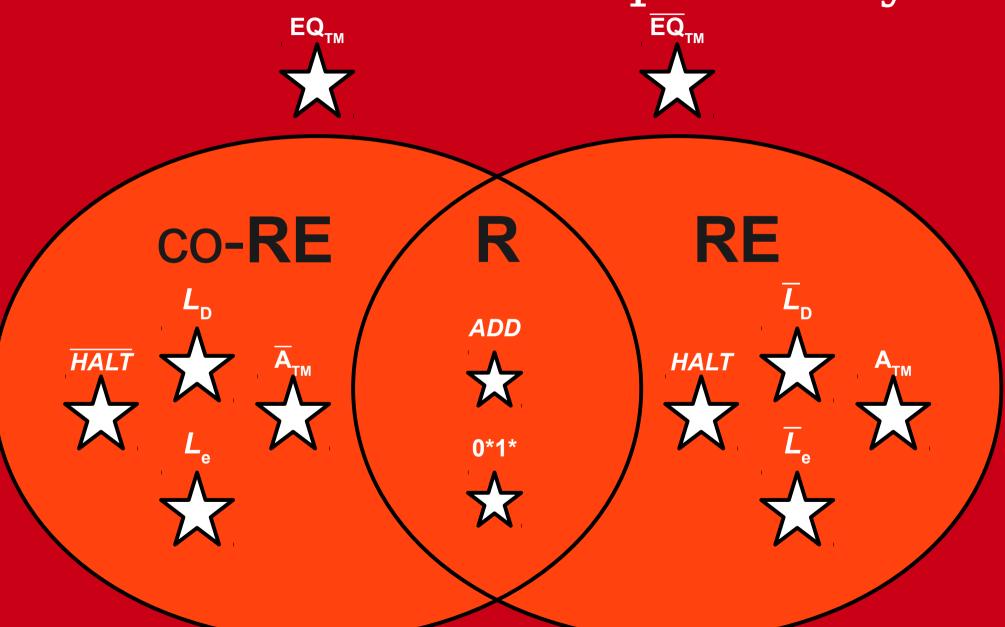
# Complexity Theory Part I

Problem Set 7 due right now using a late period

## The Limits of Computability



What problems can be solved by a computer?

## What problems can be solved **efficiently** by a computer?

#### Where We've Been

- The class **R** represents problems that can be solved by a computer.
- The class **RE** represents problems where "yes" answers can be verified by a computer.
- The class co-**RE** represents problems where "no" answers can be verified by a computer.
- The mapping reduction can be used to find connections between problems.

#### Where We're Going

- The class **P** represents problems that can be solved *efficiently* by a computer.
- The class **NP** represents problems where "yes" answers can be verified *efficiently* by a computer.
- The class co-**NP** represents problems where "no" answers can be verified *efficiently* by a computer.
- The *polynomial-time* mapping reduction can be used to find connections between problems.

It may be that since one is customarily concerned with existence, [...] finiteness, and so forth, one is not inclined to take seriously the question of the existence of a better-than-finite algorithm.

- Jack Edmonds, "Paths, Trees, and Flowers"

It may be that since one is customarily concerned with existence, [...] decidability, and so forth, one is not inclined to take seriously the question of the existence of a better-than-decidable algorithm.

- Jack Edmonds, "Paths, Trees, and Flowers"

#### A Decidable Problem

- **Presburger arithmetic** is a logical system for reasoning about arithmetic.
  - $\forall x. \ x + 1 \neq 0$
  - $\forall x. \ \forall y. \ (x + 1 = y + 1 \rightarrow x = y)$
  - $\forall x. \ x + 0 = x$
  - $\forall x. \ \forall y. \ (x + y) + 1 = x + (y + 1)$
  - $\forall x. ((P(0) \land \forall y. (P(y) \rightarrow P(y+1))) \rightarrow \forall x. P(x)$
- Given a statement, it is decidable whether that statement can be proven from the laws of Presburger arithmetic.
- Any Turing machine that decides whether a statement in Presburger arithmetic is true or false has to move the tape head at least  $2^{2^{cn}}$  times on some inputs of length n (for some fixed constant c).

#### For Reference

• Assume c = 1.

