Three-Address Code IR

## Announcements

- Programming Project 3 due Monday at 11:59PM.
- OH today after lecture.
- Ask questions on Piazzza!
- Ask questions via email!
- Checkpoint feedback will be returned soon.


## Where We Are

| Lexical Analysis |
| :---: |
| Syntax Analysis |
| Semantic Analysis |
| IR Generation |
| IR Optimization |
| Code Generation |
| Optimization | Code

## Overview for Today

- The Final Assignment
- Introduction to TAC:
- TAC for simple expressions.
- TAC for functions and function calls.
- TAC for objects.
- TAC for arrays.
- Generating TAC.
- A few low-level details.


## The Final Assignment

- Goal: Generate TAC IR for Decaf programs.
- We provide a code generator to produce MIPS assembly.
- You can run your programs using spim, the MIPS simulator.
- You must also take care of some low-level details:
- Assign all parameters, local variables, and temporaries positions in a stack frame.
- Assign all global variables positions in the global memory segment.
- Assign all fields in a class an offset from the base of the object.
- You should not need to know MIPS to do this; all details will be covered in lecture.
- If you have any questions on MIPS, please feel to ask!


## An Important Detail

- When generating IR at this level, you do not need to worry about optimizing it.
- It's okay to generate IR that has lots of unnecessary assignments, redundant computations, etc.
- We'll see how to optimize IR code later this week and at the start of next week.
- It's tricky, but extremely cool!


## Three-Address Code

- Or "TAC"
- The IR that you will be using for the final programming project.
- High-level assembly where each operation has at most three operands.
- Uses explicit runtime stack for function calls.
- Uses vtables for dynamic dispatch.


## Sample TAC Code

$$
\begin{aligned}
& \text { int } x ; \\
& \text { int } y ; \\
& \text { int } x 2=x * x ; \\
& \text { int } y 2=y * y ; \\
& \text { int } r 2=x 2+y 2 ;
\end{aligned}
$$



## Sample TAC Code

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& \text { int } x 2=x * x ; \\
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& \text { int } r 2=x 2+y 2 ;
\end{aligned}
$$

## Sample TAC Code

$$
\begin{aligned}
& \text { int } \mathrm{a} ; \\
& \text { int } \mathrm{b} ; \\
& \text { int } \mathrm{c} ; \\
& \text { int } \mathrm{d} ; \\
& \mathrm{a}=\mathrm{b}+\mathrm{c}+\mathrm{d} ; \\
& \mathrm{b}=\mathrm{a} * \mathrm{a}+\mathrm{b} * \mathrm{~b} ;
\end{aligned}
$$



## Sample TAC Code

$$
\begin{aligned}
& \text { int } \mathrm{a} ; \\
& \text { int } \mathrm{b} ; \\
& \text { int } \mathrm{c} ; \\
& \text { int } \mathrm{d} ; \\
& \mathrm{a}=\mathrm{b}+\mathrm{c}+\mathrm{d} ; \\
& \mathrm{b}=\mathrm{a} * \mathrm{a}+\mathrm{b} * \mathrm{~b} ;
\end{aligned}
$$

$$
\begin{aligned}
& t 0=b+c i \\
& \bar{a}=-t 0+d ; \\
& t 1=a * a ; \\
& \overline{t 2}=b * b ; \\
& \bar{b}=-t 1+\operatorname{t2}
\end{aligned}
$$

## Sample TAC Code

$$
\begin{aligned}
& \text { int } \mathrm{a} ; \\
& \text { int } \mathrm{b} ; \\
& \text { int } \mathrm{c} ; \\
& \text { int } \mathrm{d} ; \\
& \mathrm{a}=\mathrm{b}+\mathrm{c}+\mathrm{d} ; \\
& \mathrm{b}=\mathrm{a} * \mathrm{a}+\mathrm{b} * \mathrm{~b} ;
\end{aligned}
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$$
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& t 0=b+c i \\
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& t 1=a * a ; \\
& \overline{t 2}=b * b ; \\
& \bar{b}=-t 1+\operatorname{t2}
\end{aligned}
$$

## Temporary Variables

- The "three" in "three-address code" refers to the number of operands in any instruction.
- Evaluating an expression with more than three subexpressions requires the introduction of temporary variables.
- This is actually a lot easier than you might think; we'll see how to do it later on.


## Sample TAC Code

```
int a;
int b;
a=5 + 2 * b;
```



## Sample TAC Code

$$
\begin{aligned}
& \text { int } \mathrm{a} ; \\
& \text { int } \mathrm{b} ; \\
& \mathrm{a}=5+2 * \mathrm{~b}
\end{aligned}
$$

$$
\begin{aligned}
& t 0=5 ; \\
& \mathrm{t} 1=2 * \mathrm{~b} \\
& \overline{\mathrm{a}}=-\mathrm{t0}+\mathrm{t} 1 ;
\end{aligned}
$$

## Sample TAC Code

$$
\begin{aligned}
& \text { int } \mathrm{ai} \\
& \text { int } \mathrm{b} ; \\
& \mathrm{a}=5+2 * \mathrm{~b}
\end{aligned}
$$

TAC allows for instructions with two operands.

$$
\begin{aligned}
& t 0=5 ; \\
& -\mathrm{t} 1=2 * \mathrm{~b} ; \\
& \mathrm{a}=-\mathrm{t} 0+\ldots \mathrm{t} 1 ;
\end{aligned}
$$

## Simple TAC Instructions

- Variable assignment allows assignments of the form
- var $=$ constant;
- $\operatorname{var}_{1}=\operatorname{var}_{2}$;
- $\operatorname{var}_{1}=\operatorname{var}_{2}$ op $\operatorname{var}_{3}$;
- $\operatorname{var}_{1}=$ constant op $\operatorname{var}_{2}$;
- $\operatorname{var}_{1}=\operatorname{var}_{2}$ op constant;
- var $=$ constant $_{1}$ op constant ${ }_{2}$;
- Permitted operators are $+,-, *, /, \%$.
- How would you compile $\mathbf{y}=-\mathbf{x}$; ?


