

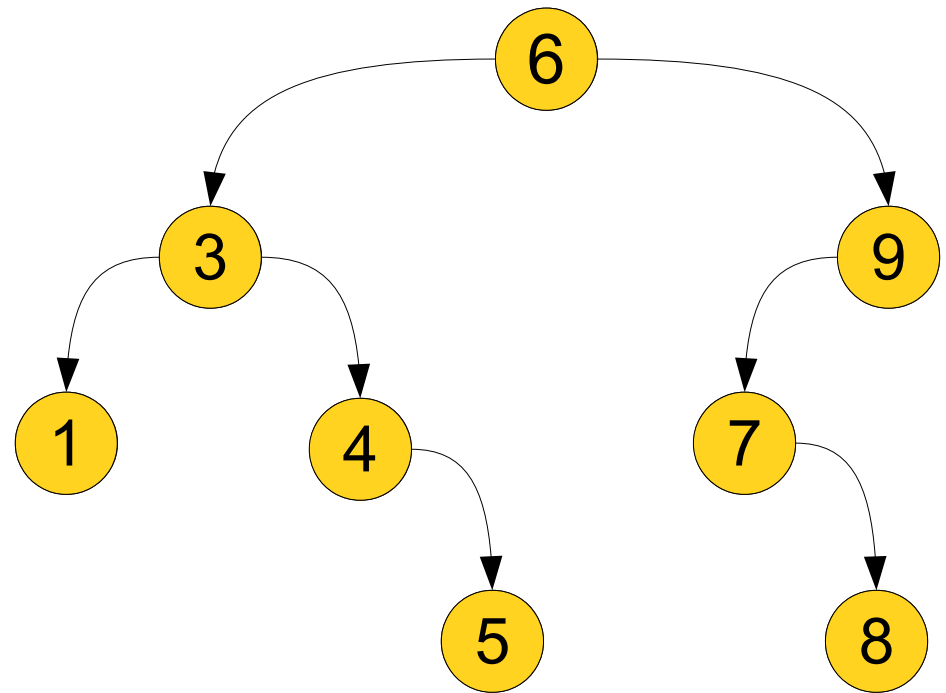
# Binary Search Trees

## Part Two

Recap from Last Time

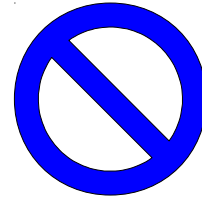
# Binary Search Trees

- A **binary search tree** (or **BST**) is a data structure often used to implement maps and sets.
- The tree consists of a number of **nodes**, each of which stores a value and has zero, one, or two **children**.
- **Key structural property:** All values in a node's left subtree are **smaller** than the node's value, and all values in a node's right subtree are **greater** than the node's value.

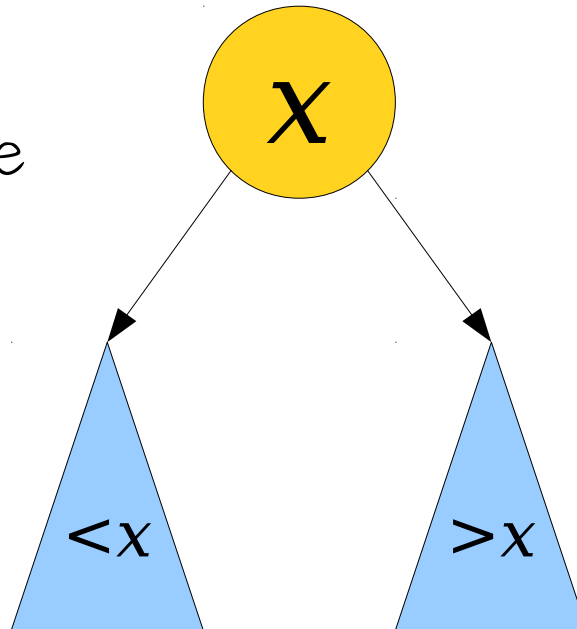


# A Binary Search Tree Is Either...

an empty tree,  
represented by  
**nullptr**, or...