$$2^{2^{0}}=2$$

$$2^{2^{1}}=4$$

$$2^{2^{2}}=16$$

$$2^{2^{3}}=256$$

$$2^{2^{4}}=65536$$

$$2^{2^{5}}=18446744073709551616$$

$$2^{2^{6}}=340282366920938463463374607431768211456$$

## The Limits of Decidability

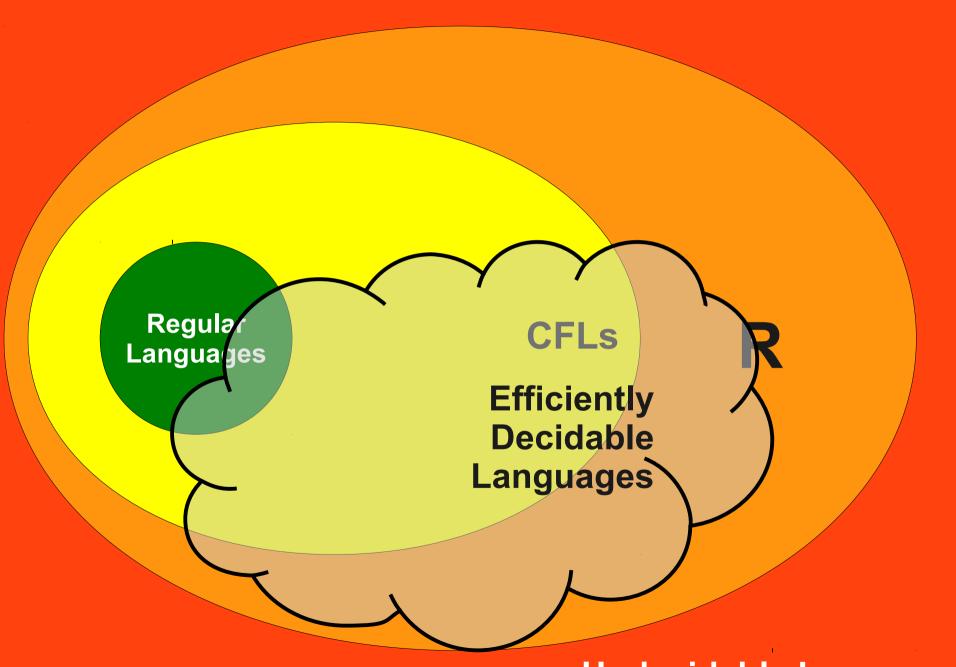
- The fact that a problem is decidable does not mean that it is *feasibly* decidable.
- In computability theory, we ask the question

Is it **possible** to solve problem L?

• In complexity theory, we ask the question

Is it possible to solve problem *L* **efficiently**?

• In the remainder of this course, we will explore this question in more detail.