## Simple TAC Instructions

- Variable assignment allows assignments of the form
- var $=$ constant;
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- $\operatorname{var}_{1}=$ constant op $\operatorname{var}_{2}$;
- $\operatorname{var}_{1}=\operatorname{var}_{2}$ op constant;
- $\operatorname{var}=$ constant $_{1}$ op constant ${ }_{2}$;
- Permitted operators are $+,-, *, /, \%$.
- How would you compile $\mathbf{y}=-\mathbf{x}$; ?

$$
y=0-x ; \quad y=-1 * x ;
$$

## One More with bools

int $x$;
int $y$;
bool b1;
bool b2;
bool b3;
b1 $=x+x<y$
b2 $=x+x==y$
b3 $=x+x>y$

## One More with bools

$$
\begin{aligned}
& \text { int } x \text {; } \\
& \text { int y; } \\
& \text { bool b1; } \\
& \text { bool b2; } \\
& \text { bool b3; } \\
& \text { b1 }=x+x<y \\
& \text { b2 }=x+x==y \\
& \text { b3 }=x+x>y
\end{aligned}
$$

$$
\begin{aligned}
& \text { _t0 = } \mathbf{x}+\mathbf{x} \text {; } \\
& \text { _t1 = y; } \\
& \overline{\mathrm{b}} 1 \mathrm{=} \text { _t0 < _t1; } \\
& \text { _t2 = } \mathbf{x}+\mathbf{x} \text {; } \\
& \text { _t3 = y; } \\
& \overline{\mathrm{b}} 2=\text { _t2 == _t3; } \\
& \text { _t4 = x + x; } \\
& \text { _t5 = y; } \\
& \text { b3 = _t5 < _t4; }
\end{aligned}
$$

## TAC with bools

- Boolean variables are represented as integers that have zero or nonzero values.
- In addition to the arithmetic operator, TAC supports $<,==, \mid I$, and $\& \&$.
- How might you compile $\mathrm{b}=(\mathrm{x}<=\mathrm{y})$ ?


## TAC with bools

- Boolean variables are represented as integers that have zero or nonzero values.
- In addition to the arithmetic operator, TAC supports $<,==, \mid I$, and $\& \&$.
- How might you compile $\mathrm{b}=(\mathrm{x}<=\mathrm{y})$ ?

$$
\begin{aligned}
& \text { _t0 = x < y; }
\end{aligned}
$$

## Control Flow Statements

$$
\begin{aligned}
& \text { int } x ; \\
& \text { int } y ; \\
& \text { int } z ; \\
& \text { if }(x<y) \\
& z=x ; \\
& \text { else } \\
& \quad z=Y ; \\
& z=z * z ;
\end{aligned}
$$



## Control Flow Statements

$$
\begin{aligned}
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& z=x ; \\
& \text { else } \\
& \quad z=y ; \\
& z=z * z ;
\end{aligned}
$$

## Labels

- TAC allows for named labels indicating particular points in the code that can be jumped to.
- There are two control flow instructions:
- Goto label;
- IfZ value Goto label;
- Note that Ifz is always paired with Goto.


## Control Flow Statements

$$
\begin{aligned}
& \text { int } x ; \\
& \text { int } y ; \\
& \text { while }(x<y) \\
& \quad x=x * 2 ; \\
& \} \\
& y=x ;
\end{aligned}
$$



## Control Flow Statements

```
int x;
int y;
while (x<y) {
while (x<y) {
while (x<y) {
y = x;
```

_L0:

## A Complete Decaf Program

```
void main() {
    int x, y;
    int m2 = x * x + y * y;
    while (m2 > 5) {
        m2 = m2 - x;
    }
}
```


## A Complete Decaf Program

```
void main() {
    int x, y;
    int m2 = x * x + y * y;
    while (m2 > 5) {
        m2 = m2 - x;
    }
```

main:
BeginFunc 24 ;
$\begin{aligned} t 0 & =x * x ; \\ -t 1 & =y * y ;\end{aligned}$
$\overline{\mathrm{m}} 2=$ t0 + t1;
L0:
$\mathrm{t} 2=5<\mathrm{m} 2 ;$
$\mathrm{IfZ} Z \mathrm{t} 2$ Goto $\mathrm{L} 1 ;$
$\mathrm{m} 2=\mathrm{m} 2-\mathrm{x} ;$
Goto _L0;
_L1:
EndFunc;

## A Complete Decaf Program

```
void main() {
    int x, y;
    int m2 = x * x + y * y;
    while (m2 > 5) {
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Goto _L0;
L1:
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## A Complete Decaf Program

```
void main() {
    int x, y;
    int m2 = x * x + y * y;
    while (m2 > 5) {
        m2 = m2 - x;
    }
```

main:
BeginFunc 24 ;
$\begin{aligned} \mathrm{t0} & =\mathrm{x} * \mathrm{x} ; \\ \mathrm{z}_{\mathrm{t}} & =\mathrm{y} * \mathrm{y} \text {; }\end{aligned}$
$\overline{\mathrm{m}} 2=$ _t0 + t1;
L0:
$\mathrm{t2}=5<\mathrm{m} 2 ;$
$\mathrm{IfZ}-\mathrm{t2}$ Goto $\mathrm{L} 1 ;$
$\mathrm{m} 2=\mathrm{m} 2-\mathrm{x} ;$
Goto _L0;
_L1:
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## A Complete Decaf Program

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void main() {
    int x, y;
    int m2 = x * x + y * y;
    while (m2 > 5) {
        m2 = m2 - x;
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main:
BeginFunc 24 ;
t0 $=\mathbf{x} * x$;
-t1 $=y * y$;
$\overline{\mathrm{m}} 2=$ t0 + t1;
L0:
t2 $=5<\mathrm{m} 2$;
IfZ _t2 Goto _L1;
m2 = m2 - x ;
Goto _L0;
L1:
EndFunc;

## Compiling Functions

- Decaf functions consist of four pieces:
- A label identifying the start of the function.
- (Why?)
- A BeginFunc $N$; instruction reserving $\mathbf{N}$ bytes of space for locals and temporaries.
- The body of the function.
- An EndFunc ; instruction marking the end of the function.
- When reached, cleans up stack frame and returns.


## A Logical Decaf Stack Frame



## A Logical Decaf Stack Frame



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## A Logical Decaf Stack Frame



## A Logical Decaf Stack Frame



## A Logical Decaf Stack Frame

| Stack frame for function $f(a, \ldots, n)$ | Param N |
| :---: | :---: |
|  | Param N - 1 |
|  | ... |
|  | Param 1 |
|  | Storage for |
|  | Locals and |
|  | Temporaries |
|  | Param M |
| Stack frame for | ... |
|  | Param 1 |
| function | Storage for |
| $g(a, \ldots, m)$ | Locals and |
|  | Temporaries |

## A Logical Decaf Stack Frame



## A Logical Decaf Stack Frame



## A Logical Decaf Stack Frame



## Compiling Function Calls

}
void main() {
SimpleFunction(137);
}