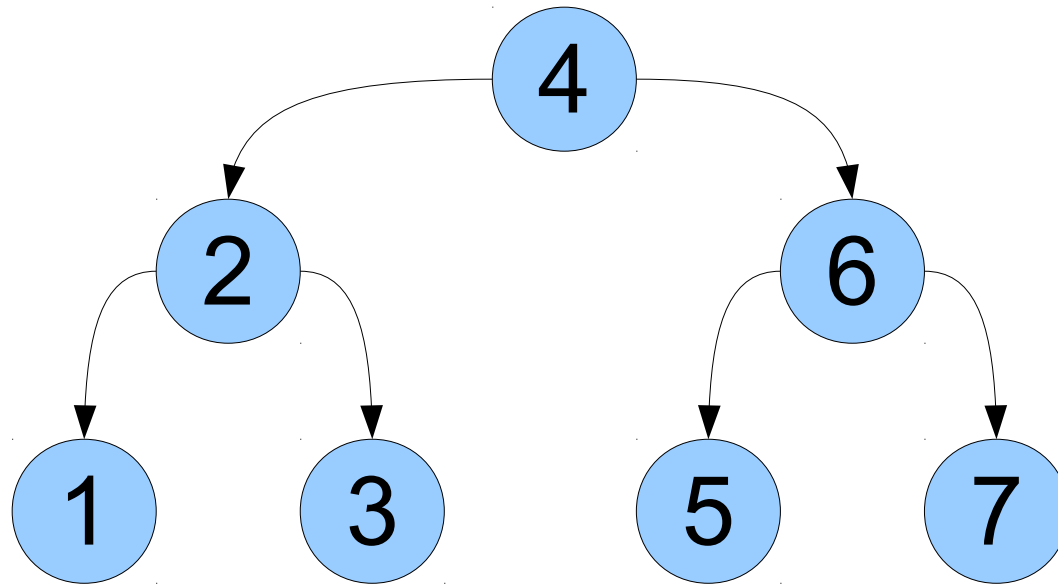
... a single node,  
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... and whose right  
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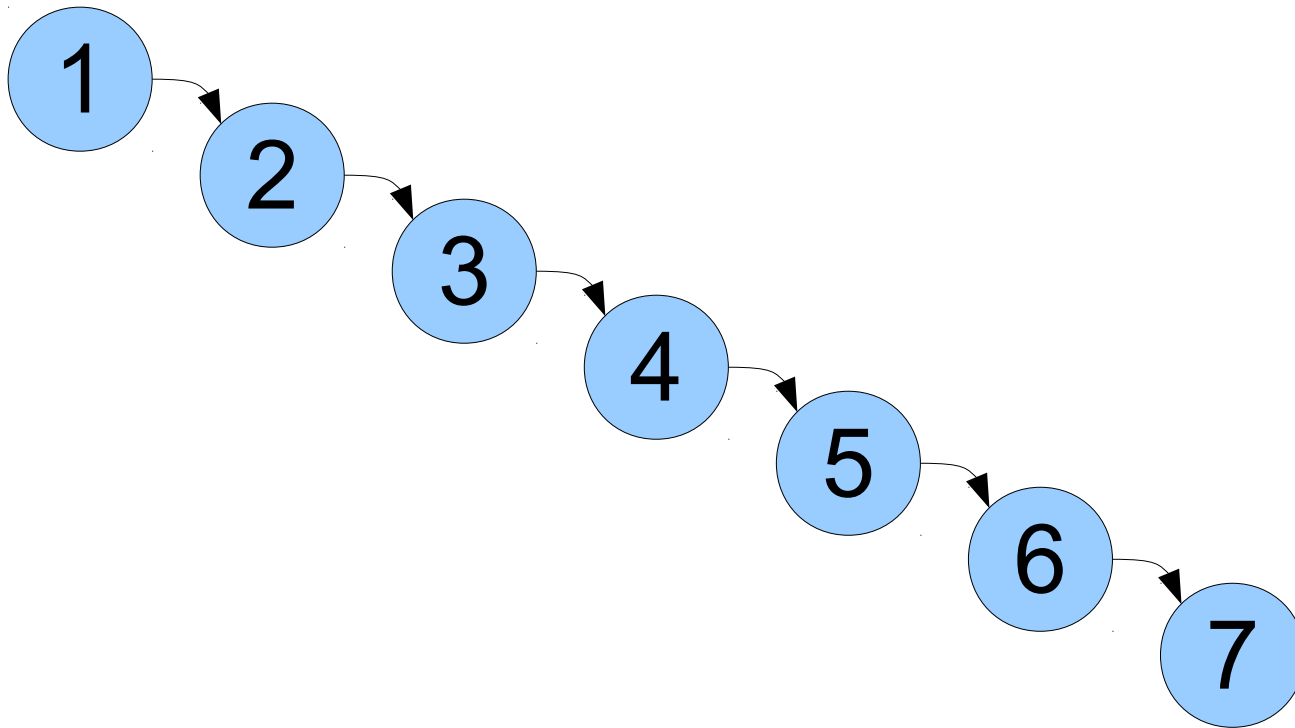
# Tree Terminology

