/2)}{(1/2)^2} = 2n$$

- So at most 2*n* swaps are performed!
- We visit each node once and do at most O(n) swaps, so the runtime is  $\Theta(n)$ .