```
```

```
void SimpleFn(int z) {
```

```
void SimpleFn(int z) {
    int x, y;
    int x, y;
    x = x * y * z;
```

    x = x * y * z;
    ```

\section*{Compiling Function Calls}
```

void SimpleFn(int z) {
int x, y;
x = x * y * z;
}
void main() {
SimpleFunction(137);
}

```
_SimpleFn: BeginFunc 16; _t0 = x * y ; \(\overline{\mathrm{x}}=\mathrm{t}=\mathrm{t} \mathrm{I}^{\mathrm{I}}\); \({ }^{\mathrm{t}} \mathrm{z}\);
EndFunc;

\section*{Compiling Function Calls}
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void SimpleFn(int z) {
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_SimpleFn: BeginFunc 16; _t0 = x * \(y\); \(\overline{\mathrm{x}}=\mathrm{t}=\mathrm{t} \overline{\mathrm{I}}^{\mathrm{t}}\); \({ }^{\mathrm{t}} \mathrm{z}\);
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\section*{Compiling Function Calls}
```

void SimpleFn(int z) {
int x, Y;
X = X * Y * z;
}
void main() {
SimpleFunction(137);

```
_SimpleFn:
    BeginFunc 16;
    _t0 \(=x * y\);

    EndFunc;
main:
    BeginFunc 4;
    _七0 = 137;
    PushParam to;
    LCall _SimpleFn;
    PopParams 4;
    EndFunc;

\section*{Compiling Function Calls}
```

void SimpleFn(int z) {
int x, y;
X = X * Y * z;
}
void main() {
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```
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\section*{Compiling Function Calls}
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    LCall SimpleFn;
    PopParams 4;
    EndFunc;

\section*{Compiling Function Calls}
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    _t0 = 137;
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\section*{Compiling Function Calls}
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_SimpleFn:
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    EndFunc;
main:
    BeginFunc 4;
    _七0 = 137;
    PushParam to;
    LCall _SimpleFn;
    PopParams 4;
    EndFunc;

\section*{Stack Management in TAC}
- The BeginFunc \(\boldsymbol{N}\); instruction only needs to reserve room for local variables and temporaries.
- The EndFunc; instruction reclaims the room allocated with BeginFunc \(N\);
- A single parameter is pushed onto the stack by the caller using the PushParam var instruction.
- Space for parameters is reclaimed by the caller using the PopParams \(N\); instruction.
- \(N\) is measured in bytes, not number of arguments.

\section*{A Logical Decaf Stack Frame}


\section*{A Logical Decaf Stack Frame}


PushParam var;

\section*{A Logical Decaf Stack Frame}


PushParam var;
PushParam var;

\section*{A Logical Decaf Stack Frame}


PushParam var;
PushParam var;
PushParam var;

\section*{A Logical Decaf Stack Frame}


\section*{A Logical Decaf Stack Frame}


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\section*{A Logical Decaf Stack Frame}


\section*{Storage Allocation}
- As described so far, TAC does not specify where variables and temporaries are stored.
- For the final programming project, you will need to tell the code generator where each variable should be stored.
- This normally would be handled during code generation, but Just For Fun we thought you should have some experience handling this. ©

\section*{The Frame Pointer}

\author{
Param N \\ Param N - 1 \\ Param 1 \\ Storage for \\ Locals and \\ Temporaries
}

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Param N \\ Param N - 1 \\ Param 1 \\ Storage for \\ Locals and \\ Temporaries
}

\section*{The Frame Pointer}
\begin{tabular}{|l|}
\hline Param N \\
\hline Param \(\mathrm{N}-1\) \\
\hline\(\ldots\) \\
\hline Param 1 \\
\hline Storage for \\
Locals and \\
Temporaries \\
\hline Param M \\
\hline Param 1 \\
\hline
\end{tabular}

\section*{Frame}

Param 1

\section*{The Frame Pointer}
\begin{tabular}{|l|l|}
\hline & \begin{tabular}{l} 
Param N \\
Param N - 1
\end{tabular} \\
\(\ldots\) & \begin{tabular}{l} 
Param 1
\end{tabular} \\
\hline \begin{tabular}{l} 
Storage for \\
Locals and \\
Temporaries
\end{tabular} \\
\hline Param M
\end{tabular}

\section*{The Frame Pointer}
\begin{tabular}{|c|c|}
\hline & Param N \\
\hline & Param N - 1 \\
\hline & \(\ldots\) \\
\hline & Param 1 \\
\hline & Storage for Locals and Temporaries \\
\hline & Param M \\
\hline & ... \\
\hline Frame & Param 1 \\
\hline \multirow[t]{3}{*}{Pointer} & Storage for \\
\hline & Locals and \\
\hline & Temporaries \\
\hline
\end{tabular}

\section*{The Frame Pointer}
\begin{tabular}{|l|l|}
\hline & Param N \\
& Param N - 1 \\
& \(\ldots\) \\
& Param 1 \\
& \begin{tabular}{l} 
Storage for \\
Locals and \\
Temporaries
\end{tabular} \\
\hline & Param M \\
& Param 1 \\
\hline Frame \\
Pointer
\end{tabular}\(\longrightarrow\)\begin{tabular}{l} 
\\
\hline
\end{tabular}

\section*{The Frame Pointer}

\author{
Param N \\ Param N - 1 \\ Param 1 \\ Storage for \\ Locals and \\ Temporaries
}