- The **height** of a tree is the number of nodes in the longest path from the root to a leaf.
- By convention, an empty tree has height -1.



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# Efficiency Questions

- In a *balanced* BST, the cost of doing an insertion or lookup is  $O(\log n)$ .
- Although we didn't cover this, the cost of a deletion is also  $O(\log n)$  (play around with this in section!)
- The runtimes of these operations depend on the height of the BST, which we're going to assume is  $O(\log n)$  going forward.

New Stuff!

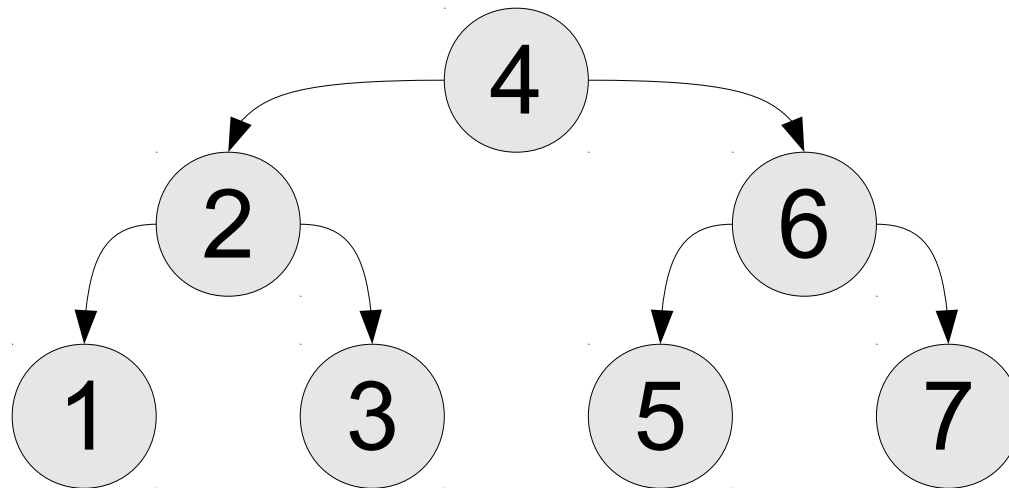


# Walking Trees



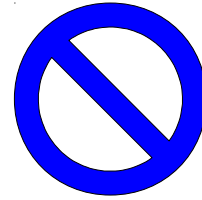
# Printing a Tree

- BSTs store their elements in sorted order.
- By visiting the nodes of a BST in the right order, we'll get back the nodes in sorted order!
  - (This is also why iterating over a Map or Set gives you the keys/elements in sorted order!)