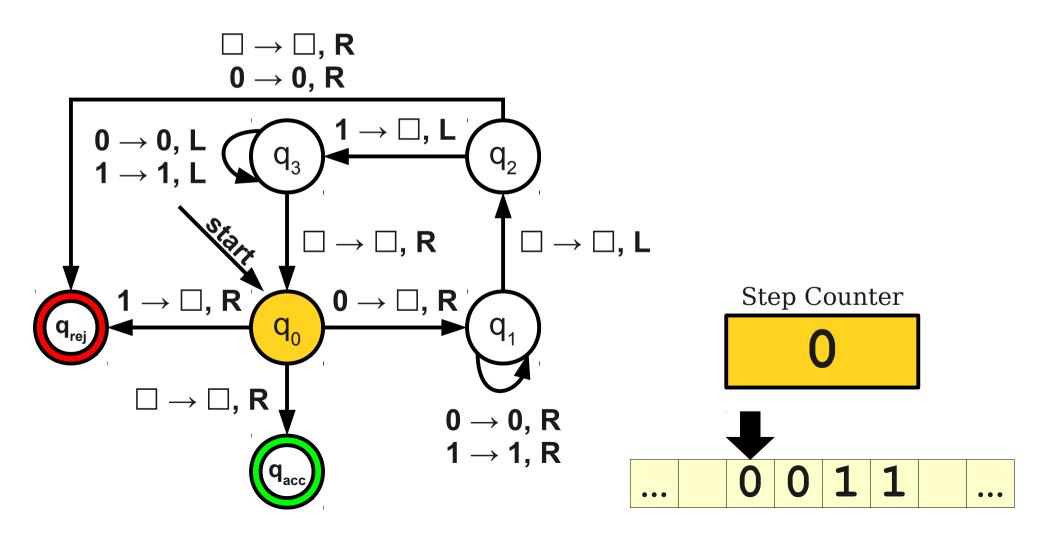
**Undecidable Languages** 

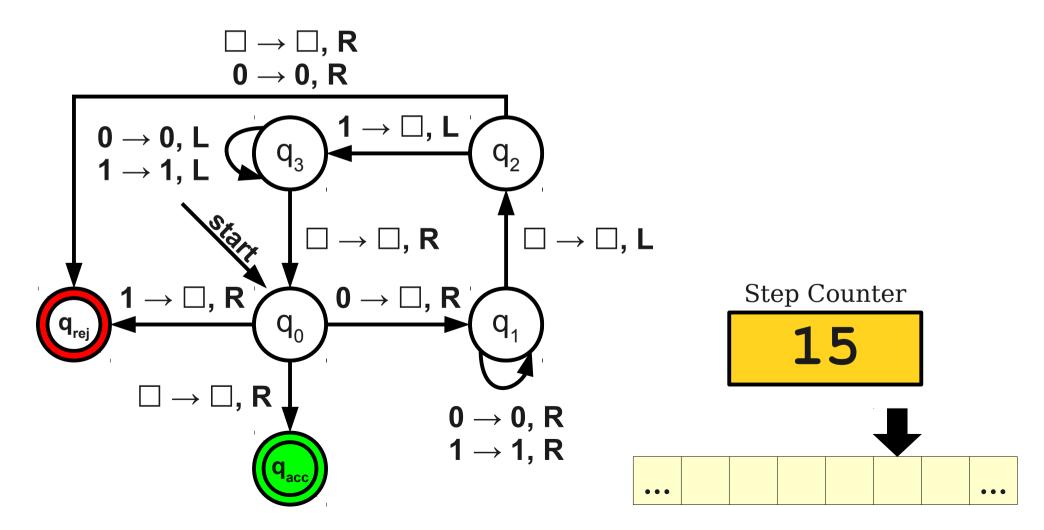
#### The Setup

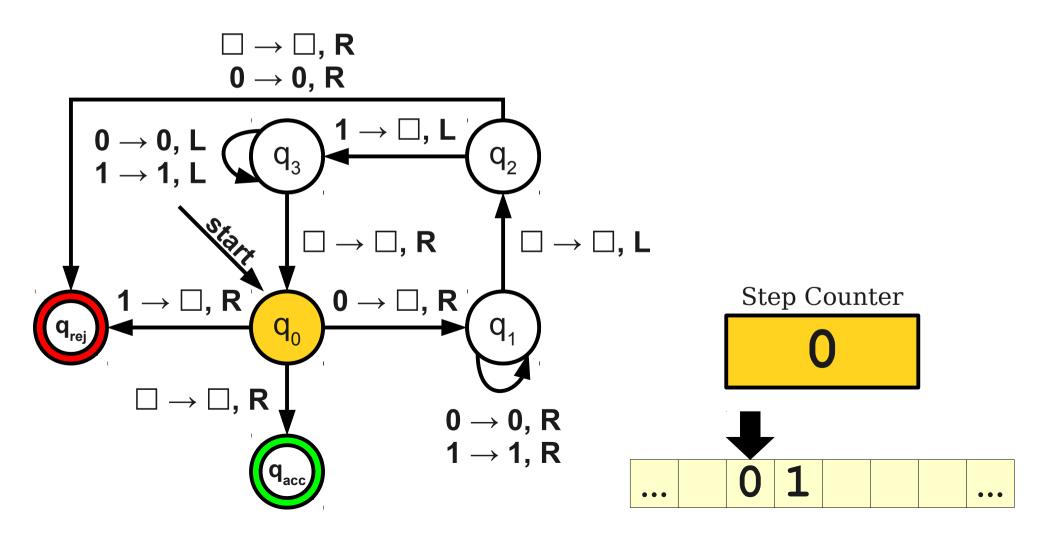
- In order to study computability, we needed to answer these questions:
  - What is "computation?"
  - What is a "problem?"
  - What does it mean to "solve" a problem?
- To study complexity, we need to answer these questions:
  - What does "complexity" even mean?
  - What is an "efficient" solution to a problem?