\section*{Frame \\ Pointer}

\section*{The Frame Pointer}

\author{
Param N \\ Param N - 1 \\ Param 1 \\ Storage for \\ Locals and \\ Temporaries
}

\section*{Logical vs Physical Stack Frames}

\author{
Param N \\ Param N - 1 \\ Param 1 \\ Storage for \\ Locals and \\ Temporaries
}

\section*{Logical vs Physical Stack Frames}
\begin{tabular}{|c|}
\hline Param N \\
\hline Param \(\mathrm{N}-1\) \\
\hline\(\ldots\) \\
\hline Param 1 \\
\hline Storage for \\
Locals and \\
Temporaries \\
\hline
\end{tabular}
\begin{tabular}{|c|}
\hline Param N \\
\hline Param N-1 \\
\hline Param 1 \\
\hline fp of caller \\
\hline Storage for \\
Locals and \\
Temporaries \\
\hline
\end{tabular}

\section*{Logical vs Physical Stack Frames}
\begin{tabular}{|l|}
\hline Param N \\
\hline Param \(\mathrm{N}-1\) \\
\hline\(\ldots\) \\
\hline Param 1 \\
\hline Storage for \\
Locals and \\
Temporaries \\
\hline
\end{tabular}
\begin{tabular}{|c|}
\hline Param N \\
\hline Param \(\mathrm{N}-1\) \\
\hline Param 1 \\
\hline fp of caller \\
\hline Storage for \\
Locals and \\
Temporaries \\
\hline
\end{tabular}

\section*{Frame Pointer}

\section*{(Mostly) Physical Stack Frames}

\author{
Param N \\ Param 1 \\ fp of caller \\ Storage for \\ Locals and \\ Temporaries
}

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\author{
Param N \\ Param 1 \\ fp of caller \\ Storage for \\ Locals and \\ Temporaries
}

\section*{The Stored Return Address}
- Internally, the processor has a special register called the program counter (PC) that stores the address of the next instruction to execute.
- Whenever a function returns, it needs to restore the PC so that the calling function resumes execution where it left off.
- The address of where to return is stored in MIPS in a special register called ra ("return address.")
- To allow MIPS functions to call one another, each function needs to store the previous value of ra somewhere.

\section*{Physical Stack Frames}

\author{
Param N \\ Param 1 \\ fp of caller \\ ra of caller \\ Locals and \\ Temporaries
}

\author{
Frame Pointer
}

\section*{Physical Stack Frames}
\begin{tabular}{|c|}
\hline Param N \\
\hline Param 1 \\
\hline fp of caller \\
ra of caller \\
\hline Locals and \\
Temporaries \\
\hline Param N \\
\hline\(\ldots\) \\
\hline Param 1 \\
\hline
\end{tabular}

\section*{Frame Pointer}

\section*{Physical Stack Frames}


\section*{Physical Stack Frames}


\section*{Physical Stack Frames}
\begin{tabular}{|c|c|}
\hline & Param N \\
\hline & \\
\hline & Param 1 \\
\hline & \({ }_{\text {fp of caller }}\) \\
\hline & ra of caller \\
\hline & Temporaries \\
\hline & Param N \\
\hline & Param 1 \\
\hline Frame & fp of caller \(^{\text {a }}\) \\
\hline Pointer & ra of caller \\
\hline
\end{tabular}

\section*{Physical Stack Frames}
\begin{tabular}{|c|c|}
\hline & Param N \\
\hline & Param 1 \\
\hline & \({ }^{\text {sp }}\) of caller \\
\hline & ra of caller
Locals and
a \\
\hline & \({ }_{\substack{\text { Locals and } \\ \text { Temporaries }}}^{\text {Led }}\) \\
\hline & Param N \\
\hline & Param 1 \\
\hline Pointer & Ep of caller \\
\hline & \(x\) a of caller \\
\hline & Locals and
Temporaries \\
\hline
\end{tabular}

\section*{So What?}
- In your code generator, you must assign each local variable, parameter, and temporary variable its own location.
- These locations occur in a particular stack frame and are called fp-relative.
- Parameters begin at address fp +4 and grow upward.
- Locals and temporaries begin at address fp - 8 and grow downward
\begin{tabular}{|c|c|}
\hline Param N & \(\mathbf{f p}+\mathbf{4 N}\) \\
\cline { 1 - 1 }\(\ldots\) & \(\ldots\) \\
\hline Param 1 & \(\mathbf{f p}+\mathbf{4}\) \\
\cline { 1 - 1 } fp of caller & \(\mathbf{f p}+\mathbf{0}\) \\
\cline { 1 - 1 } ra of caller & \(\mathbf{f p}-\mathbf{4}\) \\
\cline { 1 - 1 } Local 0 & \(\mathbf{f p}-\mathbf{8}\) \\
\cline { 1 - 1 }\(\ldots\) & \(\ldots\) \\
\hline Local M & \(\mathbf{f p}-\mathbf{4}-\mathbf{4 M}\) \\
\hline
\end{tabular}

\section*{From Your Perspective}

Location* location = new Location(fpRelative, +4, locName);

\section*{From Your Perspective}

Location* location = new Location(fpRelative, +4, locName);

\section*{From Your Perspective}

Location* location = new Location(fpRelative, +4, locName);

What variable does this refer to?

\title{
And One More Thing...
}
```

int globalVariable;
int main() {
globalVariable = 137;
}

```

\section*{And One More Thing...}
```

int globalVariable;
int main() {
globalVariable = 137;
}

```

\section*{And One More Thing...}
dint globalVariable;
int main() \{
globalVariable = 137;
\}

Where is this stored?

\section*{The Global Pointer}
- MIPS also has a register called the global pointer (gp) that points to globally accessible storage.
- Memory pointed at by the global pointer is treated as an array of values that grows upward.
- You must choose an offset into this array for each global variable. Global Variable \(\mathrm{N} \operatorname{gp}+4 \mathrm{~N}\)

Global Variable \(1 \quad \mathbf{g p}+\mathbf{4}\)
gp \(\longrightarrow\) Global Variable \(0 \quad\) gp + \(\mathbf{0}\)

\section*{From Your Perspective}

Location* global = new Location(gpRelative, +8, locName);

\section*{From Your Perspective}

Location* global = new Location(gpRelative, +8, locName);

\section*{Summary of Memory Layout}
- Most details abstracted away by IR format.
- Remember:
- Parameters start at fp + 4 and grow upward.
- Locals start at fp-8 and grow downward.
- Globals start at \(\mathbf{g p}+\mathbf{0}\) and grow upward.
- You will need to write code to assign variables to these locations.