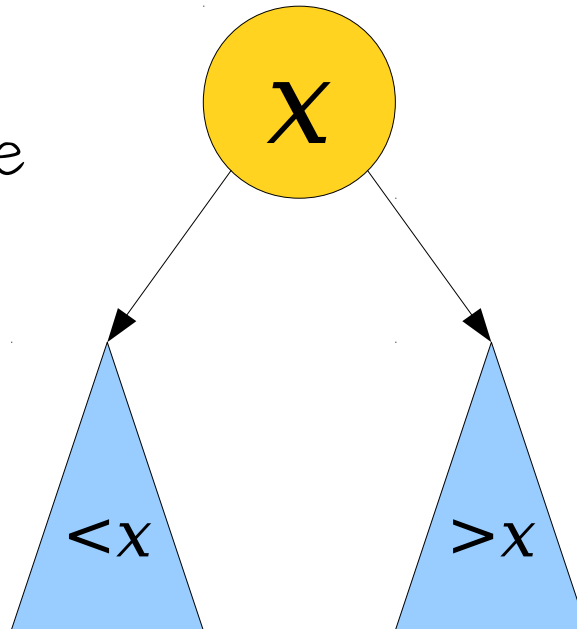


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# Inorder Traversals

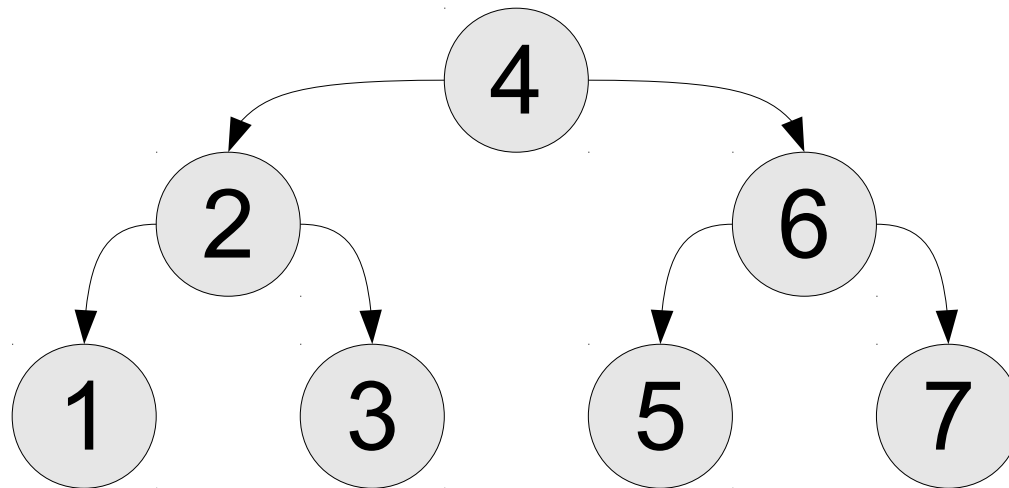
- The particular recursive pattern we just saw is called an ***inorder traversal*** of a binary tree.
- Specifically:
  - Recursively visit all the nodes in the left subtree.
  - Visit the node itself.
  - Recursively visit all the nodes in the right subtree.

# Getting Rid of Trees



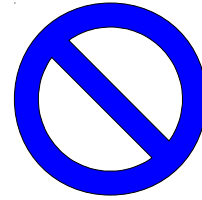
# Freeing a Tree

- Once we're done with a tree, we need to free all of its nodes.
- As with a linked list, we have to be careful not to use any nodes after freeing them.