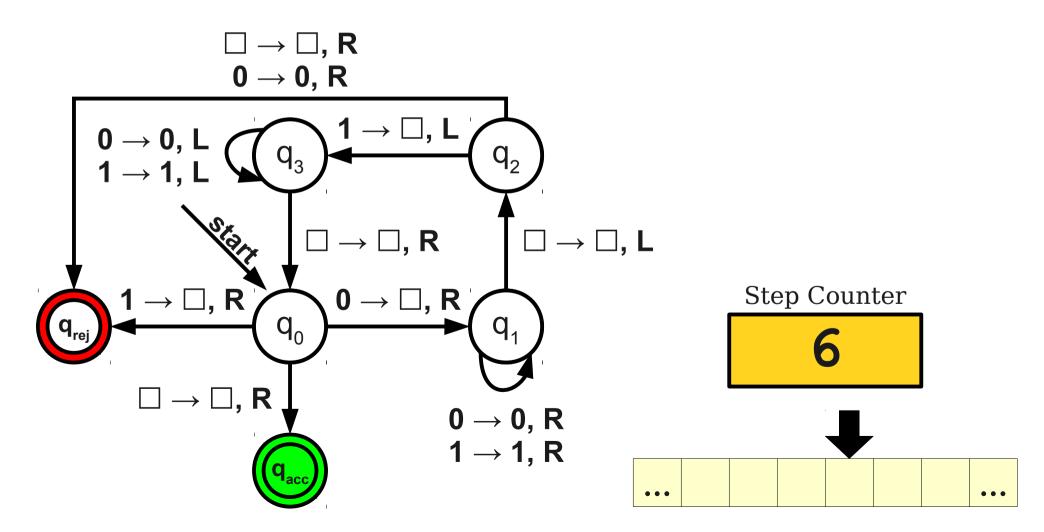
## Measuring Complexity

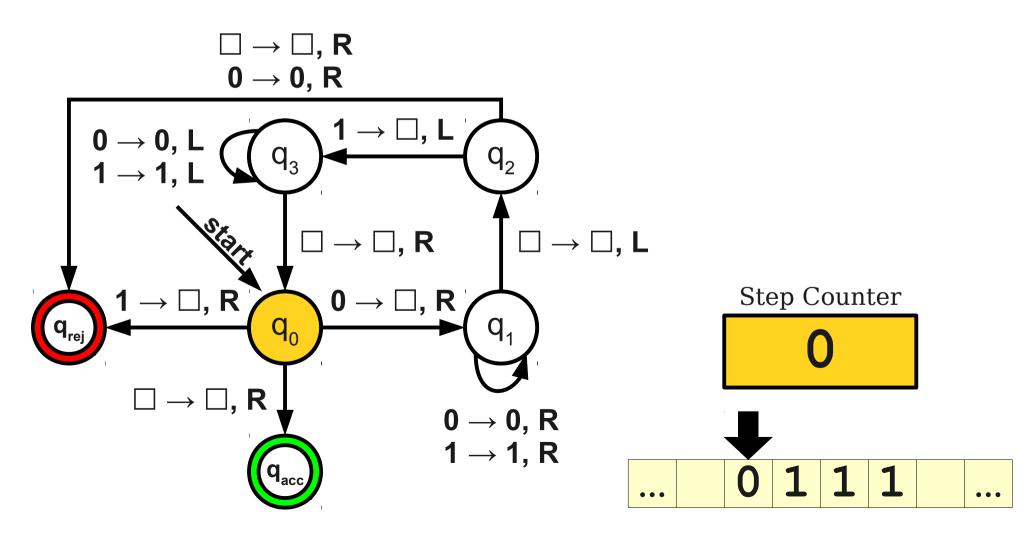
- Suppose that we have a decider D for some language L.
- How might we measure the complexity of *D*?
  - Number of states.
  - Size of tape alphabet.
  - Size of input alphabet.
  - Amount of tape required.
  - Number of steps required.
  - Number of times a given state is entered.
  - Number of times a given symbol is printed.
  - Number of times a given transition is taken.
  - (Plus a whole lot more...)

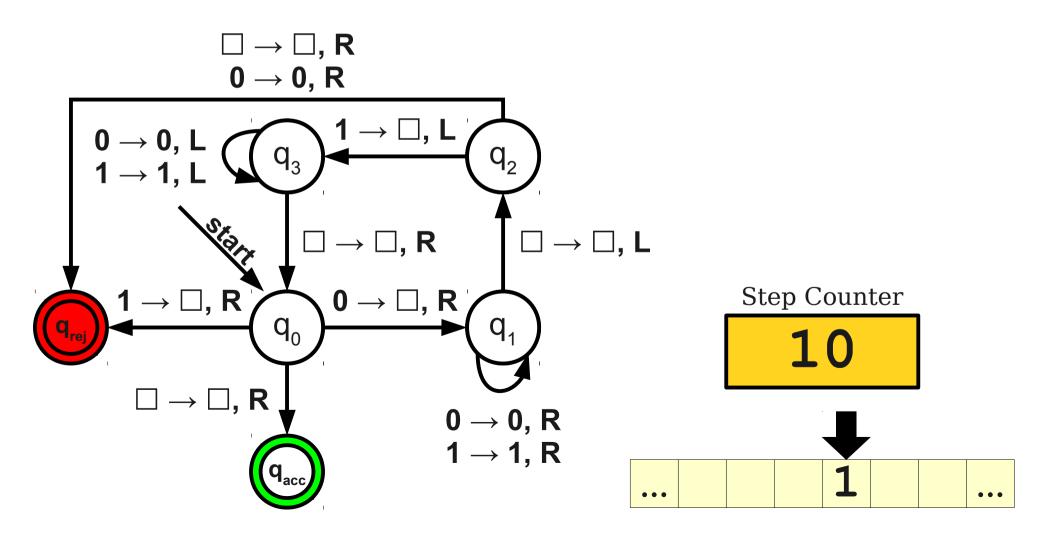












- The number of steps a TM takes on some input is sensitive to
  - The structure of that input.
  - The length of the input.
- How can we come up with a consistent measure of a machine's runtime?

- The **time complexity** of a TM *M* is a function denoting the *worst-case* number of steps *M* takes on any input of length *n*.
  - By convention, n denotes the length of the input.
  - Assume we're only dealing with deciders, so there's no need to handle looping TMs.
- The previous TM has a time complexity that is (roughly) proportional to  $n^2$  / 2.
  - Difficult and utterly unrewarding exercise: compute the *exact* time complexity of the previous TM.

## A Slight Problem

- Consider the following TM over  $\Sigma = \{0, 1\}$  for the language  $BALANCE = \{ w \in \Sigma^* \mid w \}$  has the same number of 0s and 1s 3:
  - M = "On input w:
    - Scan across the tape until a o or 1 is found.
    - If none are found, accept.
    - If one is found, continue scanning until a matching 1 or 0 is found.
    - If none is found, reject.
    - Otherwise, cross off that symbol and repeat."
- What is the time complexity of M?