\section*{TAC for Objects, Part I}
```

class A {
void fn(int x) {
int y;
y = x;
}
}
int main() {
A a;
a.fn(137);
}

```

\section*{TAC for Objects, Part I}
```

class A {
void fn(int x) {
int y;
y = x;
}
}
int main() {
A a;
a.fn(137);

```
\}
A.fn:

BeginFunc 4;
\(\mathrm{y}=\mathrm{x}\);
EndFunc;
main:
BeginFunc 8;
t0 = 137;
PushParam _t0;
PushParam a;
LCall_A.fn;
PopParams 8; EndFunc;

\section*{TAC for Objects, Part I}
```

class A {
void fn(int x) {
int y;
y = x;
}
}
int main() {
A a;
a.fn(137);
}

```
A.fn:
    BeginFunc 4;
    \(\mathrm{Y}=\mathrm{x}\);
    EndFunc;
main:
BeginFunc 8;
_t0 = 137;
PushParam _t0;
PushParam a;
LCall_A.fn;
PopParams 8; EndFunc;

\section*{A Reminder: Object Layout}
\begin{tabular}{|c|}
\hline Vtable* \\
\hline Field 0 \\
\hline\(\ldots\) \\
\hline Field N \\
\hline
\end{tabular}
Method 0
Method 1
...
Method K
\begin{tabular}{|c|}
\hline Vtable* \\
\hline Field 0 \\
\hline\(\ldots\) \\
\hline Field N \\
\hline Field 0 \\
\hline\(\ldots\) \\
\hline Field M \\
\hline
\end{tabular}
\begin{tabular}{c} 
Method 0 \\
Method 1 \\
\(\ldots\) \\
Method K \\
Method 0 \\
\(\ldots\) \\
Method L \\
\hline
\end{tabular}


\section*{TAC for Objects, Part II}
```

class A {
int y;
int z;
void fn(int x) {
y = x;
X = Z;
}
}
int main() {
A a;
a.fn(137);
}

```

\section*{TAC for Objects, Part II}
```

class A {
int y;
int z;
void fn(int x) {
y = x;
x = z;
}
int main() {
A a;
a.fn(137);

```
_A.fn:
BeginFunc 4;
* (this +4 ) \(=x\);
\(\mathbf{x}=\) * (this +8 ); EndFunc;
main:
BeginFunc 8; t0 = 137;
PushParam _t0;
PushParam a;
LCall_A.fn;
PopParams 8;
EndFunc;

\section*{TAC for Objects, Part II}
```

class A {
int y;
int z;
void fn(int x) {
y = x;
x = z;
}
int main() {
A a;
a.fn(137);

```
A.fn:
    BeginFunc 4;
    * (this +4 ) \(=\mathrm{x}\);
    \(\mathbf{x}=\) * (this +8 );
    EndFunc;
main:
BeginFunc 8; t0 = 137;
PushParam _t0;
PushParam a;
LCall_A.fn;
PopParams 8;
EndFunc;

\section*{TAC for Objects, Part II}
```

class A {
int y;
int z;
void fn(int x) {
y = x;
x = z;
}
int main() {
A a;
a.fn(137);

```
A.fn:

BeginFunc 4;
* (this +4 ) \(=\mathrm{x}\);
\(\mathbf{x}=\) * (this +8 ); EndFunc;
main:
BeginFunc 8; t0 = 137;
PushParam _t0;
PushParam a;
LCall_A.fn;
PopParams 8;
EndFunc;

\section*{Memory Access in TAC}
- Extend our simple assignments with memory accesses:
- \(\operatorname{var}_{1}=\) *var \(_{2}\)
- \(\operatorname{var}_{1}=*\left(\operatorname{var}_{2}+\right.\) constant \()\)
- *var var \(_{1}\)
- *(var \(\operatorname{van}_{1}\) constant \()=\operatorname{var}_{2}\)
- You will need to translate field accesses into relative memory accesses.

\section*{TAC for Objects, Part III}
```

class Base {
void hi() {
Print("Base");
}
}
class Derived extends Base{
void hi() {
Print("Derived");
}
}
int main() {
Base b;
b = new Derived;
b.hi();
}

```

\section*{TAC for Objects, Part III}
```

class Base {
void hi() {
Print("Base");
}
}
class Derived extends Base{
void hi() {
Print("Derived");
}
}
int main() {
Base b;
b = new Derived;
b.hi();
}

```

\section*{TAC for Objects, Part III}
```

class Base {
void hi() {
Print("Base");
}
}
class Derived extends Base{
void hi() {
Print("Derived");
}
}
int main() {
Base b;
b = new Derived;
b.hi();
}

```
    _Base.hi:
    BeginFunc 4;
        _t0 = "Base";
        PushParam to;
        LCall _PrintString;
        PopParams 4;
    EndFunc;
    Vtable Base = _Base.hi,
    ;
    _Derived.hi:
    BeginFunc 4;
        _t0 = "Derived";
    PushParam _t0;
        LCall _PrintString;
        PopParams 4;
    EndFunc;
Vtable Derived = _Derived.hi,

\section*{TAC for Objects, Part III}
```

class Base {
void hi() {
Print("Base");
}
}
class Derived extends Base{
void hi() {
Print("Derived");
}
}
int main() {
Base b;
b = new Derived;
b.hi();
}

```
    _Base.hi:
        BeginFunc 4;
        _t0 = "Base";
        PushParam to;
        LCall _PrintString;
        PopParams 4;
    EndFunc;
    Vtable Base = _Base.hi,
    ;
    _Derived.hi:
    BeginFunc 4;
    _t0 = "Derived";
    PushParam _t0;
    LCall _PrintString;
    PopParams 4;
    EndFunc;
Vtable Derived = _Derived.hi,