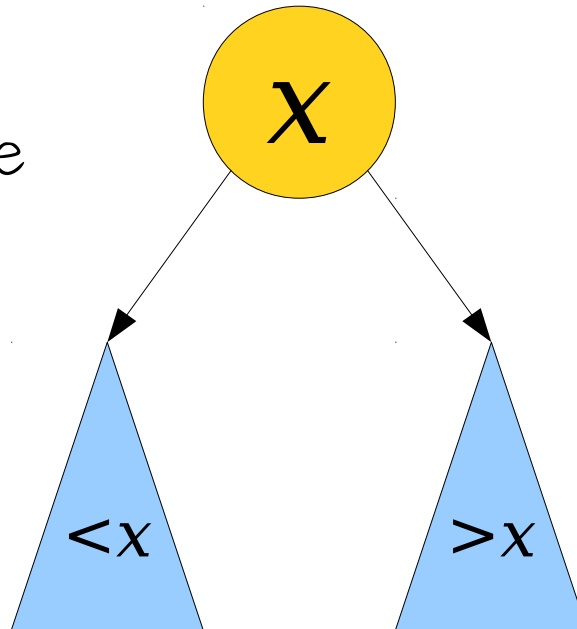


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# Postorder Traversals

- The particular recursive pattern we just saw is called a ***postorder traversal*** of a binary tree.
- Specifically:
  - Recursively visit all the nodes in the left subtree.
  - Recursively visit all the nodes in the right subtree.
  - Visit the node itself.



**Time-Out for Announcements!**

# Assignment 5

- Assignment 5 is due this Friday at the start of class.
- ***Recommendation:*** Aim to complete the first three implementations by the end of tonight. Finish the binary heap by Wednesday.
- Questions? Ask your SL, stop by the LaIR, visit office hours, or ask on Piazza!

CS+SOCIAL GOOD PRESENTS

# WINTER CAREERS PANEL & DISCUSSION

WHERE: Kehillah Hall, 2nd Floor Hillel

WHEN: February 28th, 6:00-7:30pm

Interested in using your CS skills for social impact? Come hear from people working on tech for social good - learn about career paths and ways to get involved! Dinner will be served at the event.

*Moderated by Cynthia Lee*

*Featuring:*



Lean In



Exygy



Lioness



Udemy



Facebook



Google

Back to CS106B!

Has this ever happened to you?

# What's Going On?

- Internally, the Map and Set types are implemented using binary search trees.
- BSTs assume there's a way to compare elements against one another using the relational operators.
- But you can't compare two structs using the less-than operator!
- "There's got to be a better way!"

# Defining Comparisons

- Most programming languages provide some mechanism to let you define how to compare two objects.
- C has comparison functions, Java has the Comparator interface, Python has `__cmp__`, etc.
- In C++, we can use a technique called ***operator overloading*** to tell it how to compare objects using the `<` operator.

This function is  
named "operator<"

```
bool operator< (const Doctor& lhs, const Doctor& rhs) {  
    /* ... */  
}
```

Its arguments correspond to the  
left-hand and right-hand operands  
to the < operator.

```
Doctor zhivago = /* ... */  
Doctor acula   = /* ... */
```

```
if (zhivago < acula) {  
    /* ... */  
}
```



```
bool operator< (const Doctor& lhs, const Doctor& rhs) {  
    /* ... */  
}
```

```
Doctor zhivago = /* ... */  
Doctor acula   = /* ... */
```

```
if (zhivago < acula) {  
    /* ... */  
}
```

C++ treats this as  
`operator< (zhivago, acula)`

# Overloading Less-Than

- To store custom types in Maps or Sets in C++, overload the less-than operator by defining a function like this one:

```
bool operator< (const Type& lhs, const Type& rhs);
```

- This function must obey four rules:
  - It is **consistent**: writing  $x < y$  always returns the same result given  $x$  and  $y$ .
  - It is **irreflexive**:  $x < x$  is always false.
  - It is **transitive**: If  $x < y$  and  $y < z$ , then  $x < z$ .
  - It has **transitivity of incomparability**: If neither  $x < y$  nor  $y < x$  are true, then  $x$  and  $y$  behave indistinguishably.
- (These rules mean that  $<$  is a **strict weak order**; take CS103 for details!)