#### A Loss of Precision

- When considering computability, using high-level TM descriptions is perfectly fine.
- When considering *complexity*, high-level TM descriptions make it nearly impossible to precisely reason about the actual time complexity.
- What are we to do about this?

#### The Best We Can

#### M = "On input w:

- Scan across the tape until a 0 or 1 At most is found.
- If none are found, accept.
- If one is found, continue scanning until a matching 1 or 0 is found.
- If none are found, reject.
- Otherwise, cross off that symbol and repeat."

At most *n* steps.

At most 1 step.

At most *n* more steps.

At most 1 step

At most *n* steps to get back to the start of the tape.

At most 3n + 2 steps.

 $\times$  At most n/2 loops.

At most  $3n^2/2 + n$  steps.

At most n/2 loops

#### An Easier Approach

- In complexity theory, we rarely need an exact value for a TM's time complexity.
- Usually, we are curious with the long-term growth rate of the time complexity. That tells us how *scalable* our algorithm will be.
- For example, if the time complexity is 3n + 5, then doubling the length of the string roughly doubles the worst-case runtime.
- If the time complexity is  $2^n n^2$ , since  $2^n$  grows much more quickly than  $n^2$ , for large values of n, increasing the size of the input by 1 doubles the worst-case running time.

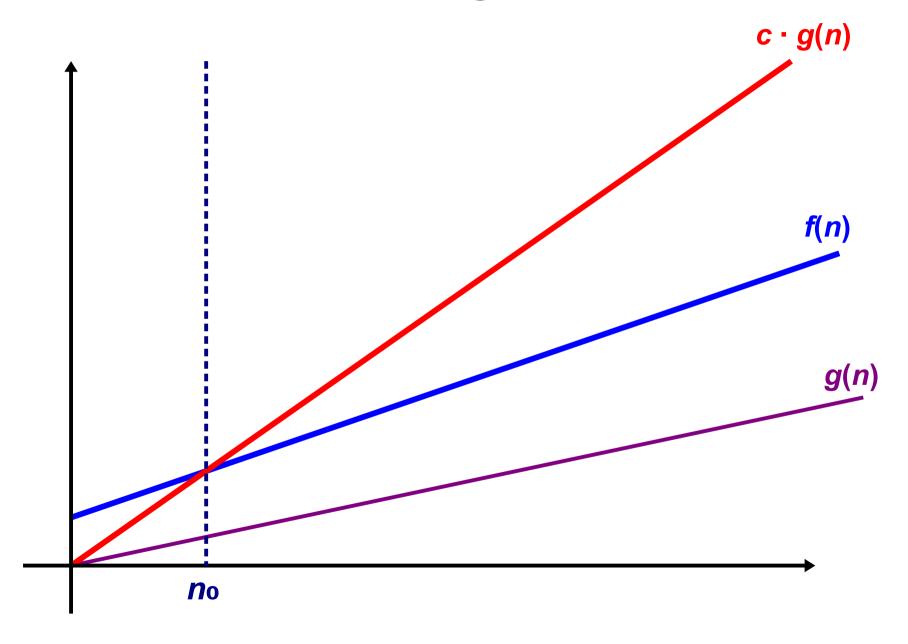
#### Big-O Notation

- Ignore *everything* except the dominant growth term, including constant factors.
- Examples:
  - 4n + 4 = O(n)
  - 137n + 271 = O(n)
  - $n^2 + 3n + 4 = O(n^2)$
  - $2^n + n^3 = O(2^n)$
  - 137 = 0(1)
  - $n^2 \log n + \log^5 n = O(n^2 \log n)$

## Big-O Notation, Formally

- Formally speaking, let  $f, g : \mathbb{N} \to \mathbb{N}$ .
- We say f(n) = O(g(n)) iff
  - There are constants  $n_0$ , c such that  $\forall n \in \mathbb{N}$ .  $(n \ge n_0 \to f(n) \le c \cdot g(n))$
- Intuitively, when n gets "sufficiently large" (i.e. greater than  $n_0$ ), f(n) is bounded from above by some constant multiple (specifically, c) of g(n).

$$f(n) = O(g(n))$$



## Properties of Big-O Notation

- Theorem: If  $f_1(n) = O(g_1(n))$  and  $f_2(n) = O(g_2(n))$ , then  $f_1(n) + f_2(n) = O(g_1(n) + g_2(n))$ .
  - Intuitively: If you run two programs one after another, the big-O of the result is the big-O of the sum of the two runtimes.
- Theorem: If  $f_1(n) = O(g_1(n))$  and  $f_2(n) = O(g_2(n))$ , then  $f_1(n)f_2(n) = O(g_1(n)g_2(n))$ .
  - Intuitively: If you run one program some number of times, the big-O of the result is the big-O of the program times the big-O of the number of iterations.
- This makes it substantially easier to analyze time complexity, though we do lose some precision.