\section*{TAC for Objects, Part III}
```

class Base {
void hi() {
Print("Base");
}
}
class Derived extends Base{
void hi() {
Print("Derived");
}
}
int main() {
Base b;
b = new Derived;
b.hi();
}

```

\section*{TAC for Objects, Part III}
```

class Base {
void hi() {
Print("Base");
}
}
class Derived extends Base{
void hi() {
Print("Derived");
}
}
int main() {
Base b;
b = new Derived;
b.hi();
}

```
main:
BeginFunc 20;
\[
\text { _t0 }=4 ;
\]
PushParam _t0;
\[
\mathrm{b}=\mathrm{LCall} \text { _Alloc; }
\]
\[
\text { PopParams } \overline{4}
\]
_t1 = Derived;
\[
\bar{\star}_{\mathrm{b}}=-\mathrm{t} 1 ;
\]
\[
-\mathrm{t} 2=-* \mathrm{~b}
\]
\[
\text { t } 3=* \text { t2 }
\]
PushParam b;
ACall _t3;
PopParäms 4;
EndFunc ;

\section*{TAC for Objects, Part III}
```

class Base {
void hi() {
Print("Base");
}
}
class Derived extends Base{
void hi() {
Print("Derived");
}
}
int main() {
Base b;
b = new Derived;
b.hi();
}

```
main:
BeginFunc 20;
\[
\text { _t0 }=4 ;
\]

PushParam _t0;
b = LCall _Alloc;
PopParams \(\overline{4}\);
_t1 = Derived;
\({ }^{*} \mathrm{~b}=-\mathrm{t} 1\);
_t2 \(={ }^{-}\)* b ;
_t3 = *_t2;
PushParām b;
ACall _t3;
PopParams 4;
EndFunc;
\[
\begin{gathered}
\text { What's going } \\
\text { on here? }
\end{gathered}
\]

\section*{Dissecting TAC}
```

int main() {
Base b;
b = new Derived;
b.hi () ;
}

```
main:
BeginFunc 20;
\[
\text { to }=4 ;
\]

PushParam to;
b = LCall Alloc;
PopParams 4;
_t1 = Derived;
\({ }^{*} \mathrm{~b}=\) t1;
t2 \(=\) * b ;
_t3 \(=\) *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi() ;
}

```
main:
BeginFunc 20;
\[
\text { to }=4 ;
\]

PushParam to;
b = LCall Alloc; PopParams \(\overline{4}\);
_t1 = Derived;
\({ }^{*} \mathrm{~b}=\) t1;
\(-\mathrm{t} 2={ }^{*} \mathrm{~b}\);
_t3 = *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

fp of caller
ra of caller
```

int main() {

```
int main() {
    Base b;
    Base b;
    b = new Derived;
    b = new Derived;
    b.hi() ;
```

    b.hi() ;
    ```
\}
main:
    BeginFunc 20;
        t0 \(=4\);
    PushParam to;
    b = LCall Alloc;
    PopParams \(\overline{4}\);
    _t1 = Derived;
    \(\bar{*}_{b}=-t 1 ;\)
    \(-t 2=-* b\);
    _t3 \(=\) *_t2;
    PushParam b;
    ACall _t3;
    PopParams 4;
    EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi() ;

```
fp of caller
main:
BeginFunc 20;
\[
\text { to }=4 ;
\]

PushParam to;
b = LCall Alloc; PopParams \(\overline{4}\);
_t1 = Derived;
\({ }^{*} \mathrm{~b}=-\mathrm{t} 1\);
- \(2=* \mathrm{~b}\);
_t3 \(=\) *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {

```
int main() {
    Base b;
    Base b;
    b = new Derived;
    b = new Derived;
    b.hi();
```

    b.hi();
    ```
\}
main:
    BeginFunc 20;
    _t0 \(=4\);
    PushParam to;
    b = LCall Alloc;
    PopParams \(\overline{4}\);
    _t1 = Derived;
    \(\bar{*}_{\mathrm{b}}=\) _t1;
    _t2 \(={ }^{*}\) b;
    _t3 = *_t2;
    PushParam b;
    ACall _t3;
    PopParams 4;
    EndFunc;

\section*{Dissecting TAC}

```

int main() {

```
int main() {
    Base b;
    Base b;
    b = new Derived;
    b = new Derived;
    b.hi();
```

    b.hi();
    ```
\}
main:
BeginFunc 20; t0 = 4; PushParam _t0; b = LCall Alloc; PopParams \(\overline{4}\);
_t1 = Derived;
*b \(=\) _ t ;
_t2 \(=\) *b;
_t3 = *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20; _t0 = 4; PushParam _t0; b = LCall Alloc; PopParams \(\overline{4}\);
_t1 = Derived;
*b \(=\) _t1;
_t2 \(=\) *b;
_t3 = *_t2;
PushParam b;
ACall _t3; PopParams 4; EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
\[
\text { _t0 }=4 ;
\]
PushParam to;
\[
\mathrm{b}=\mathrm{LCall} \text { _Alloc; }
\]
\[
\text { PopParams } \overline{4}
\]
til = Derived;
\[
\bar{*} \mathrm{~b}=\mathrm{t} 1 ;
\]
\[
\text { _t2 }=\star \mathrm{t} \text {; }
\]
\[
\text { _t } 3=\text { *_t2; }
\]
PushParām b;
ACall _t3;
PopParäms 4;
EndFunc ;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
\[
\text { _t0 }=4 ;
\]
PushParam to;
\[
\mathrm{b}=\mathrm{LCall} \text { _Alloc; }
\]
\[
\text { PopParams } 4 ;
\]
til = Derived;
\[
\bar{*} \mathrm{~b}=-\mathrm{t} 1 ;
\]
\[
\text { t2 }=\star \mathrm{b} \text {; }
\]
_t3 = *_t2;
PushParām b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
_t0 = 4;
PushParam _t0;
\[
\mathrm{b}=\mathrm{LCall} \text { _Alloc; }
\]
\[
\text { PopParams } \overline{4}
\]
til = Derived;
\[
\bar{\star}_{\mathrm{b}}=\mathrm{t} 1 ;
\]
\[
\text { _t2 }=\star \mathrm{t} \text {; }
\]
_t3 = *_t2;
PushParām b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
_t0 = 4;
PushParam _t0;
b = LCall Alloc; PopParams \(\overline{4}\);
_t1 = Derived;
\(\bar{*} \mathrm{~b}=\) _ t ;
_t2 = *b;
_t3 = *_t2;
PushParam b;
ACall _t3; PopParams 4; EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
_t0 = 4;
PushParam to;
b = LCall Alloc; PopParams \(\overline{4}\);
_t1 = Derived;
\(\bar{*} \mathrm{~b}=\) _ t ;
_t2 = *b;
_t3 = *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20; _t0 = 4; PushParam to; b = LCall Alloc; PopParams \(\overline{4}\);
_t1 = Derived;
\(\bar{*} \mathrm{~b}=\) _ t ;
_t2 = *b;
_t3 = *_t2;
PushParam b;
ACall _t3; PopParams 4; EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20
t0 = 4;
PushParam _t0;
\(\mathrm{b}=\) LCall Alloc;
PopParams 4;