# Overloading Less-Than

A standard technique for implementing the less-than operator is to use a *lexicographical comparison*, which looks like this:

```
bool operator< (const Type& lhs, const Type& rhs) {  
    if (lhs.field1 != rhs.field1) {  
        return lhs.field1 < rhs.field1;  
    } else if (lhs.field2 != rhs.field2) {  
        return lhs.field2 < rhs.field2;  
    } else if (lhs.field3 != rhs.field3) {  
        return lhs.field3 < rhs.field3;  
    } ... {  
        ...  
    } else {  
        return lhs.fieldN < rhs.fieldN;  
    }  
}
```

One Last Cool Trick, If We Have Time

# Filtering Trees

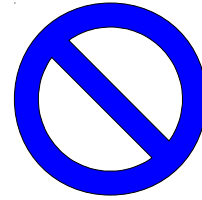


# Range Searches

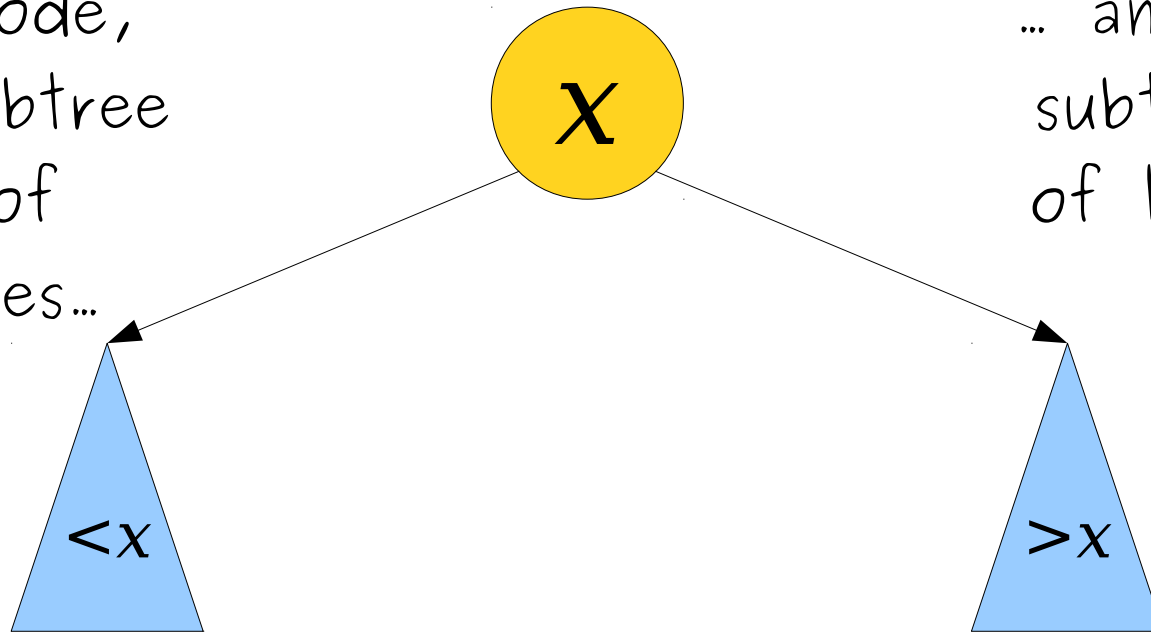
- We can use BSTs to do *range searches*, in which we find all values in the BST within some range.
- For example:
  - If the values in the BST are dates, we can find all events that occurred within some time window.
  - If the values in the BST are number of diagnostic scans ordered, we can find all doctors who order a disproportionate number of scans.

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# Range Searches

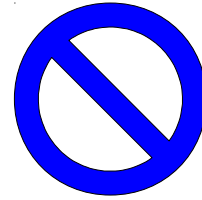
- The cost of a range search in a balanced BST is  **$O(\log n + z)$** ,  
where  $z$  is the number of matches reported.
- In a general BST, it's  $O(h + z)$ .
- Curious about where that analysis comes from?  
Come talk to me after class!