## Life is Easier with Big-O

#### M = "On input w:

- Scan across the tape until a 0 or 1 is found.
- If none are found, accept.
- If one is found, continue scanning until a matching 1 or 0 is found.
- If none is found, reject.
- Otherwise, cross off that symbol and repeat."

O(n) steps O(1) steps O(n)O(n) steps loops O(1) steps O(n) steps O(n) steps O(n) loops

 $O(n^2)$  steps

#### A Quick Note

- Time complexity depends on the model of computation.
  - A computer can binary search over a sorted array in time  $O(\log n)$ .
  - A TM has to spend at least *n* time doing this, since it has no random access.
- For now, assume that the slowdown going from a computer to a TM or vice-versa is not "too bad."

## The Story So Far

- We now have a definition of the runtime of a TM.
- We can use big-O notation to measure the relative growth rates of different runtimes.
- **Big question:** How do we define efficiency?

Time-Out For Announcements!

#### Problem Set 6 Graded

All Problem Set 6's have been graded.
 Late submissions will be returned at the end of lecture today.

A Question from Last Time

"Aren't there some cases where we can know a TM is infinite looping? Couldn't we modify the  $U_{\text{TM}}$  so it keeps a record of IDs and then if it sees the same one twice know it was in a loop? This doesn't guarantee to find all loops, but would it be useful?"

Back to CS103!

What is an efficient algorithm?

# Searching Finite Spaces

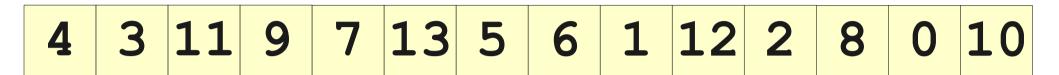
- Many decidable problems can be solved by searching over a large but finite space of possible options.
- Searching this space might take a staggeringly long time, but only finite time.
- From a decidability perspective, this is totally fine.
- From a complexity perspective, this is totally unacceptable.

### A Sample Problem

 4
 3
 11
 9
 7
 13
 5
 6
 1
 12
 2
 8
 0
 10

Goal: Find the length of the longest increasing subsequence of this sequence.

### A Sample Problem



Longest so far:

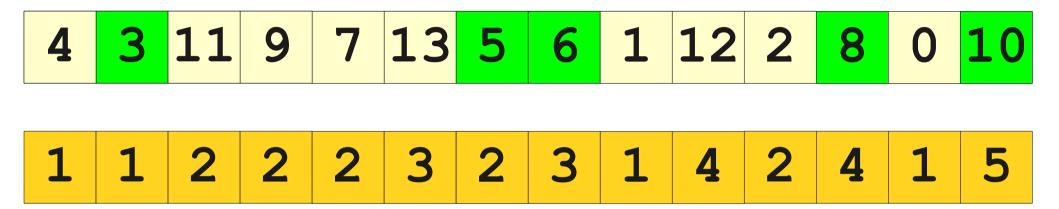
4 11

How many different subsequences are there in a sequence of n elements?  $2^n$ 

How long does it take to check each subsequence? O(n) time.

Runtime is around  $O(n \cdot 2^n)$ .