ACall

\section*{Dissecting TAC}


\section*{Dissecting TAC}

```

int main() {

```
int main() {
    Base b;
    Base b;
    b = new Derived;
    b = new Derived;
    b.hi();
```

    b.hi();
    ```
\}
    main:
    BeginFunc 20;
        _t0 = 4;
    PushParam _t0;
    b = LCall Alloc;
    PopParams \(\overline{4}\);
    t1 = Derived;
    \(\bar{*}_{\mathrm{b}}=\) _t1;
    _t2 \(={ }^{*}\) b;
    _t3 = *_t2;
    PushParām b;
    ACall _t3;
    PopParams 4;
    EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
    BeginFunc 20;
        _t0 = 4;
    PushParam _t0;
    b = LCall Alloc;
    PopParams \(\overline{4}\);
    _t1 = Derived;
    *b \(=\) t 1 ;
    _t2 \(={ }^{*}\) b;
    _t3 = *_t2;
    PushParam b;
    ACall _t3;
    PopParams 4;
    EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
    BeginFunc 20;
        _t0 = 4;
    PushParam _t0;
    b = LCall Alloc;
    PopParams \(\overline{4}\);
    _t1 = Derived;
    *b \(=\) t1;
    _t2 \(={ }^{*}\) b;
    _t3 = *_t2;
    PushParam b;
    ACall _t3;
    PopParams 4;
    EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
_t0 = 4;

PushParam _t0;
b = LCall Alloc;
PopParams \(\overline{4}\);
_t1 = Derived;
*b \(=\) t1;
_t2 \(=\) *b;
_t3 = *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}


\section*{Dissecting TAC}

\[
\begin{aligned}
& \text { int main() \{ } \\
& \text { Base b; } \\
& \text { b = new Derived; } \\
& \text { b.hi () ; }
\end{aligned}
\]


\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
_t0 = 4;

PushParam _t0;
b = LCall Alloc;
PopParams \(\overline{4}\);
\(\underset{\text { Vtable }}{\text { Set }}\left\{\begin{array}{l}\text { t1 }=\text { Derived; } \\ \star \mathrm{b}=\mathrm{t} 1 ;\end{array}\right.\)
_t2 \(=\) *b;
_t3 = *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
_t0 = 4;

PushParam _t0;
b = LCall Alloc; PopParams \(\overline{4}\);
\(\underset{\text { Vtable }}{\text { Set }}\left\{\begin{array}{l}\mathrm{t} 1 \mathrm{C}=\text { Derived; } \\ \star \mathrm{b}=\quad \mathrm{t1} ;\end{array}\right.\)
_t2 \(=\) *b;
_t3 = *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
BeginFunc 20;
_t0 = 4;

PushParam _t0;
b = LCall Alloc;
PopParams \(\overline{4}\);
\(\underset{\text { Vtable }}{\text { Set }}\left\{\begin{array}{l}\text { t1 }=\text { Derived; } \\ \star \mathrm{b}=\mathrm{t} 1 ;\end{array}\right.\)
_t2 \(={ }^{*}\) *;
_t3 = *_t2;
PushParam b;
ACall _t3;
PopParams 4;
EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}
main:
    BeginFunc 20;
        _t0 = 4;
    PushParam _t0;
    Allocate
    Object
    b = LCall Alloc;
    PopParams \(\overline{4}\);
    \(\underset{\text { Vtable }}{\text { Set }}\left\{\begin{array}{l}\mathrm{t} 1=\text { Derived; } \\ \star \mathrm{b}=\mathrm{tI} ;\end{array}\right.\)
    _t2 \(={ }^{*}\) *;
    _t3 = *_t2;
    PushParam b;
    ACall _t3;
    PopParams 4;
    EndFunc;

\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}


\section*{Dissecting TAC}