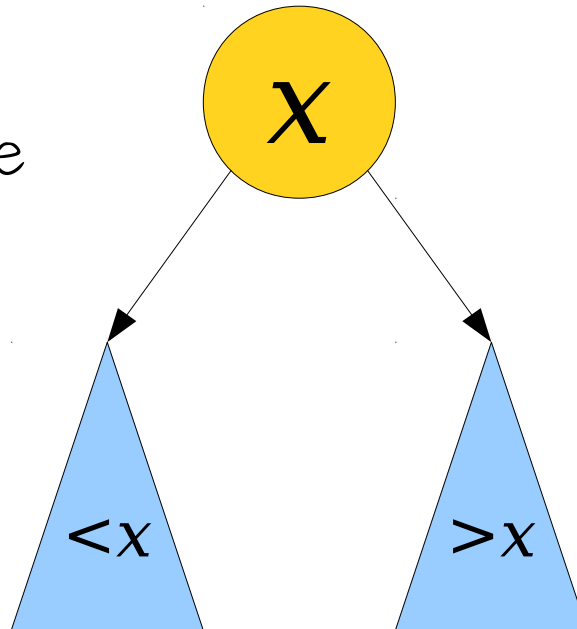
To Summarize:

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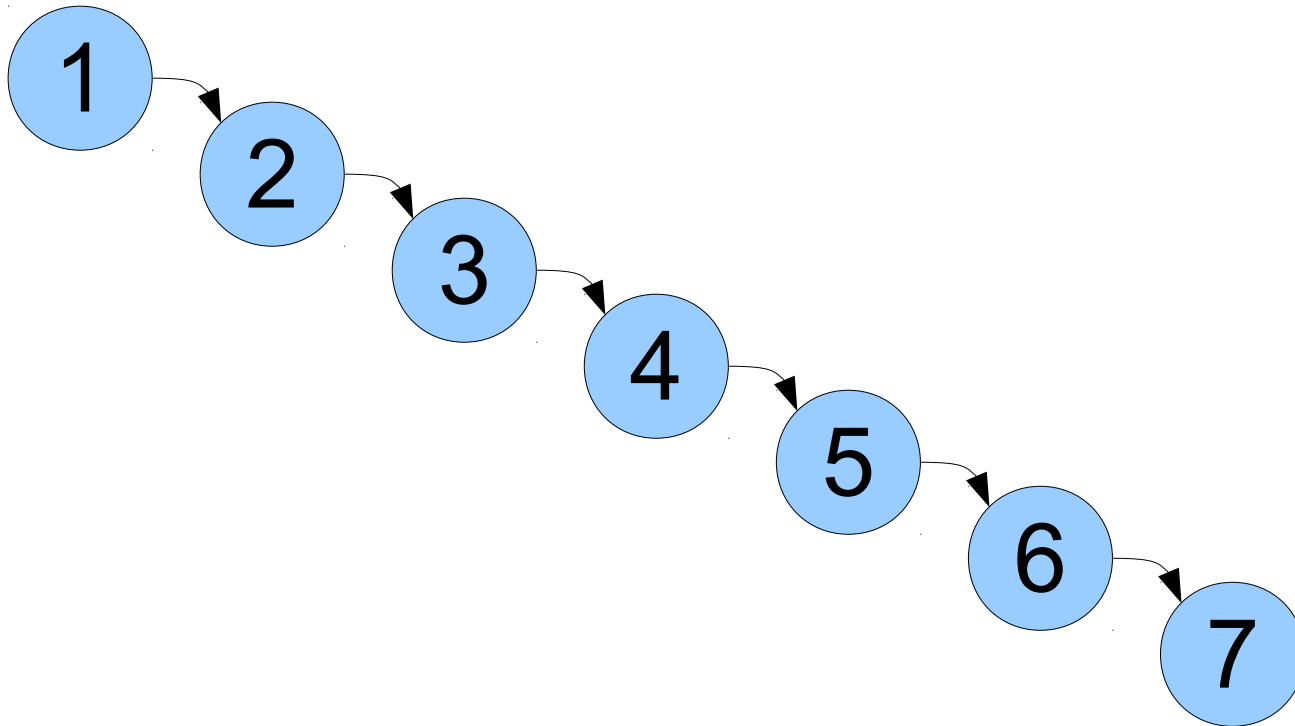
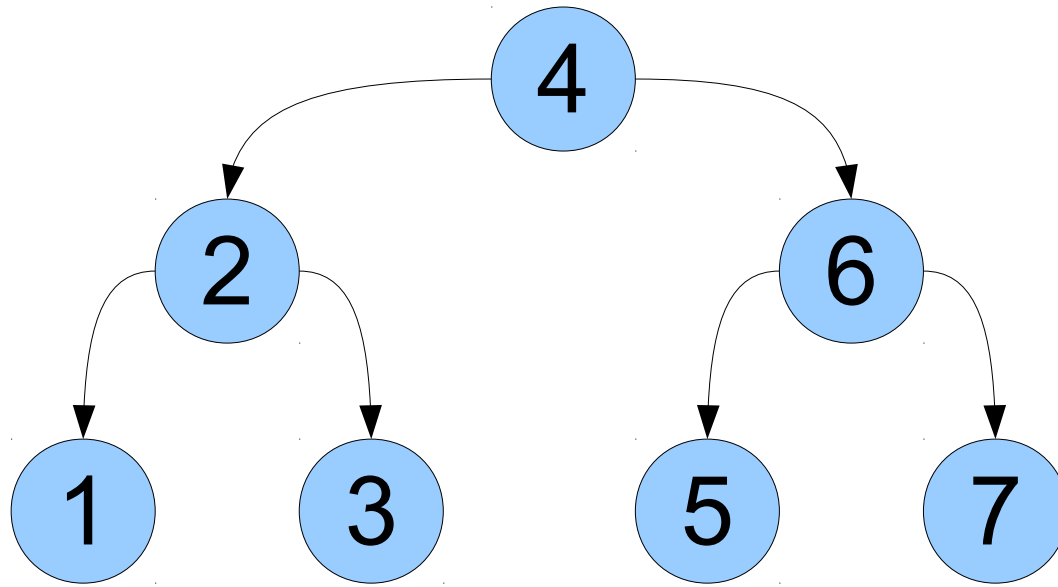