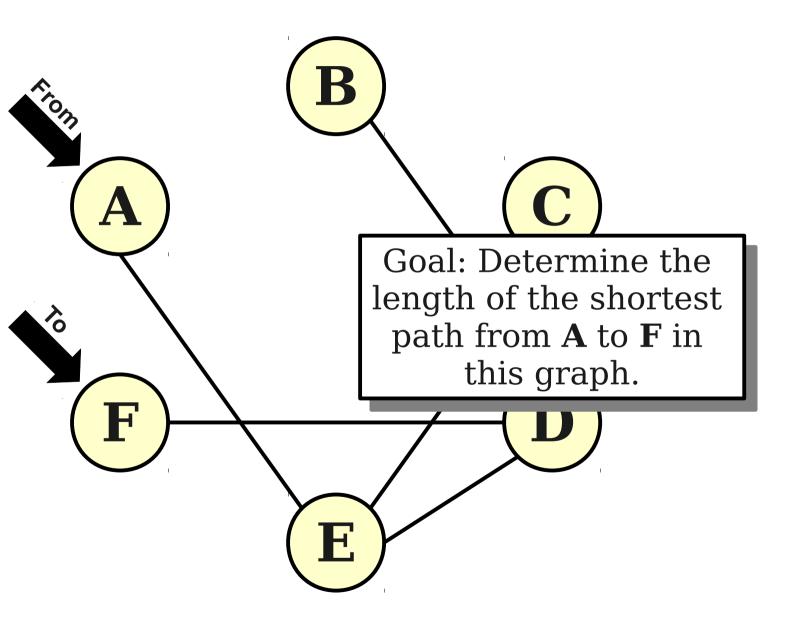
### A Sample Problem



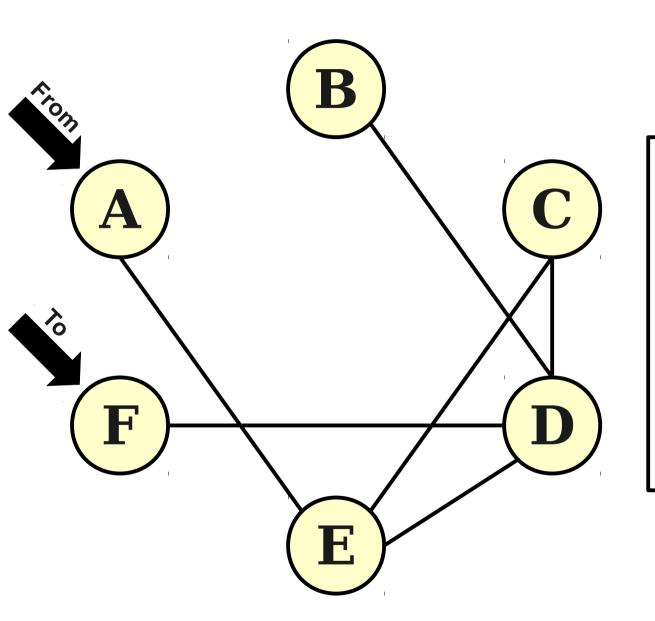
How many elements of the sequence do we have to look at when considering the *k*th element of the sequence? *k* - 1

Total runtime is 
$$1 + 2 + ... + (n - 1) = \mathbf{O}(n^2)$$

#### Another Problem



#### Another Problem

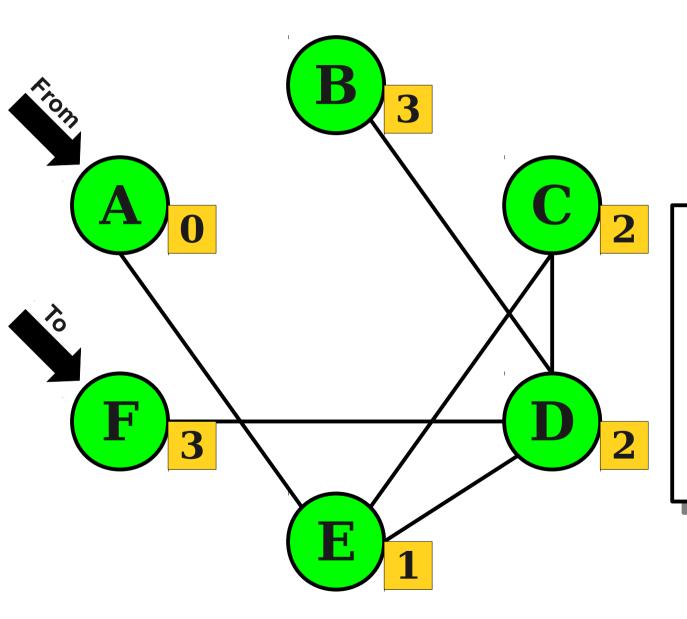


Number of possible ways to order a subset of n nodes is  $O(n \times n!)$ 

Time to check a path is O(n).

Runtime:  $O(n^2 \cdot n!)$ 

#### Another Problem



With a precise analysis, runtime is O(n + m), where n is the number of nodes and m is the number of edges.

## For Comparison

- Longest increasing
   Shortest path subsequence:
  - Naive:  $O(n \cdot 2^n)$
  - Fast:  $O(n^2)$

- problem:
  - Naive:  $O(n^2 \cdot n!)$
  - Fast: O(n + m), where *n* is the number of nodes and m the number of edges. (Take CS161 for details!)

# Defining Efficiency

- When dealing with problems that search for the "best" object of some sort, there are often at least exponentially many possible options.
- Brute-force solutions tend to take at least exponential time to complete.
- Clever algorithms often run in time O(n), or  $O(n^2)$ , or  $O(n^3)$ , etc.

# Polynomials and Exponentials

- A TM runs in **polynomial time** iff its runtime is some polynomial in *n*.
  - That is, time  $O(n^k)$  for some constant k.
- Polynomial functions "scale well."
  - Small changes to the size of the input do not typically induce enormous changes to the overall runtime.
- Exponential functions scale terribly.
  - Small changes to the size of the input induce huge changes in the overall runtime.

#### The Cobham-Edmonds Thesis

A language L can be **decided efficiently** iff there is a TM that decides it in polynomial time.

Equivalently, L can be decided efficiently iff it can be decided in time  $O(n^k)$  for some  $k \in \mathbb{N}$ .

Like the Church-Turing thesis, this is **not** a theorem!

It's an assumption about the nature of efficient computation, and it is somewhat controversial.