```

int main() {
Base b;
b = new Derived;
b.hi();

```
\}


\section*{Dissecting TAC}


\section*{Dissecting TAC}


\section*{Dissecting TAC}


\section*{Dissecting TAC}


\section*{Dissecting TAC}


\section*{Dissecting TAC}


\section*{OOP in TAC}
- The address of an object's vtable can be referenced via the name assigned to the vtable (usually the object name).
- e.g. _t0 = Base;
- When creating objects, you must remember to set the object's vtable pointer or any method call will cause a crash at runtime.
- The ACall instruction can be used to call a method given a pointer to the first instruction.

\section*{Generating TAC}

\section*{TAC Generation}
- At this stage in compilation, we have
- an AST,
- annotated with scope information,
- and annotated with type information.
- To generate TAC for the program, we do (yet another) recursive tree traversal!
- Generate TAC for any subexpressions or substatements.
- Using the result, generate TAC for the overall expression.

\section*{TAC Generation for Expressions}
- Define a function cgen(expr) that generates TAC that computes an expression, stores it in a temporary variable, then hands back the name of that temporary.
- Define cgen directly for atomic expressions (constants, this, identifiers, etc.).
- Define cgen recursively for compound expressions (binary operators, function calls, etc.)

\section*{cgen for Basic Expressions}

\section*{cgen for Basic Expressions}
\(\operatorname{cgen}(k)=\{/ / k\) is a constant Choose a new temporary \(t\) \(\operatorname{Emit}(t=k)\); Return \(t\)

\section*{cgen for Basic Expressions}
\(\operatorname{cgen}(k)=\{/ / k\) is a constant Choose a new temporary \(t\) Emit( \(t=k\) );
Return \(t\)
\}
\(\operatorname{cgen}(i d)=\{/ /\) id is an identifier
Choose a new temporary \(t\) \(\operatorname{Emit}(t=i d)\)
Return \(t\)
\}

\section*{cgen for Binary Operators}

\section*{cgen for Binary Operators}
\(\boldsymbol{\operatorname { c g e n }}\left(\mathrm{e}_{1}+\mathrm{e}_{2}\right)=\{\)
Choose a new temporary \(t\)
Let \(t_{1}=\boldsymbol{\operatorname { c g e n }}\left(\mathrm{e}_{1}\right)\)
Let \(t_{2}=\boldsymbol{\operatorname { c g e n }}\left(\mathrm{e}_{2}\right)\)
\(\operatorname{Emit}\left(t=t_{1}+t_{2}\right)\)
Return \(t\)
\}

\section*{An Example}
\(\operatorname{cgen}(5+x)=\{\)
Choose a new temporary \(t\) Let \(\mathrm{t}_{1}=\boldsymbol{\operatorname { c g e n }}(5)\)
Let \(t_{2}=\boldsymbol{\operatorname { c g e n }}(\mathrm{x})\)
Emit \(\left(\mathrm{t}=\mathrm{t}_{1}+\mathrm{t}_{2}\right)\)
Return t
\}

\section*{An Example}
```

$\operatorname{cgen}(5+x)=\{$
Choose a new temporary $t$
Let $\mathrm{t}_{1}=$ \{
Choose a new temporary $t$
Emit $(t=5$ )
return $t$
\}
Let $\mathrm{t}_{2}=\boldsymbol{\operatorname { c g e n }}(\mathrm{x})$
Emit $\left(\mathrm{t}=\mathrm{t}_{1}+\mathrm{t}_{2}\right)$
Return t
\}

```

\section*{An Example}
```

$\operatorname{cgen}(5+x)=\{$
Choose a new temporary $t$
Let $\mathrm{t}_{1}=$ \{
Choose a new temporary $t$
Emit $(t=5$ )
return $t$
\}
Let $\mathrm{t}_{2}=\{$
Choose a new temporary $t$
$\operatorname{Emit}(t=\mathrm{x})$
return $t$
\}
Emit $\left(t=t_{1}+t_{2}\right)$
Return t
\}

```

\section*{An Example}
\(\operatorname{cgen}(5+x)=\{\)
Choose a new temporary \(t\) Let \(\mathrm{t}_{1}=\) \{

Choose a new temporary \(t\) Emit \((t=5)\) return \(t\)
\}
Let \(\mathrm{t}_{2}=\{\)
\[
\text { _t0 }=5
\]

Choose a new temporary \(t\) Emit( \(t=\mathrm{x}\) )
return \(t\)
\}
Emit \(\left(t=\mathrm{t}_{1}+\mathrm{t}_{2}\right)\)
Return t

\section*{cgen for Statements}
- We can extend the cgen function to operate over statements as well.
- Unlike cgen for expressions, cgen for statements does not return the name of a temporary holding a value.
- (Why?)

\section*{cgen for Simple Statements}

\section*{cgen for Simple Statements}

\section*{cgen(expr;) = \{ cgen(expr) \\ \}}

\section*{cgen for while loops}

\section*{cgen for while loops}

\section*{cgen(while (expr) stmt) \(=\{\)}

\section*{cgen for while loops}
cgen(while (expr) stmt) \(=\{\) Let \(\mathrm{L}_{\text {before }}\) be a new label. Let \(\mathrm{L}_{\text {after }}\) be a new label.

\section*{cgen for while loops}

\section*{\(\operatorname{cgen}(\) while \((\) expr \()\) stmt \()=\{\) Let \(\mathrm{L}_{\text {before }}\) be a new label. Let \(\mathrm{L}_{\text {after }}\) be a new label. Emit( \(\mathrm{L}_{\text {before }}\) :)}

Emit ( \(\mathrm{L}_{\text {after }}:\) )

\section*{cgen for while loops}
\(\boldsymbol{c g e n}(\) while \((\) expr \()\) stmt \()=\{\) Let \(\mathrm{L}_{\text {before }}\) be a new label. Let \(\mathrm{L}_{\text {after }}\) be a new label.
Emit( \(\mathrm{L}_{\text {before }}\) :)
Let \(t=\boldsymbol{c g e n}(\) expr \()\)
Emit ( IfZ \(t\) Goto \(\mathrm{L}_{\text {after }}\) )

Emit ( \(\mathrm{L}_{\text {after }}:\) )

\section*{cgen for while loops}
\(\boldsymbol{c g e n}(\) while \((\) expr \()\) stmt \()=\{\) Let \(L_{\text {before }}\) be a new label. Let \(\mathrm{L}_{\text {after }}\) be a new label. Emit( \(\mathrm{L}_{\text {before }}\) :) Let \(t=\boldsymbol{c g e n}(\) expr \()\) Emit( IfZ \(t\) Goto \(\mathrm{L}_{\text {after }}\) ) cgen(stmt)

Emit ( \(\mathrm{L}_{\text {after }}:\) )

\section*{cgen for while loops}
\(\boldsymbol{\operatorname { c g e n }}(\) while \((\) expr \() \mathrm{stmt})=\{\)
Let \(\mathrm{L}_{\text {before }}\) be a new label.
Let \(\mathrm{L}_{\text {after }}\) be a new label.
Emit( \(\mathrm{L}_{\text {before }}\) :)
Let \(t=\boldsymbol{c g e n}(\) expr \()\)
Emit( IfZ \(t\) Goto \(\mathrm{L}_{\text {after }}\) )
cgen(stmt) Emit( Goto \(\mathrm{L}_{\text {before }}\) )
Emit ( \(\mathrm{L}_{\text {after }}\) : )
\}

\section*{Next Time}
- Intro to IR Optimization
- Basic Blocks
- Control-Flow Graphs
- Local Optimizations```