... and whose right  
subtree is a BST  
of larger values.

```
struct Node {  
    int value;  
    Node* left; // Smaller values  
    Node* right; // Bigger values  
};
```

```
bool contains(Node* root, const string& key) {  
    if (root == nullptr) return false;  
    else if (key == root->value) return true;  
    else if (key < root->value) return contains(root->left, key);  
    else return contains(root->right, key);  
}
```

```
void insert(Node*& root, const string& key) {  
    if (root == nullptr) {  
        root = new Node;  
        node->value = key;  
        node->left = node->right = nullptr;  
    } else if (key < root->value) {  
        insert(root->left, key);  
    } else if (key > root->value) {  
        insert(root->right, key);  
    } else {  
        // Already here!  
    }  
}
```



```
void printTree(Node* root) {  
    if (root == nullptr) return;  
  
    printTree(root->left);  
    cout << root->value << endl;  
    printTree(root->right);  
}
```

```
void freeTree(Node* root) {  
    if (root == nullptr) return;  
  
    freeTree(root->left);  
    freeTree(root->right);  
    delete root;  
}
```

```
bool operator< (const Type& lhs, const Type& rhs) {  
    if (lhs.field1 != rhs.field1) {  
        return lhs.field1 < rhs.field1;  
    } else if (lhs.field2 != rhs.field2) {  
        return lhs.field2 < rhs.field2;  
    } else if (lhs.field3 != rhs.field3) {  
        return lhs.field3 < rhs.field3;  
    } ... {  
        ...  
    } else {  
        return lhs.fieldN < rhs.fieldN;  
    }  
}
```

# Next Time

- ***Beyond Data Structures***
  - Why are these ideas useful outside of the realm of sets and maps?
- ***Huffman Encoding***
  - A powerful data compression algorithm.