#### The Cobham-Edmonds Thesis

- Efficient runtimes:
  - 4n + 13
  - $n^3 2n^2 + 4n$
  - n log log n
- "Efficient" runtimes:
  - n<sup>1,000,000,000,000</sup>
  - 10<sup>500</sup>

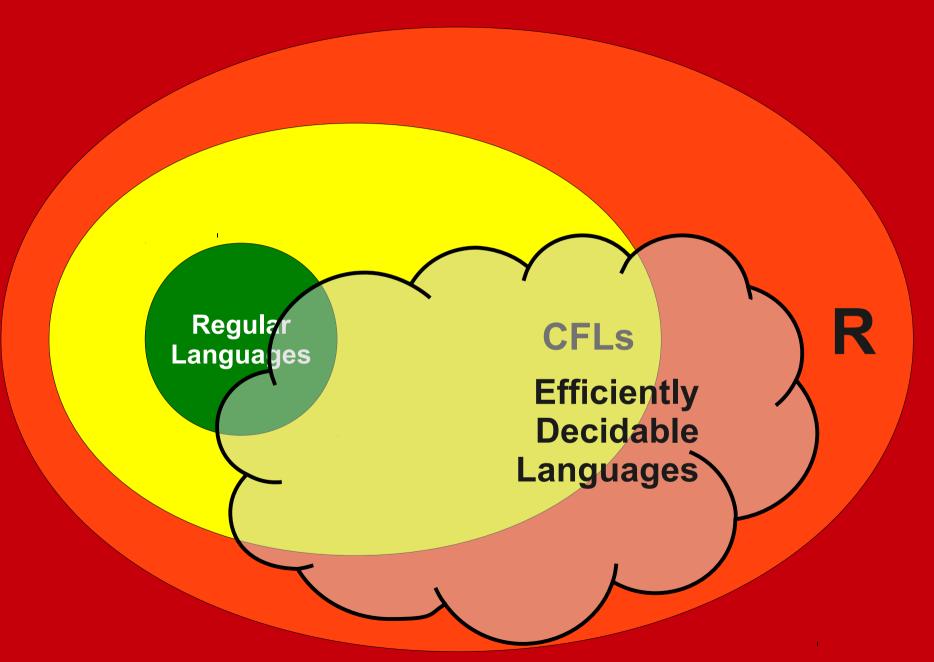
- Inefficient runtimes:
  - 2<sup>n</sup>
  - n!
  - *n*<sup>n</sup>
- "Inefficient" runtimes:
  - $n^{0.0001 \log n}$
  - $1.00000001^n$

# The Complexity Class **P**

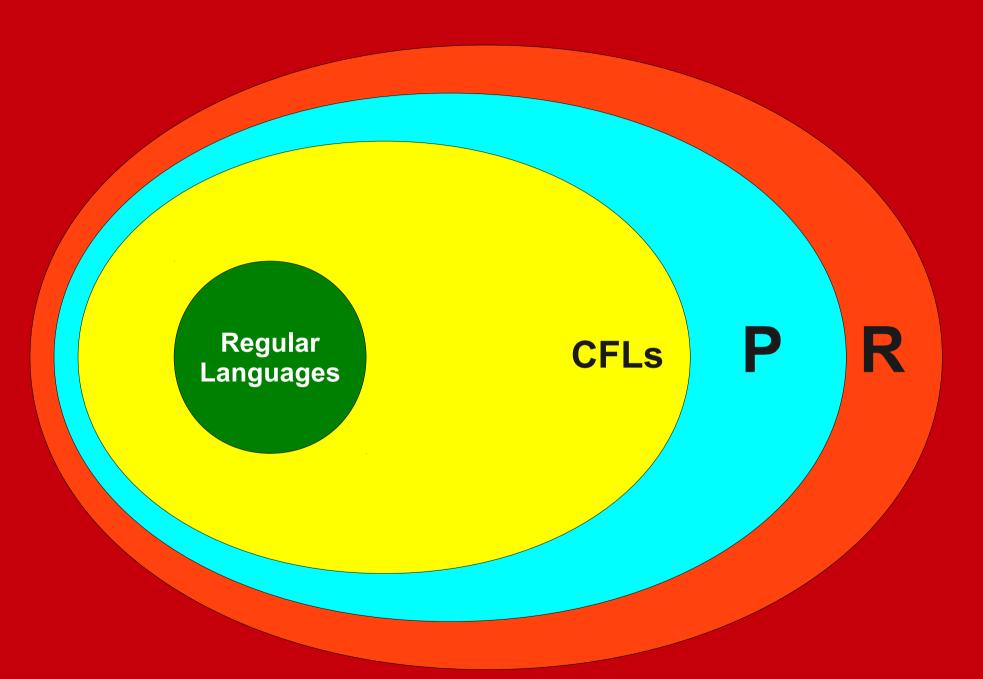
- The **complexity class P** (for **p**olynomial time) contains all problems that can be solved in polynomial time.
- Formally:
  - $\mathbf{P} = \{ L \mid \text{There is a polynomial-time decider for } L \}$
- Assuming the Cobham-Edmonds thesis, a language is in P iff it can be decided efficiently.

## Examples of Problems in **P**

- All regular languages are in **P**.
  - All have linear-time TMs.
- All CFLs are in **P**.
  - Requires a more nuanced argument (the *CYK algorithm* or *Earley's algorithm*.)
- Many other problems are in P.
  - More on that in a second.



**Undecidable Languages** 



**Undecidable Languages**